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**Overlay Network - Path Computation Approaches**  
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Abstract

This document discusses various path computations approaches which are applicable to overlay networks [framework doc ref]. It discusses how the customer edge nodes uses the information advertised by the provider network to compute a path between two customer edge nodes or how it can request the provider network to compute a path and setup an end-2-end LSP.

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## 1 Introduction

This document attempts to describe possible ways to advertise information required for customer network CE nodes to compute a path for LSPs between two points in two customer network islands connected by a provider network, so as to adhere a set of constraints in provider network without knowledge of the detailed provider network topology. These constraints could be, but not limited to, diversity, latency, jitter, skew etc. Connectivity between customer network islands is presumed to be an "overlay" over provider network.

### 1.1 Terminology

The key words "MUST", "MUST NOT", "REQUIRED", "SHALL", "SHALL NOT", "SHOULD", "SHOULD NOT", "RECOMMENDED", "MAY", and "OPTIONAL" in this document are to be interpreted as described in [RFC 2119](#) [[RFC2119](#)].

## 2. Path Computation Use-cases

In case of overlay networks it is required to compute a path between the customer edge nodes for the overlay FA-LSP as shown in the figure.

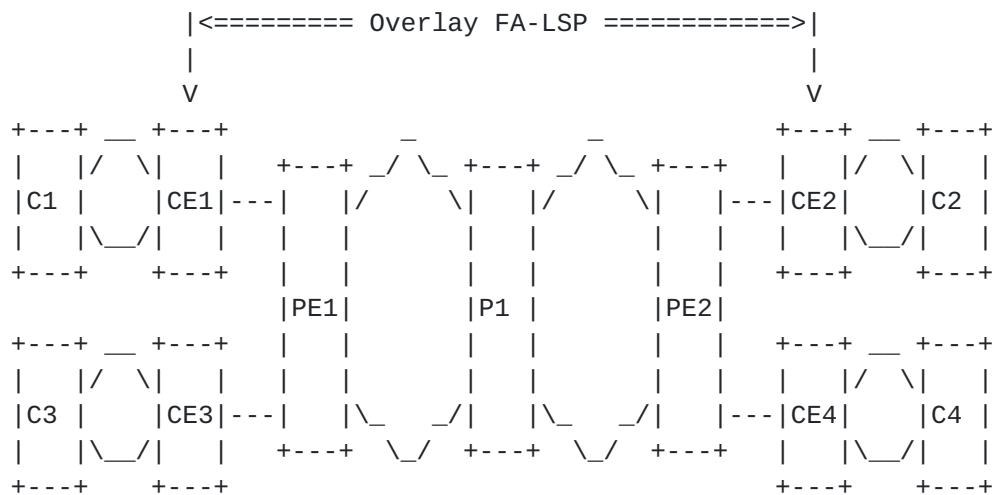


Figure. 1

The typical path computation use-cases are the following:

1. Point-to-point overlay path.
2. Multiple point-to-point diverse overlay paths sharing common LSP head and tail ends.
3. Multiple point-to-point diverse overlay paths that do not share common LSP head and tail ends.
4. Point-to-multipoint overlay paths.



5. Overlay paths over multi-domain (i.e. Multi-area or multi-AS) provider networks.

The typical TE constraints are:

1. Bandwidth or resource (this is technology specific).
2. Include or exclude nodes/links/SRLG or paths identified by path-keys.
3. Latency, jitter, max-hop requirements.
4. Optimization options - minimize cost, minimize latency etc.

### **3. Path Computation Approaches**

There are three path computation approaches

1. Virtual-topology approach
2. PCE approach
3. Hybrid approach - combined virtual topology and PCE approach



### 3.1 Virtual Topology Approach

This path computation approach uses a virtual topology that is advertised by the provider network by the customer edge nodes.

