New Spin bit enabled measurements with one or two more bits
draft-cfb-tsvwg-spinbit-new-measurements-00

Abstract

   This document introduces additional measurements by using the same
   spin bit signal as defined in [I-D.trammell-tsvwg-spin] and
   [I-D.trammell-ippm-spin]. The spin bit signal alone is not enough to
   evaluate correctly in every network condition the RTT of a flow. In
   order to solve this problem, it is theorized the possibility of
   introducing an additional validation signal called delay bit, similar
   to what is done by the Valid Edge Counter (VEC), but using just one
   bit instead of two. An alternative with two bits is also introduced
   with a so called loss bit. More in general a loss signal is defined
   to measure packet loss and two alternatives are presented with one
   bit and two bits.

Requirements Language

   The key words "MUST", "MUST NOT", "REQUIRED", "SHALL", "SHALL NOT",
   "SHOULD", "SHOULD NOT", "RECOMMENDED", "MAY", and "OPTIONAL" in this
   document are to be interpreted as described in RFC 2119 [RFC2119].

Status of This Memo

   This Internet-Draft will expire on May 7, 2020.

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Table of Contents

1. Introduction

   Both [I-D.trammell-tsvwg-spin] and [I-D.trammell-ippm-spin] define an
   explicit per-flow transport-layer signal for hybrid measurement of
   end-to-end RTT. This signal consists of three bits: a spin bit,
   which oscillates once per end-to-end RTT, and a two-bit Valid Edge
   Counter (VEC), which compensates for loss and reordering of the spin
   bit to increase fidelity of the signal in less than ideal network
   conditions.

   In this document it is introduced the delay bit, that is a single bit
   signal that can be used together with the spin bit by passive
   observers to measure the RTT of a network flow, avoiding the spin bit
   ambiguities that arise as soon as network conditions deteriorate.
   Unlike the spin bit, which is actually set in every packet
   transmitted on the network, the delay bit is set only once per round
   trip.

   This document defines a hybrid measurement RFC 7799 [RFC7799] path
   signal to be embedded into a transport layer protocol, explicitly
   intended for exposing end-to-end RTT to measurement devices on path.

   The document introduces a mechanism applicable to any transport-layer
   protocol, then explains how to bind the signal to a variety of IETF
   transport protocols, and in particular to QUIC and TCP.

   The application of the Spin bit to QUIC is described in
   [I-D.ietf-quic-spin-exp] which adds the spin bit only (without the
   VEC) to QUIC for experimentation purposes.

   Note that both the spin bit and the delay bit are inspired by RFC
   8321 [RFC8321]. This is also mentioned in [I-D.trammell-quic-spin].

2. Spin bit and Delay bit mechanism

   The main idea is to have a single packet, with a second marked bit
   (the delay bit), that bounces between client and server during the
   entire connection life. This single packet is called Delay Sample.

   A simple observer placed in an intermediate point, tracking the delay
   sample and the relative timestamp in every spin bit period, can
   measure the end-to-end round trip delay of the connection. In the
   same way as seen with the spin bit and the VEC, it is possible to
   carry out other types of measurements. The next paragraphs give an
   overview of the observer capabilities.

   In order to describe the delay sample working mechanism in detail, we
   have to distinguish two different phases which take part in the delay

bit lifetime: initialization and reflection. The initialization is
the generation of the delay sample, while the reflection realizes the
bounce behavior of this single packet between the two endpoints.

The next figure describes the Delay bit mechanism: the first bit is
the spin bit and the second one is the delay bit.

```
     +--------+    --   --   --   --   --    +--------+
     |        |         ----------->    |        |
     | Client |                         | Server |
     |        |         <-----------    |        |
     +--------+    --   --   --   --   --    +--------+

     (a) No traffic at beginning.

     +--------+   00   00   01   --   --    +--------+
     |        |         ----------->    |        |
     | Client |                         | Server |
     |        |         <-----------    |        |
     +--------+    --   --   --   --   --    +--------+

      (b) The Client starts sending data and
       sets the first packet as Delay Sample.

     +--------+   00   00   00   00   00    +--------+
     |        |         ----------->    |        |
     | Client |                         | Server |
     |        |         <-----------    |        |
     +--------+    --   --   01   00   00    +--------+

      (c) The Server starts sending data
       and reflects the Delay Sample.

     +--------+   10   10   11   00   00    +--------+
     |        |         ----------->    |        |
     | Client |                         | Server |
     |        |         <-----------    |        |
     +--------+   00   00   00   00   00    +--------+

      (d) The Client inverts the spin bit and
       reflects the Delay Sample.

     +--------+   10   10   10   10   10    +--------+
     |        |         ----------->    |        |
     | Client |                         | Server |
     |        |         <-----------    |        |
     +--------+   00   00   11   10   10    +--------+
```

   (e) The Server reflects the Delay Sample.

