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Network-Hexagons:Geolocation Mobility Edge Network Based On H3 and LISP draft-ietf-lisp-nexagon-41

Abstract

This document uses virtual layer3 routing and geospatial addressing based on a hierarchical grid forming a Geolocation mobility-edge network. When vehicles with AI cameras detect objects of interest on the road, they use their GPS to calculate their high-resolution grid-tile position. Then they use this tile to calculate the high-resolution tile of the detection. A low-resolution tile which contains the detection-tile identifies a network-addressable object. The object tile-ID is used as basis for IPv6 endpoint identifier(EID). Geospatial EIDs are queue-destination and channel-source of objects. Geolocation objects consolidate detections form all vehicles in a given area. Geolocation objects based on EID queues and channels are network portable via the Locator/ID Separation Protocol (LISP).

Status of This Memo

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1. Introduction

This document uses virtual layer3 routing and geospatial addressing based on a hierarchical grid forming a Geolocation mobility-edge network. When vehicles with AI cameras detect objects of interest on the road, they use their GPS to calculate their high-resolution grid-tile position. Then they use this tile to calculate the high-resolution tile of the detection. A low-resolution tile which contains the detection-tile identifies a network-addressable object. The object tile-ID is used as basis for IPv6 endpoint identifier(EID). Geospatial EIDs are queue-destination and channel-source of objects. Geolocation objects consolidate detections form all vehicles in a given area. Geolocation objects based on EID queues and channels are network portable via the Locator/ID Separation Protocol (LISP).

Network addressable hexagonal grid objects (nexagons) encapsulate geolocation processing are delegated dynamically to compute locations per road activity: vehicle uploads and client subscriptions. Dynamics of vehicles and clients causes key-issues resolved by LISP:

- Dynamic allocation and coherency of services IPs cached by clients

- Context-switching between Geolocation Services IPs while driving
- Geo-privacy and tracking of clients interacting with services
- Subscription continuity when switching IP Anchors while driving

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These key-issues are resolved using LISP mapped EID virtualization:

- Addresses virtualization of the communicating clients and services
- Algorithmic service-addressing based on geospatial grid identifiers
- Algorithmic client-addressing based on an authorization procedure

Geolocation virtual addressing for queues and for channels helps solve services objects portability. Because other than queues and channels, functional stacks are pervasive and objects-states quickly regenerate. Portability solves dynamic allocation and reduces coherency issues. As for client side EIDs, these enable subscription continuity and geoprivacy. The resulting elastic allocation uses EID algorithmic context switching, maintain subscription continuity and IP geo-privacy.

```
Addressable >> States >> Addressable
Upload Queues \ ___ / Channels
/\ Functions() \/
```

Figure 1: Geolocation schematics: queues, channels, states, functions

To summarize Address virtualization based on LISP EIDs:

- EID addressing of Geolocation upload queues by H3 identifiers
- EID addressing of detection channels, H3 ID sources and topics
- EID addressing of mobility clients, assigned and also renewed

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Note 1: The breakdown of Geolocations Services to objects is done based on geospatial grid lines known to both mobility clients and Geolocation Services. We use H3 [H3] hierarchical hexagonal grid because of its clear tile adjacency properties. Each grid-tile in each resolution has a unique 64bit identifier (HID). HIDs are mapped to EIDs algorithmically. In addition to objects, the same grid at higher resolution (smaller tiles) is used to localize detections. We refer to h3.rB as the lower resolution object big tile, and h3.rS as the detection location, higher resolution small tile.

Mappings: GPS => h3.rS => H3.rB => EID are therefore algorithmic. Sizeof (h3.rB) / Sizeof (h3.rS) x density-factor / MTU ~ number of messages needed to convey object state snapshot of small-tiles in it.

Off-Peak object Allocation Packed on less compute

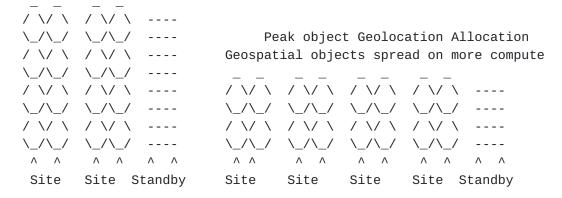


Figure 2: Geolocation dynamic allocation per geospatial activity

Note 2: LISP solution for address virtualization forms an application network. In order for clients and services to use it there needs to be a formal provisioning step. For the clients this step will require Authentication Authorization and Accounting (AAA) procedure by which clients are assigned and renew EIDs and XTRs to be used to interact with services. This process may be done in various vendor specific methods, or multivendor AAA service. AAA procedure is described as a life-cycle example.