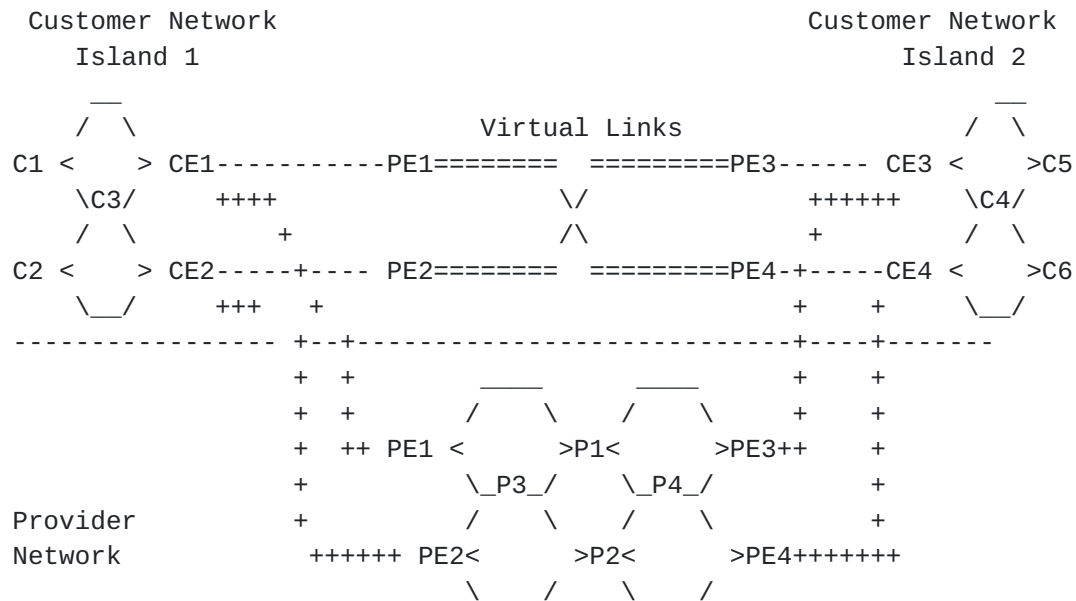


Figure. 2

In Figure 2, Provider Network has 4 interconnected rings supports full node diversity to connect any 2 Provider Edge Nodes.

PE1, PE2, PE3, PE4 are provider edge nodes.

P1, P2, P3, P4 are internal provider Network nodes, that must not be known to the customer network.

Customer Network has two islands connected by provider network.

C1, C2, C3, C4, C5, C6 are internal customer network nodes.

CE1, CE2, CE3, CE4 are customer network edge nodes connected to provider network edge nodes PE1, PE2, PE3, PE4.

**Virtual Link Set :** Virtual Link set is defined as set of one or more virtual links between any two provider edge nodes. The virtual links in the virtual link set, when realized may take different paths within provider domain, having different SRLGs and other TE metrics.

Above example topology has following Virtual Link Sets

- a/ [PE1, PE2]
- b/ [PE1, PE3]
- c/ [PE1, PE4]
- d/ [PE2, PE3]





e/ [PE2, PE4]  
f/ [PE3, PE4]

The PEs in provider network do full peering with its attached CEs for virtual topology. So provider network virtual Links along with its SRLG IDs and other TE metrics are advertised into customer network.

Customer network internal Nodes C1..C6 can see provider network virtual TE Links and can compute paths between two points in customer network islands across provider network satisfying required diversity and TE metrics.

### 3.2 PCE Approach

An alternative approach for a CE node to obtain a path to another remote CE node would be by making a request to a provider network PCE. This approach requires either provider network PE nodes to advertise the PCE's IP address to CE nodes or CE Nodes should be configured with Provider Network PCE IP address. CE nodes needs to advertise the TE link-state of the CE-PE interface. This allows the PCE to build the overlay network topology link-state data-base.