   +--------+   00 00 01 10 10   +--------+
	----------->	
Client		Server
	<-----------	
   +--------+   10 10 10 10 10   +--------+

   (f) The client reverts the spin
    bit and reflects the Delay Sample.

                   Figure 1: Spin bit and Delay bit

[2.1](). Delay Sample generation

   During this first phase, endpoints play different roles. First of
   all a single delay sample must be bouncing per round trip period (and
   so per spin bit period). According to that statement and in order to
   simplify the general algorithm, the delay sample generation is in
   charge of just one of the two endpoints:

   o the Client, when connection starts and spin bit is set to 0,
      initializes the delay bit of the first packet to 1, so it becomes
      the delay sample for that marking period. Only this packet is
      marked with the delay bit set to 1 for this round trip period; the
      other ones will carry only the spin bit;

   o the server never initializes the delay bit to 1; its only task is
      to reflect the incoming delay bit into the next outgoing packet
      only if certain conditions occur.

   Theoretically, in absence of network impairments, the delay sample
   should bounce between client and server continuously, for the entire
   duration of the connection. Actually, that is highly unlikely mainly
   for two different reasons:

   1) the packet carrying the delay bit might be lost during its journey
   on the network which is unreliable by definition;

   2) one of the two endpoints could stop or delay sending data because
   the application is limiting the amount of traffic transmitted;

   To deal with these problems, the algorithm provides a procedure to
   regenerate the delay sample and to inform a possible observer that a
   problem has occurred, and then the measurement has to be restarted.

2.1.1. The recovery process

In order to relieve the server from tasks that go beyond the mere
reflection of the sample, even in this case the recovery process
belongs to the client. A fundamental assumption is that a delay
sample is strictly related to its spin bit period. Considering this
rule, the client verifies that every spin bit period ends with its
delay sample. If that does not happen and a marking period
terminates without a delay sample, the client waits a further empty
period; then, in the following period, it reinitializes the mechanism
by setting the delay bit of the first outgoing packet to 1, making it
the new delay sample. The empty period is needed to inform the
intermediate points that there was an issue and a new delay
measurement session is starting.

2.2. Delay Sample reflection

The reflection is the process that enables the bouncing of the delay
sample between client and server. The behavior of the two endpoints
is slightly different. With the exception of the client that, as
previously exposed, generates a new delay sample, by default the
delay bit is set to 0.

Server side reflection: when a packet with the delay bit set to 1
arrives, the server marks the first packet in the opposite direction
as the delay sample, if it has the same spin bit value. While if it
has the opposite spin bit value this sample is considered lost.

Client side reflection: when a packet with delay bit set to 1
arrives, the client marks the first packet in the opposite direction
as the delay sample, if it has the opposite spin bit value. While if
it has the same spin bit value this sample is considered lost.

In both cases, if the outgoing marked packet is transmitted with a
delay greater than a predetermined threshold after the reception of
the incoming delay sample (1ms by default), reflection is aborted and
this sample is considered lost.

It is noteworthy that differently from what happens with the VEC for
which the reflection always concerns the edge of the period, in this
case reflection takes place for the packet that is carrying the delay
bit regardless of its position within the period. For this reason it
is necessary to introduce that condition of validation in order to
identify and discard those samples that, due to reordering, might
move to a contiguous period. Furthermore, by introducing a threshold
for the retransmission delay of the sample, it is possible to
eliminate all those measurements which, due to lack of traffic on the
endpoints, would be overestimated and not true. Thus, the maximum

   estimation error, without considering any other delays due to flow
   control, would amount to twice the threshold (e.g. 2ms) per
   measurement, in the worst case.