Note 3: In order to make the notion of geospatial detection concrete, we add to the 64bit HID of "where" is a detection, 64bit of "what" is the detection or situation. These 64 bits are detailed in a bit-mask based on a taxonomy defined by Berkeley Deep Drive [BDD]. It is meant as a baseline that can be extended or overridden depending on need.

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2. Definition of Terms

Based on [I-D.ietf-lisp-rfc6830bis][I-D.ietf-lisp-rfc6833bis]

H3ServiceEID: Is an EID addressable Geolocation Service object. It is a designated destination for geospatial detections, and an (S,G) source of multicast of themed detection channels. It has a light-weight LISP protocol stack to tunnel packets via ServerXTR. The EID is IPv6 and contains HID in the lower bits.

ServerXTR: Is a data-plane only LISP protocol stack implementation, it is co-located with H3ServiceEID process. ServerXTR encapsulates and decapsulates packets to and from EdgeRTRs.

MobilityClient: Is an application that may be a part of a vehicle system, part of a navigation application, gov-muni application etc. It has light-weight LISP data-plane stack to packets via ClientXTR.

MobilityClientEID: Is the IPv6 EID used by the Mobility Clients. The destination of such packets are H3ServiceEIDs. The EID format is assigned as part of the MobilityClient mobility-network AAA.

ClientXTR: Is a data-plane only LISP protocol stack implementation co-located with the Mobility Client application. It encapsulates and decapsulates packets to and from EdgeRTRs.

EdgeRTR: EdgeRTR network connects MobilityClients to H3ServiceEIDs. EdgeRTRs manage MobilityClients multicast registrations [RFC8378]. EdgeRTRs aggregate MobilityClients/H3Services using tunnels to facilitate hosting-providers and mobile-providers in accessing the LISP based Geolocation mobility-network. EdgeRTRs decapsulate packets from ClientXTRs and ServerXTRs, and re-encapsulates packets to clients and servers. EdgeRTRs glean H3ServiceEIDs and MobilityClient EIDs when they decapsulates packets. EdgeRTRs store H3ServiceEIDs and routelocations (RLOC) using map-caches. Mappings are registered to the LISP mapping system [I-D.ietf-lisp-rfc6833bis]. Mappings may be provisioned when H3Services are assigned EdgeRTRs. EdgeRTRs do not register MobilityClients' EIDs. Enterprises may provide their own EdgeRTRs to protect geo-privacy.

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h3.rB routed-objects grid tiles

```
H3ServiceEIDs ___ / \
                                 H3ServiceEIDs ___ / \
                                       ___ / | h3.rB |
          __ / | h3.rB |
                                    / | h3.rB \ ___ /
       / | h3.rB \ ___ /
      | h3.rB \ ___ / sXTR
                                   | h3.rB \ ___ / sXTR
       \ ___ / sXTR ||
                                    \ / sXTR
                                                  - 11
         sXTR ||
                    \Box
                                     sXTR
                                            11 11
                                             11
                    | | |
                                      \Box
                                       = = = = EdgeRTR
                                      EdgeRTR = = = = =
                     || (( ()
                                  ))
                                      (
                        Geolocation
                                       )
                        Mobility Network
                                        )
                      Based on LISP
                  ( | | | (( (()) () | | ) |
                      | | |
                                      II
            = = = = = =
                                       = = = = = =
           \Pi
                                                 EdgeRTR
                                               EdgeRTR
        (((((|)))))
                                       (((((|)))))
   /|\
       RAN /|\
                                         /|\ RAN /|\
   \prod
   \prod
                                                    \prod
 Uploads Upstream
                                                    П
Channels Downstream
   \Pi
   || << movment << / \/ \<<cXTR::MobilityClientB</pre>
   || - - - - - - h3.rS h3.rS - - - - - - - -
   MobilityClientA::cXTR >> \ ___ /\ ___ / >> movement >> ......
```

