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R. Tamir Ariga.io A. Rodriguez-Natal F. Maino Cisco Systems A. Cabellos-Aparicio J. Paillisse-Vilanova Universitat Politecnica de Catalunya D. Farinacci lispers.net

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Network-Hexagons:Geolocation Mapping Network Based On H3 and LISP draft-ietf-lisp-nexagon-52.txt

Abstract

This specification describes functionality of LISP Nexagon networks. The network shares a joint vision of any number of producing sources, fleets, drones, and satellite, with any number of consuming clients, maps, GIS, and path planning copilots.

Specifically it outlines:

- joint-vision tiled enumeration geolocation language channels
- addressing change notifications, overlaps, points of view,
- freshness, privacy, localization, seamless context-switching,
- via stateful driving of stateless models by EID location agents

Safety applications of this network are:

- 1. Safety on-road: blockages & hazards beyond line of sight
- 2. Safety off-road: traffic-ability and varying risk degrees
- 3. Safety during disasters: fires, floods, snow, abrupt change

The use of LISP enables the network to function securely uninterrupted while vision producers and consumers are constantly moving due to the connectivity-anchoring properties of LISP EIDs. Since EIDs are logical being based on mapping-system, it provides semantic-anchoring as well. Semantic joint vision consolidation uses H3 EID unicast and multicast.

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1. Introduction

This specification describes real-time machine-to-machine trafficability mapping of any terrain based on the Locator/ID Separation protocol (LISP) and the H3 hierarchical hexagonal grid. Distributed geolocation agents are logically addressed using LISP endpoint identifiers (EID), determined by the agent's geospatial jurisdiction according to the H3 hexagonal grid. Geolocation agents consolidate and propagate data and logic to and from in-vehicle and satellite feeds. In-vehicle agents' EIDs are ephemeral to protect vehicle owners geoprivacy while interacting with geolocation agents. The in-vehicle agents' EIDs are obtained and renewed through an authorization, authentication, and accounting procedure (AAA). Geolocation traffic-ability mapping includes training and notification prompts based on H3 tile traffic-ability key-value enumeration.

The [H3] grid is a hierarchical, spatially-aware system that uses a hexagonal tiling scheme to subdivide the earth's surface into nested hexagons, each with a unique identifier (HID). This grid efficiently represents both fine-grained and coarse-grained spatial data, and its HIDs form the basis for the IPv6 EIDs of the geolocation agents in the network, also known as 'nexagons' in this document. These agents consolidate and process the data uploaded by vehicles within their jurisdiction, and delegate remote procedure calls to them. Agents use their EIDs as destination queues for vehicle uploads and source channels for updates. The agents are dynamically deployed to compute locations based on vehicle density and activity, which poses several key challenges: preserving the geo-privacy of vehicles, maintaining vehicle-agent selection coherency, context-switching between agents as vehicles move, and maintaining scaled-continuity of subscriptions to notifications from agents' channels. To address these challenges, the network employs algorithmic EID-addressing using LISP qualities.

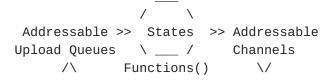


Figure 1: Nexagon Agents

The nexagon agents in the system utilize the H3 hierarchical hexagonal grid because of its clear tile adjacency properties. Each tile in the H3 grid has a unique 64-bit identifier called an HID, which is algorithmically mapped to an EID. The H3 grid is used at two resolutions: one for the nexagons ("h3.rB") and one for geo-mapping, detections, and navigation paths ("h3.rS"). Mappings between GPS coordinates, HIDs, and EIDs are all algorithmic.

Unlike traditional mapping associating geospatial attributes with objects, in this document, we associate traffic-ability enumerations to geospatial tiles. 64 bits of information about "what" traffic-ability enumerations are outlined with the 64-bit HID of "where" is the enumeration association, totaling 127 bits or 16 Bytes. Enumeration 64 bits are detailed in a bit-mask based on a taxonomy defined by Berkeley Deep Drive [BDD] and serve as a baseline. This baseline can be extended or overridden

The mobility network requires a formal provisioning step for both clients and agents. For clients, this step involves an authentication, authorization, and accounting (AAA) procedure through which clients request and renew EIDs and tunnel-routers to interact with agents. This process may be implemented using various methods or formal AAA. An example procedure is provided below.