[3](#). Using the Spin bit and Delay bit for Hybrid RTT Measurement

   Unlike what happens with the spin bit for which it is necessary to
   validate or at least heuristically evaluate the goodness of an edge,
   the delay sample can be used by an intermediate observer as a simple
   demarcator between a period and the following one eliminating the
   ambiguities on the calculation of the RTT found with the analysis of
   the spin-bit only. The measurement types, that can be done from the
   observation of the delay sample, are exactly the same achievable with
   the spin bit only (with or without the VEC).

[3.1](#). End-to-end RTT measurement

   The delay sample generation process ensures that only one packet
   marked with the delay bit set to 1 runs back and forth on the wire
   between two endpoints per round trip time. Therefore, in order to
   determine the end-to-end RTT measurement of a QUIC flow, an on-path
   passive observer can simply compute the time difference between two
   delay samples observed in a single direction. Note that a
   measurement, to be valid, must take into account the difference in
   time between the timestamps of two consecutive delay samples
   belonging to adjacent spin-bit periods. For this reason, an
   observer, in addition to intercepting and analyzing the packets
   containing the delay bit set to 1, must maintain awareness of each
   spin period in such a way as to be able to assign each delay sample
   to its period and, at the same time, identifying those periods that
   do not contain it.

[3.2](#). Half-RTT measurement

   An on-path passive observer that is sniffing traffic in both
   directions -- from client to server and from server to client -- can
   also use the delay sample to measure "upstream" and "downstream" RTT
   components. Also known as the half-RTT measurement, it represents
   the components of the end-to-end RTT concerning the paths between the
   client and the observer (upstream), and the observer and the server
   (downstream). It does this by measuring the delay between a delay
   sample observed in the downstream direction and the one observed in
   the upstream direction, and vice versa. Also in this case, it should
   verify that the two delay samples belong to two adjacent periods, for
   the upstream component, or to the same period for the downstream
   component.

3.3. Intra-domain RTT measurement

   Taking advantage of the half-RTT measurements it is also possible to
   calculate the intra-domain RTT which is the portion of the entire RTT
   used by a QUIC flow to traverse the network of a provider (or part of
   it). To achieve this result two observers, able to watch traffic in
   both directions, must be employed simultaneously at ingress and
   egress of the network to be measured. At this point, to determine
   the delay between the two observers, it is enough to subtract the two
   computed upstream (or downstream) RTT components.

   The spin bit is an alternate marking generated signal and the only
   difference than RFC 8321 [RFC8321] is the size of the alternation
   that will change with the flight size each RTT. So it can be useful
   to segment the RTT and deduce the contribution to the RTT of the
   portion of the network between two on-path observers and it can be
   easily performed by calculating the delay between two or more
   measurement points on a single direction by applying RFC 8321
   [RFC8321].

4. Observer's algorithm and Waiting Interval

   Given below is a formal summary of the functioning of the observer
   every time a delay sample is detected. A packet containing the delay
   bit set to 1:

   o if it has the same spin bit value of the current period and no
      delay sample was detected in the previous period, then it can be
      used as a left edge (i.e. to start measuring an RTT sample), but
      not as a right edge (i.e. to complete and RTT measurement since
      the last edge). If the observation point is symmetric (i.e. it
      can see both upstream and downstream packets in the flow) and in
      the current period a delay sample was detected in the opposite
      direction (i.e. in the upstream direction), the packet can also be
      used to compute the downstream RTT component.

   o if it has the same spin bit value of the current period and a
      delay sample was detected in the previous period, then it can be
      used at the same time as a left or right edge, and to compute RTT
      component in both directions.

   Like stated previously, every time an empty period is detected, the
   observer must restart the measurement process and consider the next
   delay sample that will come as the beginning of a new measure, then
   as a left edge. As a result, being able to assign the delay sample
   to the corresponding spin period becomes a crucial factor for the
   proper functioning of the entire algorithm.

Considering that the division into periods is realized by exploiting the spin bit square wave, it is easy to understand that the presence of spurious spin edges -- caused by packet reordering -- would inevitably lead the observer to overestimate the amount of periods actually present in the transmission. This results in a greater number of empty periods detected and the consequent decrease of the actual RTT samples achievable. Therefore, in order to maximize the performance of the whole algorithm, the observer must implement a mechanism to filter out spurious spin edges.