Figure 3: Geolocation clients and services interaction layout

Figure 3 above describes:

- MobilityClientA detections used by MobilityClientB, and vice versa
- Clients: share information only via Geolocation Services
- ClientXTR (cXTR):encapsulates packets over access network to EdgeRTR
- ServerXTR (sXTR):encapsulates packets over edge network to EdgeRTR
- Uploads: routed to appropriate Geolocation Service by EdgeRTRs
- Channels: originate from Geolocation Services replicated by EdgeRTRs

3. Deployment Assumptions

I. We assume detections can be localized to h3.rS tiles and can be enumerated. Compact 64bit detection enumeration format:

0	1	2	3	4	5	6	7
+	-+	-+	-+	-+	-+	-+	-++
-0- -1	- -2- -3	- -4- -5	- -6- -7	- -8- -9	- -A- -B	- -C- -D	- -E- -F-
012301	23012301	23012301	23 Index	012301	23012301	23012301	2301230123
+							+

Figure 4: Nibble based compact representation of tile state

Detections are in 16 fields x 16 enumerations. Nibbles are named using hexadecimal index according to the position where the most significant nibble has index 0. Values based on [BDD] are defined in section 8.

II. Authorization of MobilityClients to mobility-network is renewed while driving. DNS/AAA procedure described bellow can be used as an example to obtain EIDs/EdgeRTRs and for enabling use of the network. Diameter [RFC6733] based AAA can be used to accommodate many types of mobility clients in a rich eco-system: vehicle systems, driving and navigation applications, smart-city and consumer applications. Example procedure for ClientXTRs to use the mobility-network:

- 1) obtain the address of the mobility-network AAA using DNS
- 2) obtain MobilityClientEIDs and EdgeRTRs from AAA procedure
- 3) renewed periodically from AAA while using the network

MobilityClient DomainNameServer	AAA Server	MobilityEdgeRTR
lookup AAA Server	1	I
>	1	
<	1	
AAA Server IP	İ	ĺ
	I	I
Client identifier and credenti	als	ĺ
	>	ĺ
	Provi	sion Client EID
İ	<	
	Ack	Provisioed EID
Send ClientEID, EdgeRTR RLOC	I	I
<		ĺ
. Use The H3-LISP Geolocati	on Mobility Ne	etwork .
<		

	Renew AAA ClientEID and EdgeRTR provisioning	
Figure 5:	Example exchange for mobility-network usage	
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4. Mobility Clients-Services Networking

The mobility-network functions as a standard LISP overlay. The overlay delivers unicast and multicast packets across: Data-plane XTRs are used in the stack of each mobility client/server. ClientXTRs and ServerXTRs are associated with EdgeRTRs.

This structure allows for MobilityClients to "show up" at any of mobility-network location behind any network provider or network address translation domain. It allows for any H3ServiceEID to be instantiated, delegated, or failed-over to any compute location.

In this specification we assume semi-random association between ClientXTRs and EdgeRTRs assigned by the AAA procedure. We assume in any given metro area a pool of EdgeRTRs distribute the Mobility Clients load. We assume EdgeRTRs are topologically equivalent. EdgeRTRs use LISP to encapsulate traffic to and from other EdgeRTRs. There may be more than one ClientEID in the same process using the same ClientXTR. For example layers on base-map or heads-up display. Such vendor specific multiplexing implementation is unspecified he

Figure 6: LISP network connecting MobilityClients and H3ServiceEIDs

The following Lisp Canonical Address Format (LCAF) [RFC8060] is used to encode H3-IDs into IPv6 address:

Figure 7: LCAF for encoding HIDs in H3ServiceEIDs

5. Mobility Unicast and Multicast

The day in a life of unicast detection upload:

- 1. A client detects condition of interest using AI camera
- 2. The client uses its GPS to establish its h3.rS location
- 3. It then estimates the h3.rS location of the detection
- 4. Detection h3.rS center is used to calculate h3.rB => H3ServerEID
- 5. Client sends (encrypted) location-detection via its ClientXTR

Outer Header src/dest: ClientXTR RLOC, EdgeRTR RLOC Inner Header src/dest: ClientEID, H3ServiceEID

