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OSPF-TE Extensions for General Network Element Constraints

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Abstract

Generalized Multiprotocol Label Switching (GMPLS) can be used to control a wide variety of technologies including packet switching (e.g., MPLS), time-division (e.g., SONET/SDH, Optical Transport Network (OTN)), wavelength (lambdas), and spatial switching (e.g., incoming port or fiber to outgoing port or fiber). In some of these technologies, network elements and links may impose additional routing constraints such as asymmetric switch connectivity, non-local label assignment, and label range limitations on links. This document describes Open Shortest Path First (OSPF) routing protocol extensions to support these kinds of constraints under the control of GMPLS.

Conventions used in this document

The key words "MUST", "MUST NOT", "REQUIRED", "SHALL", "SHALL NOT", "SHOULD", "SHOULD NOT", "RECOMMENDED", "MAY", and "OPTIONAL" in this document are to be interpreted as described in [RFC-2119](#) [[RFC2119](#)].

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[1. Introduction](#)

Some data plane technologies that require the use of a GMPLS control plane impose additional constraints on switching capability and label assignment. In addition, some of these technologies should be capable of performing non-local label assignment based on the nature of the technology, e.g., wavelength continuity constraint in Wavelength Switched Optical Network (WSON) [[RFC6163](#)]. Such constraints can lead to the requirement for link by link label availability in path computation and label assignment.

[GEN-Encode] provides efficient encodings of information needed by the routing and label assignment process in technologies such as WSON and are potentially applicable to a wider range of technologies. The encoding provided in [[GEN-Encode](#)] is protocol-neutral and can be used in routing, signaling and/or Path Computation Element communication protocol extensions.

This document defines extensions to the OSPF routing protocol based on [[GEN-Encode](#)] to enhance the Traffic Engineering (TE) properties of GMPLS TE which are defined in [[RFC3630](#)], [[RFC4202](#)], and [[RFC4203](#)]. The enhancements to the TE properties of GMPLS TE links can be advertised in OSPF TE LSAs. The TE LSA, which is an opaque LSA with area flooding scope [[RFC3630](#)], has only one top-level Type/Length/Value (TLV) triplet and has one or more nested sub-TLVs for extensibility. The top-level TLV can take one of three values (1) Router Address [[RFC3630](#)], (2) Link [[RFC3630](#)], (3) Generic Node Attribute defined in [Section 2](#). In this document, we enhance the sub-TLVs for the Link TLV and define a new top-level TLV (Generic Node Attribute TLV) in support of the general network element constraints under the control of GMPLS.

The detailed encoding of OSPF extensions are not defined in this document. [[GEN-Encode](#)] provides encoding details.

2. Node Information

According to [\[GEN-Encode\]](#), the additional node information representing node switching asymmetry constraints includes Node ID and connectivity matrix. Except for the Node ID, which should comply with Routing Address described in [\[RFC3630\]](#), the other pieces of information are defined in this document.

Per [\[GEN-Encode\]](#), we have identified the following new Sub-TLVs to the Node Attribute TLV as defined in [\[RFC5786\]](#). Detailed description for each newly defined Sub-TLV is provided in subsequent sections:

Sub-TLV Type	Length	Name
TBD	variable	Connectivity Matrix

In some specific technologies, e.g., WSON networks, the Connectivity Matrix sub-TLV may be optional, which depends on the control plane implementations. Usually, for example, in WSON networks, Connectivity Matrix sub-TLV may be advertised in the LSAs since WSON switches are currently asymmetric. If no Connectivity Matrix sub-TLV is included, it is assumed that the switches support symmetric switching.

2.1. Connectivity Matrix

If the switching devices supporting certain data plane technology is asymmetric, it is necessary to identify which ingress ports and labels can be switched to some specific labels on a specific egress port.

The Connectivity Matrix is used to identify these restrictions, which can represent either the potential connectivity matrix for asymmetric switches (e.g., ROADMs and such) or fixed connectivity for an asymmetric device such as a multiplexer as defined in [\[WSON-Info\]](#).

The Connectivity Matrix is a sub-TLV of the Generic Node Attribute TLV. The length is the length of value field in octets. The meaning and format of this sub-TLV value field are defined in Section 2.1 of [\[GEN-Encode\]](#). One sub-TLV contains one matrix. The Connectivity Matrix sub-TLV may occur more than once to contain multiple matrices within the Generic Node Attribute TLV. In addition a large connectivity matrix can be decomposed into smaller sub-matrices for transmission in multiple LSAs as described in [Section 5](#).

3. Link Information

The most common link sub-TLVs nested in the top-level link TLV are already defined in [\[RFC3630\]](#), [\[RFC4203\]](#). For example, Link ID, Administrative Group, Interface Switching Capability Descriptor (ISCD), Link Protection Type, Shared Risk Link Group Information (SRLG), and Traffic Engineering Metric are among the typical link sub-TLVs.

Per [\[GEN-Encode\]](#), we add the following additional link sub-TLVs to the link TLV in this document.

Sub-TLV Type	Length	Name
TBD	variable	Port Label Restrictions

Generally all the sub-TLVs above are optional, which depends on the control plane implementations. The Port Label Restrictions sub-TLV will not be advertised when there are no restrictions on label assignment.