To face this problem the waiting interval has to be introduced. Basically, every time a spin bit edge is detected, the observer sets a time interval during which it rejects every potential spurious edges observed on the wire. While, at the end of the interval it starts again to accept changes in the spin bit value. This guarantees a proper protection against the spurious edges in relation to the size of the interval itself. For instance, an interval of 5ms is able to filter out edges that have been reordered by a maximum of 5ms. Clearly, the mechanism does its job for intervals smaller than the RTT of the observed connection (if RTT is smaller than the waiting interval the observer can't measure the RTT).

5. Adding a Loss signal for Packet loss measurement

It is possible to introduce a mechanism to evaluate also the packet loss together with the delay measurement. This can be achieved by introducing the loss signal, a single or two bits signal whose purpose is to mark a variable number of packets (from live traffic) which are exchanged two times between the endpoints realizing a two round-trip reflection. The overall exchange comprises:

o The client first selects, generates and consequent transmits to the server a first train of packets, by marking the loss bit to 1;

o The server, upon reception from the client of each one of the packets included in the first train, reflects to the client a respective second train of packets of the same size as the first train received, by marking the loss bit to 1;

o The client, upon reception from the server of each one of the packets included in the second train, reflects to the server a respective third train of packets of the same size as the second train received, by marking the loss bit to 1;

o The server, upon reception from the client of each one of the packets included in the third train, finally reflects to the client a respective fourth train of packets of the same size as the third train received, by marking the loss bit to 1.

Packets belonging to the first round (first and second train)
represent the Generation Phase while those belonging to the second
round (third and fourth train) represent the Reflection Phase.

A passive on-path observer, placed on whatever direction, can
trivially count and compare the number of marked packets seen during
the two mentioned phases (i.e. the first and third or the second and
the fourth trains of packets, depending on which direction is
observed) and estimate the loss rate experienced by the connection.
This process is repeated continuously to obtain more measurements as
long as the endpoints exchange traffic. These measurements can be
called Round Trip(RT) losses

The general algorithm shown above gives an idea of its underlying
principles but is not enough to make the whole process working
properly.

Firstly, there is the issue that packet rates in the two directions
may be different. Therefore, the right number of packets to be
marked has to be chosen in order to avoid their congestion on the
slowest traffic direction. As a consequence, this number is
inevitably equal to the amount of packets transited, indeed, on the
slowest direction. This problem can be easily addressed by a method
wherein the two endpoints of a communication exchange marked packets
interleaved with unmarked packets. From an implementation point of
view, this result can be achieved by introducing a single token
system that adjusts the number of outgoing marked packets.
Basically, the token is enabled every time a packet arrives and
disabled when a marked packet is transmitted. Since the creation of
the initial train of marked packets is carried out by the client, the
management and use of this single token is also assigned to it, which
in fact "calculates" the correct number of packets to be marked each
time.

Secondly, a mechanism to individually identify each train of packets
must be provided to enable the observer to distinguish between trains
belonging to different phases (Generation and Reflection). About
this point, different approaches are used depending on the number of
bits of the loss signal and it will be discussed in the next
sections.

5.1. Round Trip Packet Loss measurement

Since the measurements are performed on a portion of the traffic
exchanged between client and server, the observer calculates the end-
to-end Round Trip Packet Loss that, statistically, will be equal to
the loss rate experienced by the connection along the entire network

path. So this measurement can be simply referred as the Round Trip
Packet Loss (RTPL).

In addition, this methodology allows the Half-RTPL measurement and
the Intra-domain RTPL measurement, in the same way as described in
the previous sections for RTT measurement.

6. RTT dependent Packet Loss using one bit loss signal

The single bit loss signal is implemented using just one bit: marked
packets have this bit set to 1, whereas unmarked ones have it set to
0. This solution requires a working spin-bit signal used to separate
different trains of packets. In particular, a "pause" of at least
one empty spin-bit period is introduced between each phase of the
algorithm. An on-path observer can determine in this way if a phase
(and therefore a train of packets) is ended and a new one is
starting.