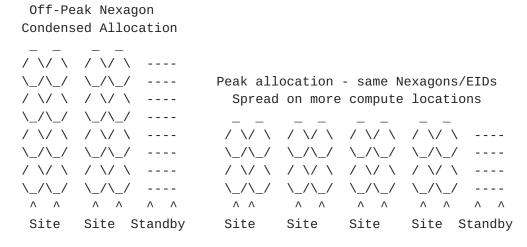


Figure 2: Nexagon dynamic allocation per activity

2. Definition of Terms

Based on [RFC9300][RFC9301]

H3AgentEID: H3AgentEID is an EID-addressable Geolocation agent, also known as a nexagon. It serves as a designated destination for Geolocation aggregation and an (S,G) source of multicast themed channels. It has a LISP data-plane stack to encapsulate packets via ServerXTR.

ServerXTR: ServerXTR is a data-plane only LISP protocol stack implementation that is co-located with the H3AgentEID process. It encapsulates and decapsulates packets to and from EdgeRTRs.

MobilityClient: MobilityClient is an application that may be a part of a driving system or mobility application, It has a LISP dataplane stack to encapsulate packets via ClientXTR.

MobilityClientEID: MobilityClientEID is the IPv6 EID used by Mobility Clients. The destination of such packets are H3AgentEIDs. The EID is assigned as part of the MobilityClient network AAA.

ClientXTR: ClientXTR is a data-plane only LISP protocol stack implementation co-located with the Mobility Client application. It encapsulates and decapsulates packets to and from EdgeRTRs.

EdgeRTR: The EdgeRTR network is responsible for connecting Mobility Clients to Agents and managing MobilityClientEIDs multicast registrations [RFC8378]. The network achieves this by using encapsulation to aggregate Mobility Clients and Geolocation Agents, making it easier to access the mobility network from hosting providers and mobile providers.

The RTRs within the EdgeRTR network re-encapsulate packets from ClientXTRs, ServerXTRs, and remote RTRs. During packet decapsulation, EdgeRTRs glean H3 agent EIDs and MobilityClientEIDs and store them along with route locations (RLOCs) in map-caches. These mappings are then registered to the LISP mapping system [RFC9301] and are provisioned when Geolocation Agents are assigned to EdgeRTRs. It's key to note that EdgeRTRs do not register MobilityClientEIDs. Enterprises can provide their own EdgeRTRs to protect the geo-privacy.

Nexagons

```
H3AgentEIDs
H3AgentEIDs
             / | h3.rB |
                                              / | h3.rB |
       / | h3.rB \ ___ /
                                         / | h3.rB \ ___ /
      | h3.rB \ ___ / sXTR
                                         | h3.rB \ ___ /
                                                        sXTR
       \ / sXTR
                                         \ / sXTR
                      | |
                                                         \Pi
         sXTR
               \Pi
                      П
                                          sXTR
                                                   \Pi
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          \Pi
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                      П
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               \Pi
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          = = = = EdgeRTR
                                           EdgeRTR = = = = =
                         ))
                                           ( Underlays used for the )
                    ( Mapping Network
                      ( | | (( ( ) ()
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            = = = = = =
                                            = = = = = =
            | | |
                                                       \Pi
         EdgeRTR
                                                     EdgeRTR
(((((|)))))
                                           ((((|))))
                                                      ((((|))))
  /|\
        RAN /|\
                                              /|\
                                                    RAN /|\
                                                          | | |
  ||<--Encapsulations to Agents' Queues & Channels via RTRs-->||
  \Pi
   <<
                              << cXTR::MobilityClientB
                                                        Vehicle
  \Pi
                                                        (_) (_)
                        \/ \/
  \prod
                    h3.rS h3.rS h3.rS - - The Tiled Road - - -
                    \ ___ /\ ___ / \ __ /
  Vehicle MobilityClientA::cXTR >> >> >>
  (_) (_)
```