- 6. EdgeRTR gleans and caches ClientEID and ClientXTR RLOC
- 7. EdgeRTR resolves RLOC of remote EdgeRTR, and re-encapsulates:

```
Outer Header src/dest: EdgeRTR RLOC, remote EdgeRTR RLOC Inner Header src/dest: ClientEID, H3ServiceEID
```

8. Remote EdgeRTR lookups H3ServerEID ServerXTR RLOC, re-encapsulates:

```
Outer Header src/dest: EdgeRTR RLOC, ServerXTR RLOC Inner Header src/dest: ClientEID, H3ServiceEID
```

9. ServerXTR delivers ClientEID message to H3ServiceEID

The detection message headers consist of the following fields:

```
- Outer headers size = 40 (IPv6) + 8 (UDP) + 8 (LISP) = 56
```

- Inner headers size = 40 (IPv6) + 8 (UDP) + 4 (Nexagon Header) = 52
- 1500 (MTU) 56 52 = 1392 bytes of effective payload size

Nexagon Header allows for key-value (kv) tuples or value-key, key ..(vkkk) using the same formats of key and value outlined bellow

Figure 8: Nexagon header format

```
Nexagon Header Type 0:reserved (*)
Type 1:key-value, key-value.. 1392 / (8 + 8) = 87 pairs
Type 2:value, key,key,key.. (1392 - 8) / 8 = 173 h3.rS IDs
Type 3-255: unassigned
Nexagon Header GZIP field: 0x000 no compression, or (**) GZIP version.
Nexagon Header Reserved bits
Nexagon Header key and value count (in any format kv or vkkk)
```

- (*) Reserved fields are specified as being set to 0 on transmission, ignored when received.
- (**) GZIP refers to entire kv or vkkk payload and major GZIP version, packets with unsupported GZIP version are dropped

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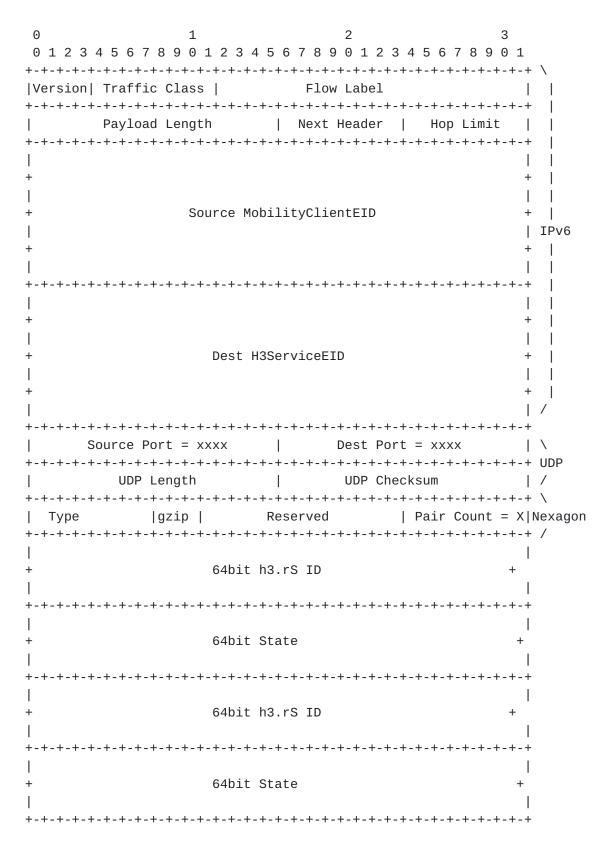


Figure 9: Uploaded detections packet format

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Each H3Service is also an IP Multicast Source used to update subscribers on the state of the h3.rS tiles in the h3.rB area. We use [RFC8378] signal-free multicast to implement overlay channels. Mobility-networks have many channels with thousands subscribers each. MobilityClients driving through/subscribing to an h3.rB area issue group address report based on any mechanism supported by [RFC8378]. Example report formats are specified in [RFC4604]. It is advised that clients establish a ring of objects on their areas of interest. Report messages are encapsulated between ClientXTRs and EdgeRTRs.