The client is in charge of almost the entire complexity of the
algorithm. Its task can be summarized in 4 different points:

1. The client starts generating marked packets for two consecutive
    spin-bit periods; it maintains a generation token that is enabled
    every time a packet arrives and disabled when another one is
    forwarded. When this token is disabled, the generation process
    is paused (i.e. outgoing packets are transmitted unmarked) and
    resumes as soon as its value returns true, and that happens as
    soon as a packet is received. In addition, at the end of the
    first spin-bit period spent in generation, the reflection counter
    is unlocked to start counting incoming marked packets which will
    be later reflected;

2. When the generation is completed, the client waits to see in
    input an empty spin-bit period so as to be sure that everyone has
    seen at least that empty period. This one will be used by the
    observer as a divider between generated and reflected packets.
    During this phase, all the outgoing packets are forwarded with
    the loss bit set to 0. The reflection counter is still
    incremented every time a marked packet arrives;

3. The client starts reflecting marked packets until the reflection
    counter is zeroed; the generation token is also used (in the same
    way) during this phase to avoid congestion on the slowest traffic
    direction. In addition, at the end of the first spin-period
    spent in reflection, the reflection counter is locked to avoid
    incoming reflected packets incrementing it;

4. When the reflection is completed, the client waits to see in
    input an empty spin-bit period so as to be sure that everyone has
    seen at least that empty period. This one will be used by the
    observer as a divider between reflected and newly generated
    packets. During this phase, all the outgoing packets are
    forwarded with the loss bit set to 0. The whole process restarts
    going back to the first point.

As previously anticipated, the server simply reflects each incoming
marked packet sent by the client. It maintains a simple counter that
is incremented every time a marked packet arrives and decremented
when a marked one is sent in the opposite direction.

This one bit loss signal methodology replies and exposes the RTT of
the connection on the wire in any case, when the spin bit and the
delay bit are used and when these are disabled.

6.1. Observer's logic for one bit loss signal

The on-path observer, placed in any direction, counts marked packets
and separates different trains detecting empty spin-bit periods
between them (one or more). Then, it simply computes the difference
between a Generation train and a Reflection train to produce a
statistical measurement of the Round Trip Packet Loss (RTPL) and of
the connection end-to-end loss rate.

Here is an example. Packets are represented by two digits (first one
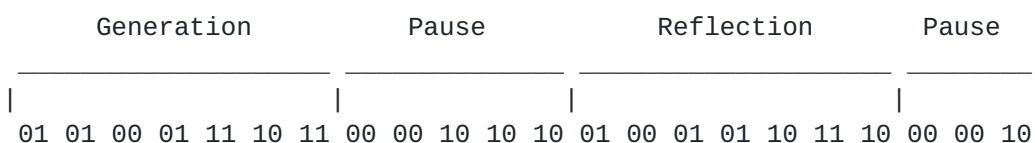is the spin bit, second one is the loss bit):

```
       Generation            Pause           Reflection         Pause
     _____  _____  _____  _____
    |                    |  |           |  |                  |  |      |
     01 01 00 01 11 10 11 00 00 10 10 10 01 00 01 01 10 11 10 00 00 10
```

                  Figure 2: one bit loss signal example

Note that 5 marked packets have been generated of which 4 reflected.

7. RTT independent Packet Loss using two bits loss signal

An RTT independent version of this algorithm requires two bits and
does not rely on the spin-bit signal to enable pause detection. That
is because packets generated and reflected by the client are marked
using two different marking values thus removing the need of
introducing a pause between them. Furthermore, instead of generating
marked packets for the duration of two spin-bit periods (as seen in

the one bit loss signal), a fixed duration for the generation phase
can be used (e.g., 100ms).

In this way, no information related to the RTT of the connection is
exposed on wire.

Using a two bits loss signal, four possible values can be used inside
each packet (i.e. 0 to 3). During the Generation phase, marked
packets have the loss value set to 1 whereas unmarked ones to 0. On
the contrary, during the Reflection phase, marked packets have the
loss value set to 2 whereas unmarked ones to 3. By doing so, even
unmarked packets have their own alternate marking methodology that
can be used by intermediate points to compute the one-way loss rate
between them (RFC 8321 [RFC8321]).