Figure 3: Nexagon Network

- MobilityClientA detections used by MobilityClientB and vice versa
- Clients share information only through the Geolocation agents
- ClientXTR (cXTR):encapsulates packets over access to EdgeRTR
- ServerXTR (sXTR):encapsulates packets over metro area to EdgeRTR
- Uploads: routed to appropriate Geolocation agent by EdgeRTRs
- Notifications: from Geolocation agents replicated by EdgeRTRs

Deployment Assumptions

The authorization of Mobility Clients to the mobility network is renewed while driving. The AAA procedure described below can be used as an example for obtaining EIDs and EdgeRTRs, and for enabling the use of the network. Diameter [RFC6733] based AAA can be used:

- 1) obtain the address of the mobility-network AAA using DNS
- 2) obtain MobilityClientEIDs and EdgeRTRs from AAA procedure
- 3) renewed periodically from AAA while using the network

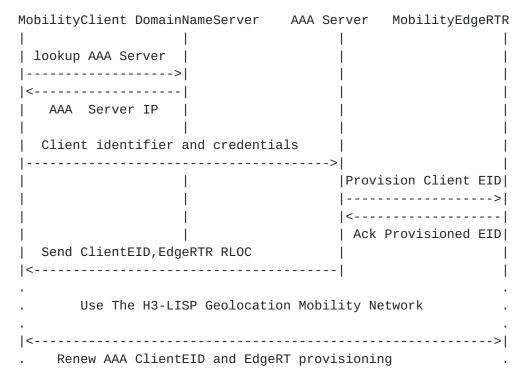


Figure 4: Example AAA procedure for mobility clients

Detections are enumerated in 16 fields \times 16 enumerations. Nibbles named using hexadecimal index according to the position where most significant nibble has index 0. Enumerations defined in section 8.

Figure 5: Nibble based detection enumeration

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4. Clients-Agents Networking

The mobility network functions as a standard LISP overlay that delivers unicast and multicast packets across data plane XTRs, which are used in the stack of each mobility client and server. ClientXTRs and ServerXTRs are associated with EdgeRTRs, which allows MobilityClients to "show up" at any location within the mobility network, regardless of the network provider or network address translation domain. This structure also enables any H3 agent EID to be instantiated, delegated, or failed over to any compute location. In this specification, we assume a semi-random association between ClientXTRs and EdgeRTRs assigned by the AAA procedure, with a pool of EdgeRTRs, which can be dynamically allocated, distributing the load of MobilityClients within a given metro area. We also assume that EdgeRTRs are topologically equivalent and use LISP to encapsulate traffic to and from other EdgeRTRs. It is possible for there to be more than one ClientEID in the same process using the same ClientXTR. The implementation of such multiplexing is not specified.

Figure 6: LISP network connecting MobilityClients and H3AgentEIDs

Figure 7: Encoding HIDs in H3AgentEIDs

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5. Mobility Unicast and Multicast

The day in a life of unicast road-segment mapping upload:

- 1. A client detects condition of interest using AI camera
- 2. The client uses its GPS to establish its h3.rS location
- 3. It then estimates the h3.rS location of the detection
- 4. Detection h3.rS center is used to calculate h3.rB => H3ServerEID
- 5. Client sends (encrypted) location-detection via its ClientXTR

Outer Header src/dest: ClientXTR RLOC, EdgeRTR RLOC Inner Header src/dest: ClientEID, H3AgentEID

- 6. EdgeRTR gleans and caches ClientEID and ClientXTR RLOC
- 7. EdgeRTR resolves RLOC of remote EdgeRTR, and re-encapsulates:

Outer Header src/dest: EdgeRTR RLOC, remote EdgeRTR RLOC Inner Header src/dest: ClientEID, H3AgentEID

8. Remote EdgeRTR lookups H3ServerEID ServerXTR RLOC, re-encapsulates:

Outer Header src/dest: EdgeRTR RLOC, ServerXTR RLOC Inner Header src/dest: ClientEID, H3AgentEID

9. ServerXTR delivers ClientEID message to H3AgentEID

The detection message headers consist of the following fields:

- Outer headers size = 40 (IPv6) + 8 (UDP) + 8 (LISP) = 56
- Inner headers size = 40 (IPv6) + 8 (UDP) + 4 (Nexagon Header) = 52
- 1500 (MTU) 56 52 = 1392 bytes of effective payload size

Figure 8: Nexagon header format

Nexagon Header allows for key-value (kv) tuples or value-key, key ...(vkkk) using the same formats of key and value outlined bellow:

Nexagon Header Type 0:reserved (*) Type 1:key-value, key-value. 1392 / (8 + 8) = 87 pairs Type 2:value, key, key, key.. (1392 - 8) / 8 = 173 h3.rS IDs Type 3-255: unassigned Nexagon Header GZIP field: 0x000 no compression, or(**) GZIP version. Nexagon Header Reserved bits Nexagon Header key and value count (in any format kv or vkkk)

- (*) Reserved fields are specified as being set to 0 on transmission, ignored when received.
- (**) GZIP refers to entire kv or vkkk payload and major GZIP version, packets with unsupported GZIP version are dropped

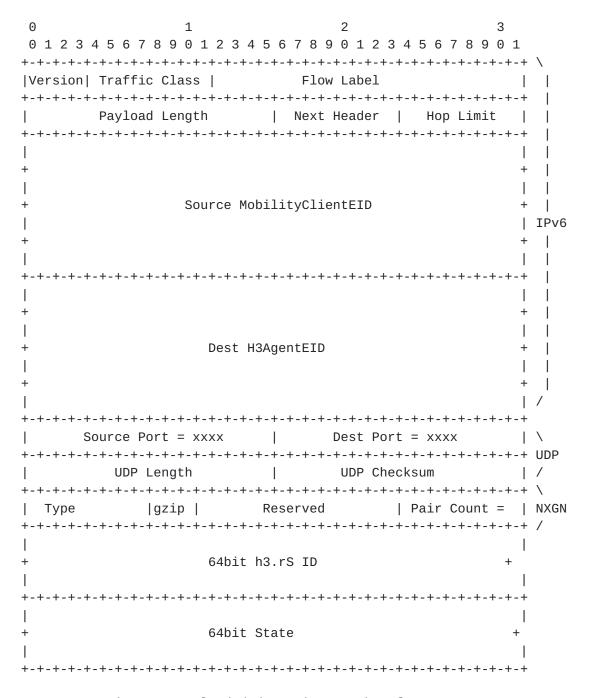


Figure 9: Uploaded detections packet format

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Each H3Agent is also an IP Multicast Source used to update subscribers on the state of the h3.rS tiles in the h3.rB area. We use [RFC8378] signal-free multicast to implement overlay channels. Mobility-networks have many channels with thousands subscribers each. MobilityClients driving through/subscribing to an h3.rB area issue group address report based on any mechanism supported by [RFC8378]. Example report formats are specified in [RFC4604]. It is advised that clients establish a ring of objects on their areas of interest. Report messages are encapsulated between ClientXTRs and EdgeRTRs.

The day in a life of multicast notification update:

- 1. H3AgentEID determines change or timing requiring an update
- 2. H3AgentEID sends (S,G) update message via its ServerXTR

Outer Header src/dest: ServerXTR RLOC, EdgeRTR RLOC Inner Header (S,G): H3ServerEID, EID chosen for theme

3. EdgeRTR resolves subscribed remote EdgeRTRs, replicates

Outer Header src/dest: EdgeRTR RLOC, remote EdgeRTR RLOC Inner Header (S,G): H3ServerEID, EID chosen for theme

4. EdgeRTRs lookups ClientEIDs ClientXTRs RLOCs, replicates

Outer Header src/dest: EdgeRTR RLOC, ClientXTR RLOC Inner Header (S,G): H3ServerEID, EID chosen for theme

5. ClientXTR delivers multicast channel update message to clientEID

Multicast update packets are of the following structure:

Θ	1	2	3
0 1 2 3 4	1 5 6 7 8 9 0 1 2 3 4	5 6 7 8 9 0 1 2 3 4 5	6 7 8 9 0 1
+-+-+-+-	+-+-+-+-+-+-	+-+-+-+-+-+-+-+-	+-+-+-+ \
Version	Traffic Class	Flow Label	
+-+-+-+-	+-+-+-+-+-+-+-+-	+-+-+-+-+-+-+-+-	+-+-+-+-
1	Payload Length	Next Header	Hop Limit
+-+-+-+-	+-+-+-+-+-+-	+-+-+-+-+-	+-+-+-+
1			
+			+
1			
+	Source	H3AgentEID	+
1			IPv6
+			+
1			
+-+-+-+-	+-+-+-+-+-+-	+-+-+-+-+-+-+-+-	+-+-+-+
1			
+			+
1			
+	Gro	oup Address	+
1			
+			+
1			/
+-+-+-+-	+-+-+-+-+-+-	+-+-+-+-+-+-+-+-	+-+-+-+-+
Sc	ource Port = xxxx	Dest Port =	xxxx \
+-+-+-+-	+-+-+-+-+-+-	+-+-+-+-+-+-+-+-	+-+-+-+ UDP
1	UDP Length	UDP Checksu	m /
+-+-+-+-	+-+-+-+-+-+-+-+-	+-+-+-+-+-+-+-+-	+-+-+-+ \
1			NXGN
+-+-+-+-	+-+-+-+-+-+-	+-+-+-+-+-+-+-+-	+-+-+- /
~	N	lexagons Payload	~
+-+-+-+-	+-+-+-+-+-	+-+-+-+-+-+-+-+-+-	+-+-+-+-+

Figure 10: multicast update packet header

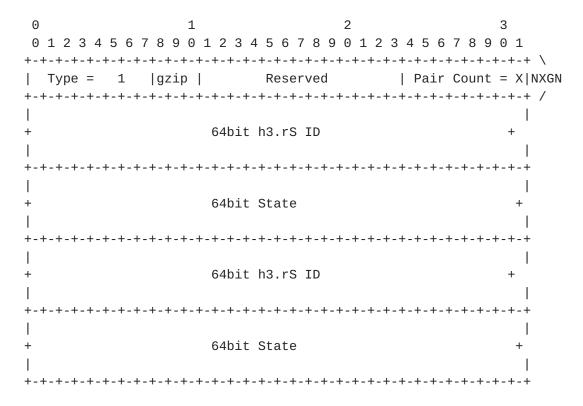


Figure 11: multicast update payload, key-value, key-value..

Θ	1	2	3
0 1 2 3 4 5 6 7 8	9 0 1 2 3 4 5 6 7 8	9 0 1 2 3 4 5	6 7 8 9 0 1
+-+-+-+-+-+-		+-+-+-+-+-+-+	+-+-+-+
Type = 2 gz	zip Reserved	H3R1	L5 Count = X NXGN
+-+-+-+-+-+-	+-+-+-+-+-+-+-+-	+-+-+-+-+-+	+-+-+-+-
+	64bit State		+
+-+-+-+-+-+-	+-+-+-+-	+-+-+-+-+-+	+-+-+-+
1			
+	64bit h3.rS ID)	+
1			
+-+-+-+-+-+-+-	+-+-+-+-+-+-+-	+-+-+-+-+-+	· +-+-+-+-+
1			I
+	64bit h3.rS ID)	+
1			I
+-+-+-+-+-+-	+-+-+-+-+-	+-+-+-+-+-+-	' +-+-+-+
1			ĺ
+	64bit h3.rS TD)	+
· -	0.010 110110 10		· I
· · · · · · · · · · · · · · · · · · ·	+-+-+-+-	+-+-+-+-+-	 +-+-+-+

Figure 12: multicast update payload, value, key, key..

6. Security Considerations

The LISP mobility-network is inherently secure and private. All information is conveyed to clients using provisioned Geolocation agents. MobilityClients receive information only via geospatial channels originating at provisioned agents, replicated by EdgeRTRs. All traffic is carried over encrypted encapsulation.