The day in a life of multicast update:

- 1. H3ServiceEID determines change or timing requiring an update
- 2. H3ServiceEID sends (S,G) update message via its ServerXTR

Outer Header src/dest: ServerXTR RLOC, EdgeRTR RLOC Inner Header (S,G): H3ServerEID, EID chosen for theme

3. EdgeRTR resolves subscribed remote EdgeRTRs, replicates

Outer Header src/dest: EdgeRTR RLOC, remote EdgeRTR RLOC Inner Header (S,G): H3ServerEID, EID chosen for theme

4. EdgeRTRs lookups subscribed ClientEIDs ClientXTRs RLOCs, replicates

Outer Header src/dest: EdgeRTR RLOC, ClientXTR RLOC Inner Header (S,G): H3ServerEID, EID chosen for theme

5. ClientXTR delivers multicast channel update message to clientEID

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Multicast update packets are of the following structure:

0	1	2	3	
0 1 2 3 4 5 6 7	8 9 0 1 2 3 4 5 6	7 8 9 0 1 2 3	4 5 6 7 8 9 0 1	1
+-+-+-+-+-+-+	-+-+-+-+-+-+-+-+	-+-+-+-+-	+-+-+-+-+-	-+ \
Version Traffic	Class	Flow Label		1 1
+-+-+-+-+-+-+	-+-+-+-+-+-+-+-+	-+-+-+-+-+-	+-+-+-+-+-+	-+
Payload	Length	Next Header	Hop Limit	1 1
+-+-+-+-+-+-+	-+-+-+-+-+-+-+	-+-+-+-+-+-	-+-+-+-+-+-+	-+
+				+
+	Source H3Ser	viceEID	+	I
				IPv6
+				+
				1 1
+-+-+-+-+-+-+	-+-+-+-+-+-+-+	-+-+-+-+-+-	+-+-+-+-+-+-	-+
				1 1
T I				+
 	Group Ac	ldrace		1 I + 1
i I	di dup Ad	iui 633		
+				+ 1
·				1 /
+-+-+-+-+-+-+	-+-+-+-+-+-+-	+-+-+-+-+-	+-+-+-+-+-	-+
Source Po	rt = xxxx	Dest Port	= xxxx	1 \
+-+-+-+-+-+-+	-+-+-+-+-+-+-+	-+-+-+-+-+-	+-+-+-+-+-	-+ UDP
UDP L	ength	UDP Chec	ksum	/
•	-+-+-+-+-+-+-	-+-+-+-+-+-	+-+-+-+-+-	-+ \
				Nexagon
+-+-+-+-+-+-+	-+-+-+-+-+-+-+-+	-+-+-+-+-		-+ /
~	Nexago	ns Payload		~
+-+-+-+-+-+-+	-+-+-+-+-+-+-+-+	-+-+-+-+-	+-+-+-+-+-	-+

Figure 10: multicast update packet header

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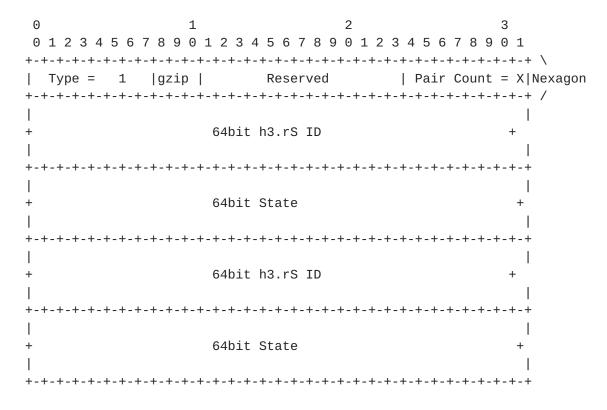


Figure 11: multicast update payload, key-value, key-value..