Even in this case, the client is in charge of almost the entire
complexity of the algorithm. Its task can be summarized in 2
different points:

1. The client generates marked packets (i.e. with loss bits set to
    1) for 100ms; it also maintains a generation token that is
    enabled every time a packet arrives and disabled when another one
    is forwarded. When this token is disabled, the generation
    process is paused (i.e. outgoing packets are transmitted unmarked
    with the loss bits set to 0) and resumes as soon as its value
    returns true.

2. When the generation is completed, the client starts reflecting
    marked packets (i.e. with loss bits set to 2) until the
    reflection counter is zeroed and for at least 100ms. The
    generation token is also used during this phase to avoid
    congestion on the slowest traffic direction; however, in this
    case, "unmarked" packets are transmitted with the loss bit set to
    3. The whole process restarts going back to the first point.

Independently of the current phase of the algorithm, the reflection
counter is increased every time a packet carrying a loss value equal
to 1 arrives. Moreover, depending on the connection RTT, the client
should vary the duration of the generation phase to different values.
For example, for connection below 100ms of RTT the client generates
for 100ms; for connection below 300ms of RTT it generates for 300ms
and for connection below 1s of RTT it generates for 1000ms. This is
necessary to ensure that the client has already received generated
marked packets before the beginning of the reflection phase.

As regards the role of the server, it simply reflects each incoming
marked packet sent by the client. It maintains two different
counters for generated and reflected packets (i.e. loss bits to 1 and

2) in concomitance with a mechanism to reflect in output the same
number of marked packets in the same order of arrival (with at most
the reordering of packets arrived out of sequence).

7.1. Observer's logic for two bits loss signal

The on-path observer, placed in any direction, counts marked packets
belonging to different phases simply looking at the loss value
carried by each packet (therefore, it does not look at the spin-bit
value anymore). Then, in the same way seen for the previous one bit
algorithm, it simply computes the difference between a Generation
train and a Reflection train to produce a statistical measurement of
the Round Trip Packet Loss (RTPL) and of the connection end-to-end
loss rate. Moreover, it can also count unmarked packets and,
cooperating with a second observer placed in the same direction,
compute the one-way loss rate between two intermediate points using
the alternate marking methodology (RFC 8321 [RFC8321]).

Here is an example. Packets are represented by a single digit
corresponding to the carried two-bits loss value (0 to 3):

```
        Generation              Reflection              Generation
  _____  _____  _____
 |                      | |                      | |                      |
  1 1 0 1 1 1 1 0 1 1 0 2 2 2 2 3 2 3 3 2 3 3 1 1 0 1 0 0 1 1 0 1 0
```

Figure 3: two bits loss signal example

Note that 8 marked packets have been generated of which 6 reflected;
then again 6 marked packets are generated.

8. Protocols

8.1. QUIC

The binding of the delay bit signal to QUIC is partially described in
[I-D.ietf-quic-spin-exp], which adds the spin bit only to the QUIC
protocol. From an implementation point of view, the delay bit is
placed in the partially unencrypted (but authenticated) QUIC header,
alongside the spin bit, occupying one of the two bits left reserved
for future experiments. As things stand, according to
[I-D.ietf-quic-transport], the proposed scheme of the first header's
byte would be 01SDRKPP.

Regarding the loss signal, since the use of the spin bit is not mandatory and many connection may not have it spinning, two different configuration are proposed:

> If the spin-bit IS enabled (i.e. the RTT is already exposed on wire), use the 1 bit loss signal alongside the delay bit to improve delay measurements accuracy; in this configuration, the proposed scheme of the first header's byte would be 01SDLKPP;

> If the spin-bit IS NOT enabled, use the 2 bits loss signal just to measure connection loss rate without exposing any RTT related information on wire; in this configuration, the proposed scheme of the first header's byte would be 01SLLKPP.

This implies that an observer must be able to determine whether the spin bit is active and correctly spinning or not (choosing, accordingly, the right version of packet loss measurement to be used).

8.2. TCP

The signal can be added to TCP by defining bit 4 of bytes 13-14 of the TCP header to carry the spin bit, and eventually bits 5 and 6 to carry additional information, like the delay bit and the 1 bit loss signal (or the two bits loss signal).

9. Security Considerations

The privacy considerations for the hybrid RTT measurement signal are essentially the same as those for passive RTT measurement in general.

10. Acknowledgements

tbc

11. IANA Considerations

tbc

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