7. Privacy Considerations

In the mobility network, MobilityClients obtain temporary clientEIDs and RLOCs of EdgeRTRs through an AAA process in order to access the network for a certain period. The interface between MobilityClients and EdgeRTRs is the most sensitive from a privacy perspective, as the EdgeRTR can determine the client RLOC and the h3.rB area that the client is engaged with based on header information, even though the traffic on this interface is tunneled and the detection content is encrypted between ClientXTR and EdgeRTR. Enterprises such as vehicle OEMs or carriers can use their own EdgeRTRs (BYO_RTRs), which are pre-provisioned to use the mapping system and are approved by other EdgeRTRs. Beyond the client to EdgeRTR hop, the mapping system does not hold MobilityClientEID information and remote EdgeRTRs are only aware of clients' temporary EIDs. H3AgentEIDs decrypt and parse actual h3.rS detections, taking into account MobilityClientEID credentials encoded in the client EID and assigned by AAA to avoid poorly made or localized detections.

In summary the privacy risk mitigations are:

- (1) tapping: all communications are through tunnels therefore may be encrypted using IP-Sec or other supported point to point underlay standards.
- (2) spoofing: it is very hard to guess a MobilityClientEID valid for a short period of time. Clients and H3Agents EIDs are provisioned in EdgeRTRs, Clients using the AAA procedure, H3Agents via dev-ops.
- (3) credibility: the interface crowd-sources and does not assume to trust single detections. Credit history track MobilityClient aggregate scores from all agents are delivered to AAA subsystem
- (4) geo-privacy: Only EdgeRTRs are aware of both clients' RLOC and geo-location, only AAA is aware of client IDs credentials and credit but not geo-location. Ongoing client credit adjustments span all H3Agents administratively to AAA without specific geo-source.

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8. Acknowledgments

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9. IANA Considerations

In accordance with BCP 26 [RFC8126].IANA is asked to create a registry named NEXAGON with the following sub registries.

Spec	IANA Name	Bit	+
Type	nexagon-type	0-7	Type of key-value encoding gzip major version used key-value pair count
gzip	nexagon-gzip	8-10	
PairCount	nexagon-paircount	24-31	

State Enumeration Field 0x0: Traffic Direction:

+	+	+
Value	Description	Reference
0x0	Null	[This Document]
0x1	I Lane North 	 [This Document]
0x2	 Lane North + 30	 [This Document]
0x3	 Lane North + 60	 [This Document]
 0x4	 Lane North + 90 	 [This Document]
0x5	 Lane North + 120	 [This Document]
0x6	 Lane North + 150	 [This Document]
 0x7	 Lane North + 180	 [This Document]
0x8	 Lane North + 210	 [This Document]
0x9	 Lane North + 240	 [This Document]
0xA	 Lane North + 270	 [This Document]
0xB	 Lane North + 300	 [This Document]
0xC	 Lane North + 330	 [This Document]
 0xD	 Junction	 [This Document]
0xE	 Shoulder	 [This Document]
 0xF	 Sidewalk	 [This Document] -
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State Enumeration Field 0x1: Persistent Condition:

+ Value	+ Description	++ Reference
0x0	Null	[This Document]
 0x1	 Pothole Light	
 0x2	 Pothole Deep	 [This Document]
0x3	 Speed-bump Low	
 0x4	 Speed-bump High	 [This Document]
 0x5	 Icy	 [This Document]
0x6	 Flooded	 [This Document]
0x7	 Snow-cover	
0x8	 Deep Snow	
0x9	 Cone	
0xA	 Gravel	
0xB	l Choppy	
0xC	 Blind-Curve	
0xD	I Steep	
0xE	 Low-bridge 	
0xF +	 Other +	

State	Enumeration	Field 6	0x2: Tr	ansient	Condition:

Value	Description	Reference
0x0	Null	[This Document]
0x1	 Jaywalker 	 [This Document]
0x2	 Bike or Scooter	 [This Document]
0x3	 Stopped Vehicle	 [This Document]
0x4	 Moving on Shoulder	 [This Document]
0x5	 First Responder	 [This Document]
0x6	 Sudden Slowdown	 [This Document]
0x7	Oversize Vehicle	 [This Document]
0x8	 Light/Sign Breach 	 [This Document]
0x9	 Collision Light	 [This Document]
0xA	Collision Severe	 [This Document]
0xB	 Collision Debris	 [This Document]
0xC	 Collision Course	 [This Document]
0xD	 Vehicle Hard Brake	
0xE	 Vehicle Sharp Turn	 [This Document]
0xF 	 Freed-up Parking +	 [This Document] ++

State Enumeration Field 0x3: Traffic-light Counter:

+ Value		++ Reference
0x0	Null	[This Document]
 0x1	 1 Second to Green	
0x2	 2 Second to Green	
0x3	 3 Second to Green	 [This Document]
0x4	 4 Second to Green	
0x5	 5 Second to Green	
0x6	 6 Second to Green	
0x7	 7 Second to Green	 [This Document]
0x8	 8 Second to Green	
0x9	 9 Second to Green	
0xA	 10 Second to Green	
0xB	 20 Second to Green	
0xC	 30 Second to Green	
0xD	 60 Second to Green	
0xE	l Green Now 	
0xF	 Red Now +	

State Enumeration Field 0x4: Impacted Tile:

Ī			
	Value	·	Reference
	0x0	Null	[This Document]
	0x1	Epicenter	[This Document]
	0x2	2 Tiles Away	[This Document]
	0x3	3 Tiles Away	[This Document]
	0x4	4 Tiles Away	[This Document]
	0x5	5 Tiles Away	[This Document]
	0x6	6 Tiles Away	[This Document]
	0x7	7 Tiles Away	[This Document]
	0x8	8 Tiles Away	[This Document]
	0x9	9 Tiles Away	[This Document]
	0xA	10 Tiles Away	[This Document]
	0xB	20 Tiles Away	[This Document]
	0xC	30 Tiles Away	[This Document]
	0xD	60 Tiles Away	[This Document]
	0xE	<100 Tiles Away	[This Document]
+	0xF	<200 Tiles Away	 [This Document]

State Enumeration Field 0x5: Expected Duration:

+ Value		++ Reference
0x0	Null	[This Document]
0x1	 Next 1 Second	 [This Document]
0x2	Next 5 Seconds	 [This Document]
0x3	 Next 10 Seconds	 [This Document]
0x4	Next 20 Seconds	 [This Document]
0x5	Next 40 Seconds	 [This Document]
0x6	 Next 60 Seconds	 [This Document]
 0x7	 Next 2 Minutes	 [This Document]
0x8	Next 3 Minutes	 [This Document]
0x9	 Next 4 Minutes	 [This Document]
0xA	 Next 5 Minutes	 [This Document]
0xB	 Next 10 Minutes	 [This Document]
0xC	 Next 15 Minutes	 [This Document]
0xD	 Next 30 Minutes	
0xE	 Next 60 Minutes	
 0xF	 Next 24 Hours	 [This Document] +

State Enumeration Field 0x6: Lane Right Sign:

+		++
Value		Reference
0x0 	Null	[This Document]
0x1	Yield	 [This Document]
0x2	 Speed Limit	 [This Document]
0x3	 Straight Only	
 0x4	 No Straight	
 0x5	 Right Only	
 0x6	 No Right	
 0x7	 Left Only	
 0x8	 No Left	
 0x9	 Right Straight	
0xA	 Left Straight	
0xB	 No U Turn	
0xC	 No Left or U	
0xD	 Bike Lane	
0xE	 HOV Lane	
 0xF	 Stop	
	·	·

State Enumeration Field 0x7: Movement Sign:

	+	++
Value		Reference
0×0	Null	[This Document]
0×1	ı Keep Right ı	
0x2	ı Keep Left 	
0x3	I Stay in Lane 	
0x4	 Do Not Enter 	
0x5	I No Trucks	
0x6	 No Bikes 	
0x7	 No Peds	
0x8	I One Way	
0x9	I Parking 	
0xA	I No Parking 	
0xB	 No Standing	
0xC	I No Passing 	
0xD	ו Loading Zone 	
0xE	 Rail Crossing 	
0xF	 School Zone +	