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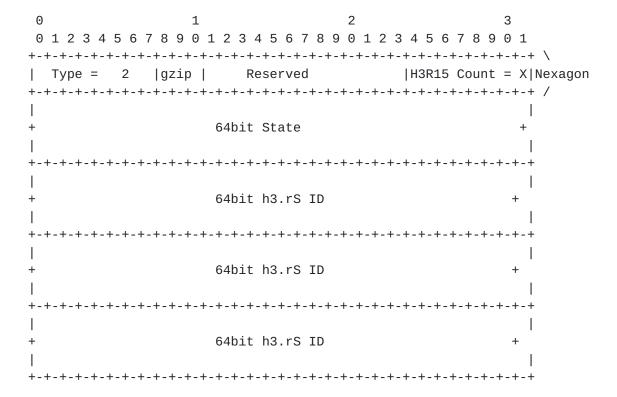


Figure 12: multicast update payload, value, key, key.. for larger areas

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6. Security Considerations

The LISP mobility-network is inherently secure and private. All information is conveyed to clients using provisioned Geolocation Services. MobilityClients receive information only via geospatial channels originating at provisioned services, replicated by EdgeRTRs. All traffic is carried over encrypted tunnels.

7. Privacy Considerations

MobilityClients have no indication as to the origin of the raw data. In order to be able to use the mobility-network for a given period, the mobility clients go through a DNS/AAA stage by which they obtain temporary clientEID and RLOCs of EdgeRTRs.

This MobilityClient to EdgeRTR interface is the most sensitive from privacy perspective. The traffic on this interface is tunneled, its detection content may be encrypted between ClientXTR to EdgeRTR. Still, the EdgeRTR will know based on headers the client RLOC, and the h3.rB area a client engages with.

Enterprises such as vehicle OEMs or carriers can "bring their own" EdgeRTRs (BYO_RTR). BYO_RTRs are pre-provisioned to be able to use the mapping system and are put on the approved list of the other EdgeRTRs. A carrier offering EdgeRTR services on multiaccess edge compute (MEC) is optimal for security and for traffic steering-replication.

Beyond client to EdgeRTR hop, the mapping system does not hold MobilityClientEIDs info. Remote EdgeRTRs are only aware of clients temporary EIDs. When EdgeRTRs register in the mapping for channels, they do not register which clients use which EdgeRTR.

The H3ServiceEIDs decrypt and parse actual h3.rS detections. They also consider MobilityClientEID credentials encoded in the client EID and assigned by AAA. This helps avoid "fake-news", e.g. poorly made or poorly localized detections.

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In summary the privacy risk mitigations are:

- (1) tapping: all communications are through tunnels therefore may be encrypted using IP-Sec or other supported point to point underlay standards.
- (2) spoofing: it is very hard to guess a MobilityClientEID valid for a short period of time. Clients and H3Services EIDs are provisioned in EdgeRTRs, Clients using the AAA procedure, H3Services via dev-ops.
- (3) credibility: the interface crowd-sources geo-state and does not assume to trust single detections. Credit history track MobilityClient EIDs as part of normal H3Services operation. The aggregate scores from all objects are delivered to AAA subsystem for updating credentials.
- (4) geo-privacy: Only EdgeRTRs are aware of both clients' RLOC and geo-location, only AAA is aware of client IDs credentials and credit but not geo-location. Ongoing client credit score adjustments span all H3Services administratively to AAA without specific geo-source.

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8. IANA Considerations

In accordance with \underline{BCP} 26 [RFC8126].IANA is asked to create a registry named NEXAGON with the following sub registries.

_	_	+	_	
Value LISP LCAF Type Name Reference				
17	H3 ID	<u>Section</u>	<u>1 4</u>	
Nexagon	+ Header Bits	•		
Spec Name	IANA Name	Bit Position	•	
Type nexagon-type gzip nexagon-gzip PairCount nexagon-paircount		0-7 8-10 t 24-31	gzip major version used	
	umeration Field 0x0:			
Value	Description	Reference +		
0x0	•	 [This Docur	·	
0x1	Lane North	ı [This Docur	ment]	
0x2	 Lane North + 30	I [This Docur	ment]	
0x3	 Lane North + 60	I [This Docur '	ment]	
0x4	 Lane North + 90	l [This Docur '	ment]	
 0x5	 Lane North + 120	l [This Docur '	nent]	
0x6	 Lane North + 150	l [This Docur	nent]	
 0×7	 Lane North + 180	l [This Docur	nent]	
0x8	 Lane North + 210	l [This Docur '	nent]	
 0x9	 Lane North + 240	 [This Docur !	nent]	
 0xA	 Lane North + 270	 [This Docur '	nent]	
 0xB	 Lane North + 300	 [This Docur 	nent]	

| Lane North + 330 | [This Document] |

0xD Junction	[This Document]	
0xE Shoulder	 [This Document]	
 0xF Sidewalk	 [This Document]	
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01 1		H 1 1 1			0 1:4:
State	Enumeration	Fleid	(i) X 1 :	Persistent	Condition:

+ Value	+ Description	++ Reference
0x0	Null	[This Document]
0x1	 Pothole Light	
0x2	 Pothole Deep	
0x3	 Speed-bump Low	
0x4	I Speed-bump High 	
0x5	 Icy	
0x6	 Flooded 	
0x7	 Snow-cover	
0x8	I Deep Snow 	
0x9	I Cone I	
0xA	 Gravel 	
0xB	ı Choppy 	
0xC	 Blind-Curve 	
0xD	ı Steep 	
0xE	I Low-bridge 	
0xF +	 Other +	

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State Enumeration Field 0x2: Transient Condition:					
Value Description Reference					
0x0	Null	[This Document]			
0x1	 Jaywalker 	 [This Document]			
0x2	 Bike or Scooter	 [This Document]			
0x3	 Stopped Vehicle	 [This Document]			
0x4	 Moving on Shoulder	 [This Document]			
0x5	 First Responder 				
0x6	 Sudden Slowdown				
0x7	 Oversize Vehicle	This Document]			
0x8 	 Light/Sign Breach 	This Document]			
0x9 	 Collision Light 	 [This Document] 			
0xA	 Collision Severe	This Document]			
0xB	 Collision Debris 	This Document]			
0xC	 Collision Course	This Document]			
0xD	 Vehicle Hard Brake 	This Document]			
I 0xE 	 Vehicle Sharp Turn 	 [This Document] 			
0xF +	 Freed-up Parking 	This Document] 			

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State Enumeration Field 0x3: Traffic-light Counter:

+ Value		Reference
0x0	Null	[This Document]
 0x1	 1 Second to Green	
 0x2	 2 Second to Green	
0x3	 3 Second to Green	
0x4	 4 Second to Green	
 0x5	 5 Second to Green	
0x6	 6 Second to Green	
0x7	 7 Second to Green	 [This Document]
0x8	 8 Second to Green	 [This Document]
0x9	 9 Second to Green	 [This Document]
0xA	 10 Second to Green	 [This Document]
0xB	 20 Second to Green	 [This Document]
0xC	 30 Second to Green	 [This Document]
0xD	 60 Second to Green 	 [This Document]
0xE	 Green Now 	
0xF +	 Red Now	 [This Document]

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State Enumeration Field 0x4: Impacted Tile:

+	+ Description	
0x0	Null	[This Document]
 0x1	 Epicenter	 [This Document]
 0x2	 2 Tiles Away	 [This Document]
0x3	 3 Tiles Away	 [This Document]
 0x4	 4 Tiles Away	
 0x5	 5 Tiles Away	
0x6	 6 Tiles Away	
0x7	 7 Tiles Away	 [This Document]
0x8	 8 Tiles Away 	 [This Document]
0x9	I 9 Tiles Away 	 [This Document]
0xA	 10 Tiles Away	 [This Document]
0xB	 20 Tiles Away	 [This Document]
0xC	 30 Tiles Away	 [This Document]
0xD	 60 Tiles Away 	 [This Document]
0xE	 <100 Tiles Away 	 [This Document]
0xF +	 <200 Tiles Away +	

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State Enumeration Field 0x5: Expected Duration:

Value	Description	
0x0	Null	[This Document]
0x1	Next 1 Second	
0x2	Next 5 Seconds	
0x3	Next 10 Seconds	
0x4	Next 20 Seconds	
0x5	Next 40 Seconds	
0x6	Next 60 Seconds	
0x7	Next 2 Minutes	 [This Document]
0x8	Next 3 Minutes	
0x9	Next 4 Minutes	 [This Document]
0xA	Next 5 Minutes	 [This Document]
0xB	Next 10 Minutes	
0xC	Next 15 Minutes	 [This Document]
0xD	Next 30 Minutes	I [This Document]
0xE	Next 60 Minutes	
0xF	Next 24 Hours	 [This Document] +

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State Enumeration Field 0x6: Lane Right Sign:

+ Value	+ Description	++ Reference
0x0	Null	[This Document]
 0x1	 Yield	
 0x2	 Speed Limit	 [This Document]
0x3	 Straight Only	
 0x4	 No Straight	
 0x5	 Right Only	
0x6	 No Right	
0x7	 Left Only	
0x8	 No Left 	
0x9	l Right Straight 	
0xA	 Left Straight	 [This Document]
0xB	I No U Turn 	
0xC	I No Left or U 	 [This Document]
0xD	 Bike Lane 	 [This Document]
0xE 	I HOV Lane 	
0xF +	 Stop +	

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State Enumeration Field 0x7: Movement Sign:

+ Value	+ Description	++ Reference
0x0	Null	[This Document]
 0x1	 Keep Right	
 0x2	 Keep Left	
0x3	l Stay in Lane	
 0x4	 Do Not Enter	
 0x5	 No Trucks	
0x6	 No Bikes 	
0x7	 No Peds	
 0x8	l One Way	
0x9	l Parking 	
0xA	l No Parking 	
0xB	 No Standing	
0xC	 No Passing 	
0xD	 Loading Zone 	
0xE	 Rail Crossing 	
0xF +	 School Zone +	

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State Enumeration Field 0x8: Curves & Intersections:

+	t	++
varue	Description +	Reference
0×0	Null	[This Document]
0x1	ı Turns Left 	
0x2	ı Turns Right 	
0x3	ı Curves Left 	
0×4	ı Curves Right 	
0x5	ı Reverses Left 	
0x6	ı Reverses Right ı	
0x7	ו Winding Road 	
0x8	I Hair Pin 	
0x9	ı Pretzel Turn 	
0xA	 Cross Roads	
0xB	 Cross T	
0xC	 Cross Y 	
0xD	 Circle 	
0xE	I Lane Ends 	
0xF +	 Road Narrows +	

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State Enumeration Field 0x9: Tile Traffic Speed:		
Value	Description	Reference
0x0	Null	[This Document]
0x1	 < 1 m/sec	
0x2	 < 2 m/sec	 [This Document]
0x3	 < 3 m/sec	 [This Document]
0x4	 < 4 m/sec	 [This Document]
0x5	 < 5 m/sec	 [This Document]
0x6	 < 6 m/sec	 [This Document]
0x7	 < 7 m/sec	 [This Document]
0x8	 < 8 m/sec	 [This Document]
0x9	 < 9 m/sec	 [This Document]
0xA	 < 10 m/sec	 [This Document]
0xB	 < 20 m/sec	 [This Document]
0xC	 < 30 m/sec	 [This Document]
0xD	 < 40 m/sec	 [This Document]
0xE	 < 50 m/sec	 [This Document]
0xF 	 > 50 m/sec +	 [This Document] +

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State Enumeration Field 0xA: Pedestrian Curb Density:

+ Value	Description	+ Reference
0x0	Null	[This Document]
 0x1	100%	
 0x2	95%	
0x3	90%	
 0x4	 85%	
 0x5	 80%	
0x6	 70%	
0x7	60%	
0x8	50%	
0x9	40%	
0xA	30%	
0xB	20%	
0xC	15%	
0xD	10%	
0xE	5%	
0xF +	 No Peds +	 [This Document] ++

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State Enumeration Field 0xB: Local Zone Speed Limit:

+	+		+
	Value		Reference
	0x0	Null	[This Document]
	0x1	1 m/sec	[This Document]
	0x2	2 m/sec	 [This Document]
	0x3	3 m/sec	 [This Document]
	0x4	4 m/sec	 [This Document]
	0x5	5 m/sec	 [This Document]
	0x6	6 m/sec	 [This Document]
	0x7	7 m/sec	 [This Document]
	0x8	8 m/sec	 [This Document]
	0x9	9 m/sec	[This Document]
	0xA	10 m/sec	 [This Document]
	0xB	15 m/sec	[This Document]
	0xC	20 m/sec	[This Document]
	0xD	25 m/sec	 [This Document]
	0xE	30 m/sec	 [This Document]
+	ا 0xF +	35 m/sec	

State enumeration fields 0xC, 0xD, 0xE, 0xF, are unassigned. IANA can assign them on a "First Come First Served" basis according to [RFC8126].

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9. Normative References

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