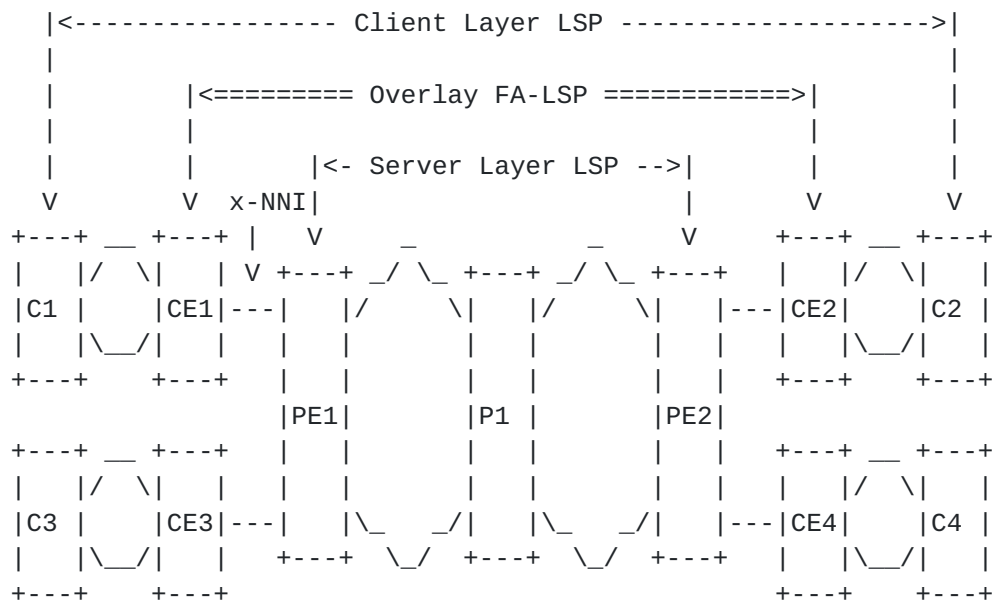


Figure. 3

In Figure. 3 above, the example depicted shows the provider network with a single IGP area and the provider network PCE has visibility to the detailed topology and TE information representing the server layer forwarding plane plus the CE-PE interface link-states that have been learned from the CE nodes. The server layer topology in addition to the CE-PE interface link-states constitutes the overlay network



topology.

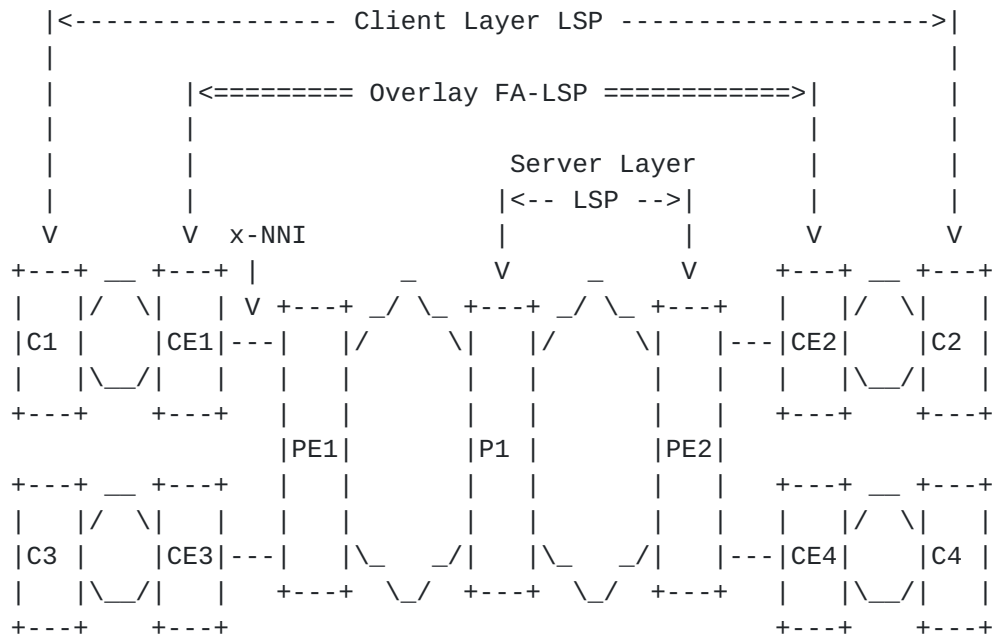


Figure. 4

Figure. 4 above shows the case in which the provider network is a multi-layer network and the server layer boundary does not coincide with the provider network boundary. Again, the provider network PCE can have visibility to a single IGP area as described for MLN or alternatively there could be multiple IGP instances as described in [\[RFC6107\]](#), one instance for the overlay network and another instance for the server layer.