State Enumeration Field 0x8: Curves & Intersections:

+ Value	+ Description	++ Reference
0x0	Null	[This Document]
0x1	 Turns Left	 [This Document]
0x2	 Turns Right	 [This Document]
0x3	 Curves Left	 [This Document]
 0x4	 Curves Right	 [This Document]
 0x5	 Reverses Left	 [This Document] -
0x6	 Reverses Right	 [This Document]
 0x7	 Winding Road	 [This Document]
0x8	 Hair Pin	 [This Document]
0x9	 Pretzel Turn	 [This Document]
0xA	 Cross Roads	 [This Document]
0xB	 Cross T	 [This Document]
0xC	 Cross Y	 [This Document]
0xD	 Circle	
0xE	 Lane Ends	 [This Document]
0xF	 Road Narrows	

State Enumeration	Field 0x9:	Tile	Traffic	Speed:

+		++ Reference
0x0	Null	[This Document]
0x1	 < 1 m/sec	 [This Document]
0x2	 < 2 m/sec	 [This Document]
0x3	 < 3 m/sec	 [This Document]
0x4	 < 4 m/sec	 [This Document]
0x5	 < 5 m/sec	 [This Document]
0x6	 < 6 m/sec	 [This Document]
0x7	 < 7 m/sec	 [This Document]
0x8	 < 8 m/sec	 [This Document]
0x9	 < 9 m/sec	 [This Document]
0xA	 < 10 m/sec	 [This Document]
0xB	 < 20 m/sec	 [This Document]
0xC	 < 30 m/sec	
0xD	 < 40 m/sec	I [This Document]
0xE	 < 50 m/sec	 [This Document]
0xF	 > 50 m/sec +	 [This Document] +

State Enumeration Field 0xA: Pedestrian Curb Density:

Value	Description	Reference
0x0	Null	[This Document]
0x1	100%	
0x2	95%	
0x3	90%	 [This Document]
0x4	85%	
0x5	80%	 [This Document]
0×6	70%	 [This Document]
0x7	60%	 [This Document]
0x8	50%	 [This Document]
0x9	40%	 [This Document]
0xA	30%	 [This Document]
0xB	20%	 [This Document]
0xC	15%	 [This Document]
0xD	10%	 [This Document]
0xE	5%	 [This Document]
0xF +	No Peds	

State Enumeration Field 0xB: Local Zone Speed Limit:

Value	+ Description	Reference
0x0	Null	[This Document]
0x1	 1 m/sec	 [This Document]
0x2	 2 m/sec	
0x3	 3 m/sec	
0x4 	 4 m/sec 	
0x5	 5 m/sec	
0x6	 6 m/sec 	
0×7	7 m/sec	
0x8	 8 m/sec 	
0×9	 9 m/sec 	 [This Document]
0xA	 10 m/sec 	
0xB	 15 m/sec 	
0×C	 20 m/sec 	This Document]
0xD	 25 m/sec 	
0xE 	 30 m/sec 	 [This Document]
0xF	 35 m/sec +	

State enumeration fields 0xC, 0xD, 0xE, 0xF, are unassigned. IANA can assign them on a "First Come First Served" basis according to [RFC8126].

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Authors' Addresses

Sharon Barkai Nexar CA USA

Email: sbarkai@gmail.com

Bruno Fernandez-Ruiz Nexar London UK

Email: b@getnexar.com

Rotem Tamir Nexar Israel

Email: r@ariga.io

Alberto Rodriguez-Natal Cisco Systems 170 Tasman Drive San Jose, CA USA

Email: natal@cisco.com

Fabio Maino Cisco Systems 170 Tasman Drive San Jose, CA USA

Email: fmaino@cisco.com

Albert Cabellos-Aparicio Universitat Politecnica de Catalunya Barcelona Spain

Email: acabello@ac.upc.edu

Jordi Paillisse-Vilanova Universitat Politecnica de Catalunya Barcelona Spain

Email: jordip@ac.upc.edu

Dino Farinacci lispers.net San Jose, CA USA

Email: farinacci@gmail.com