3.1. Port Label Restrictions

Port label restrictions describe the label restrictions that the network element (node) and link may impose on a port. These restrictions represent what labels may or may not be used on a link and are intended to be relatively static. For increased modeling flexibility, port label restrictions may be specified relative to the port in general or to a specific connectivity matrix.

For example, the Port Label Restrictions describes the wavelength restrictions that the link and various optical devices such as OXCs, ROADMs, and waveband multiplexers may impose on a port in WSON. These restrictions represent what wavelength may or may not be used on a link and are relatively static. The detailed information about port label restrictions is described in [\[WSON-Info\]](#).

The Port Label Restrictions sub-TLV is a sub-TLV of the Link TLV. The length is the length of value field in octets. The meaning and format of this sub-TLV value field are defined in Section 2.2 of [\[GEN-Encode\]](#). The Port Label Restrictions sub-TLV may occur more than once to specify a complex port constraint within the link TLV.

4. Routing Procedures

All the sub-TLVs are nested in top-level TLV(s) and contained in Opaque LSAs. The flooding rules of Opaque LSAs are specified in [\[RFC2328\]](#), [\[RFC5250\]](#), [\[RFC3630\]](#), [\[RFC4203\]](#).

Considering the routing scalability issues in some cases, the routing protocol should be capable of supporting the separation of dynamic information from relatively static information to avoid unnecessary updates of static information when dynamic information is changed. A standards-compliant approach is to separate the dynamic information sub-TLVs from the static information sub-TLVs, each nested in a separate top-level TLV ([\[RFC3630\]](#) and [RFC5876](#)), and advertise them in the separate OSPF TE LSAs.

For node information, since the Connectivity Matrix information is static, the LSA containing the Generic Node Attribute TLV can be updated with a lower frequency to avoid unnecessary updates.

For link information, a mechanism MAY be applied such that static information and dynamic information of one TE link are contained in separate Opaque LSAs. For example, the Port Label Restrictions information sub-TLV could be nested in separate top level link TLVs and advertised in the separate LSAs.

Note that as with other TE information, an implementation SHOULD take measures to avoid rapid and frequent updates of routing information that could cause the routing network to become swamped. A threshold mechanism MAY be applied such that updates are only flooded when a number of changes have been made to the label availability information (e.g., wavelength availability) within a specific time interval. Such mechanisms MUST be configurable if they are implemented.

5. Scalability and Timeliness

This document has defined two sub-TLVs for describing generic routing constraints. The examples given in [\[Gen-Encode\]](#) show that very large systems, in terms of label count or ports can be very efficiently encoded. However there has been concern expressed that some possible systems may produce LSAs that exceed the IP Maximum Transmission Unit (MTU) and that methods be given to allow for the splitting of general constraint LSAs into smaller LSAs that are under the MTU limit. This section presents a set of techniques that can be used for this purpose.

5.1. Different Sub-TLVs into Multiple LSAs

Two sub-TLVs are defined in this document:

1. Connectivity Matrix (Node Attribute TLV)
2. Port Label Restrictions (Link TLV)

The Connectivity Matrix can be carried in the Node Attribute TLV as defined in [\[RFC5786\]](#) while the Port Label Restrictions can be carried in a Link TLV of which there can be at most one in an LSA as defined in [\[RFC3630\]](#). Note that the Port Label Restrictions are relatively static, i.e., only would change with hardware changes or significant system reconfiguration.

5.2. Decomposing a Connectivity Matrix into Multiple Matrices

In the highly unlikely event that a Connectivity Matrix sub-TLV by itself would result in an LSA exceeding the MTU, a single large matrix can be decomposed into sub-matrices. Per [\[GEN-Encode\]](#) a connectivity matrix just consists of pairs of input and output ports that can reach each other and hence such this decomposition would be straightforward. Each of these sub-matrices would get a unique matrix identifier per [\[GEN-Encode\]](#).

From the point of view of a path computation process, prior to receiving an LSA with a Connectivity Matrix sub-TLV, no connectivity restrictions are assumed, i.e., the standard GMPLS assumption of any port to any port reachability holds. Once a Connectivity Matrix sub-TLV is received then path computation would know that connectivity is restricted and use the information from all Connectivity Matrix sub-TLVs received to understand the complete connectivity potential of the system. Prior to receiving any Connectivity Matrix sub-TLVs path computation may compute a path through the system when in fact no path exists. In between the reception of an additional Connectivity Matrix sub-TLV path computation may not be able to find a path through the system when one actually exists. Both cases are currently encountered and handled with existing GMPLS mechanisms. Due to the reliability mechanisms in OSPF the phenomena of late or missing Connectivity Matrix sub-TLVs would be relatively rare.

6. Security Considerations

This document does not introduce any further security issues other than those discussed in [\[RFC 3630\]](#), [\[RFC 4203\]](#).

For general security aspects relevant to Generalized Multiprotocol Label Switching (GMPLS)-controlled networks, please refer to [\[RFC5920\]](#).

[7. IANA Considerations](#)

IANA is requested to allocate new sub-TLVs as defined in Sections [2](#) and 3 as follows:

[7.1. Node Information](#)

This document also introduces the following sub-TLVs of Node Attribute TLV:

Type	sub-TLV
TBD	Connectivity Matrix

[7.2. Link Information](#)

This document introduces the following sub-TLV of TE Link TLV (Value 2):

Type	sub-TLV
TBD	Port Label Restrictions

[8. References](#)

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