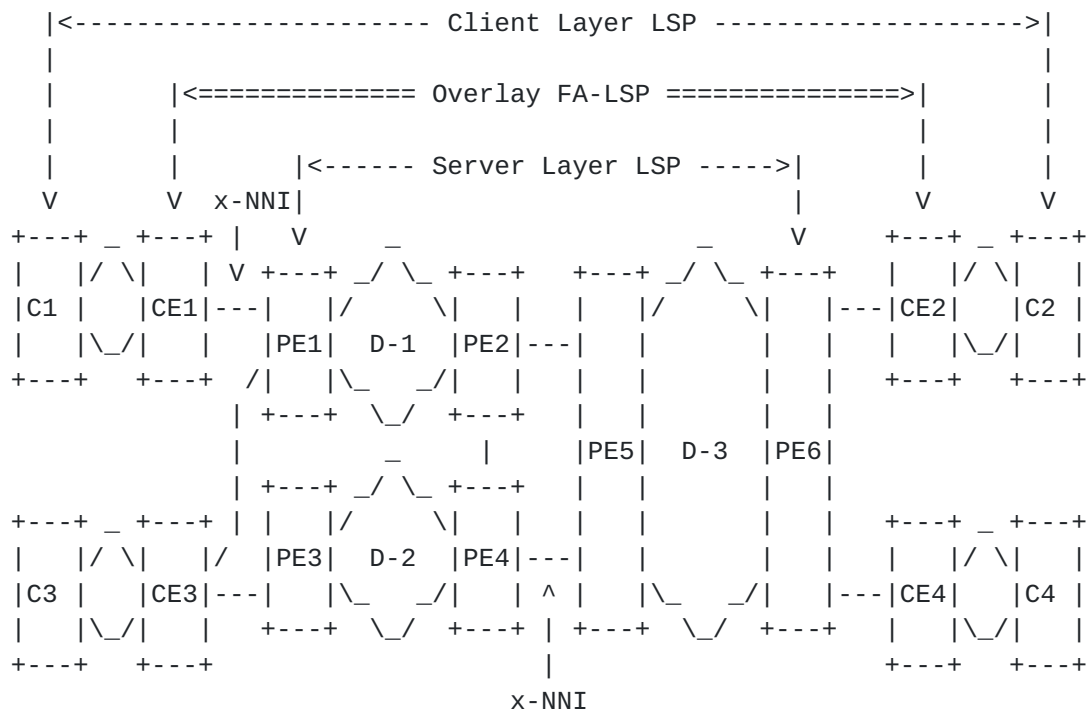


Figure. 4

Figure. 4 above shows a multi-area or multi-AS provider network (generalized as a multi-domain provider network in this document). For multi-domain networks a hierarchical PCE could be deployed and the IP address of the hierarchical PCE is advertised to the CE nodes. The hierarchical PCE could maintain a multi-domain virtual topology instead of detailed topology of each domain.

In all three cases the head-end CE node is assumed to be aware of the address in the remote CE node for which the path is to be computed. The exact manner by which this knowledge becomes available is beyond the scope of this document. The head-end CE node then makes a request to the provider network PCE with the remote address and the required set of TE constraints that need to be satisfied by the computed path.

In each case of the provider networks PCE uses the overlay network topology to compute the path. In case of the provider network example shown in Figure. 4 the hierarchical PCE computes the domain-level or inter-domain path first and then computes the intra-domain paths. The exact mechanism could be using the BRPC procedure in order to compute optimal intra-domain paths.

Once the computation is complete the PCE responds back with the path. The path generated by the PCE is expected to contain both real and virtual links and nodes. In case there is a need to maintain



confidentiality with respect to the details of the provider network topology from the customer network then the response can include a path-key. In case there is a need to compute diverse paths one of two approaches could be followed - simultaneous computation approach in which case the response will have multiple paths or path-keys or the request could include the exclude hops or exclude path-key.

### **[3.3](#) Hybrid Approach**

In the absence of a hierarchical PCE for a multi-domain provider network, it is possible a CE node learns of multiple PCE IP addresses from multiple PE nodes. This is possible in case each PE node lies in separate areas or ASs and with PCEs deployed per-area or per-AS. In such a situation it will be necessary for the CE node to pick one of the PCEs to send the path computation request. One way to select the appropriate PCE would be to advertise a virtual-topology associated with each PCE IP address to provide sufficient information for the CE node to determine whether a path to the remote CE address can be computed by the specific PCE.

In Figure. 4 above, CE3 has a dual-homed connectivity with the multi-domain provider network (i.e. CE3 to D-1 and D-2 via PE1 and PE3 respectively). In the absence of a hierarchical PCE, PE1 can advertise a virtual topology with connectivity to a set of CE nodes. Similarly PE3 advertises a virtual topology with connectivity to another set of CE nodes. This can happen in cases when there is no available bandwidth to a specific CE node via a specific domain. CE3 can determine using the virtual topologies which PCE should it send the path computation request.

## **[4.](#) CE-PE / PE-PE Interface**

The CE-PE or PE-PE interface requires a routing interface in order to be able to exchange topology information and a path-computation interface in order to be able to send path computation requests and responses. For signaling the overlay LSP a signaling interface is required as well.

## **[5](#) Security Considerations**

TBD

## **[6](#) IANA Considerations**

TBD

## **[7](#) References**





## **[7.1](#) Normative References**

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