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**Node behavior upon originating and receiving Resource ReserVation
Protocol (RSVP) Path Error message
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Abstract

The aim of this document is to describe a common practice with regard to the behavior of a node sending a Resource ReserVation Protocol (RSVP) Traffic Engineering (TE) Path Error message and to the behavior of a node receiving an RSVP Path Error message for a preempted Multi-Protocol Label Switching (MPLS) and Generalized MPLS (GMPLS) Traffic Engineering Label Switched Path (TE LSP). This document does not define any new protocol extensions.

Requirements Language

The key words "MUST", "MUST NOT", "REQUIRED", "SHALL", "SHALL NOT", "SHOULD", "SHOULD NOT", "RECOMMENDED", "MAY", and "OPTIONAL" in this document are to be interpreted as described in [RFC 2119](#) [[RFC2119](#)].

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1. Introduction

The aim of this document is to describe a common practice with regard to the behavior of a node sending a Resource ReserVation Protocol (RSVP) Traffic Engineering (TE) Path Error message and to the behavior of a node receiving an RSVP Path Error message for a preempted Multi-Protocol Label Switching (MPLS) and Generalized MPLS (GMPLS) Traffic Engineering Label Switched Path (TE LSP) (for reference to the notion of TE LSP preemption see [[RFC3209](#)]).

[[RFC2205](#)] defines two RSVP error message types: PathErr and ResvErr that are generated when an error occurs. Path Error Messages (PathErr) are used to report errors and travel upstream toward the head-end of the flow. Resv Error messages (ResvErr) travel downstream toward the tail-end of the flow.

This document describes only PathErr message processing for the specific case of a preempted Traffic Engineering Label Switched Path (TE LSP) where the term preemption is defined in [[RFC3209](#)].

2. Protocol behavior

PathErr messages are routed hop-by-hop using the path state established when a Path message is routed through the network from the head-end to its tail-end.

As stated in [[RFC2205](#)], PathErr messages do not modify the state of any node through which they pass; they are only reported to the head-end of the TE LSP (Traffic Engineering Label Switched Path).

The format of the PathErr message is defined in [Section 3. of \[\[RFC2205\]\(#\)\]](#).

The ERROR_SPEC object includes the IP address of the node that detected the error (Error Node Address), and specifies the error through two fields. The Error Code field encodes the category of the error, for example, Policy Control Failure or Unknown object class. The Error Value field qualifies the error code to indicate the error with more precision. [[RFC3209](#)] extends RSVP as defined in [[RFC2205](#)] for the management of Multi-Protocol Label Switching (MPLS) Traffic Engineered Label Switched Paths (TE-LSPs). [[RFC3209](#)] specifies several additional conditions that trigger the sending of a RSVP PathErr message for which new error codes and error values have been defined that extend the list defined in [[RFC2205](#)]. The exact circumstances under which a TE LSP is preempted and such PathErr messages are sent are defined in [Section 2.2 of \[\[RFC3209\]\(#\)\]](#) and will not be repeated here.

Values for the Error Code and Error Value fields defined in [\[RFC2205\]](#), [\[RFC3209\]](#), and other documents are maintained in a registry by the IANA.

The error conditions fall into two categories:

- o Fatal errors represent disruptive conditions for a TE LSP,
- o Non-fatal errors are non-disruptive conditions which have occurred for this TE LSP

PathErr messages may be used in two circumstances:

- o During TE LSP establishment,
- o After a TE LSP has been successfully established.

Nodal behavior is dependent on which combination of the four cases listed above applies. The following sections describe the expected behavior at nodes that perform a preemption action for a TE LSP (and therefore report using error PathErr messages), and at nodes that receive PathErr messages. This text is a clarification and re-statement of the procedures set out in [\[RFC3209\]](#) and does not define any new behavior.

2.1. Behavior at Detecting Nodes

In the case of fatal errors ("Hard Preemption" see [section 4.7.3 of \[RFC3209\]](#)), the detecting node SHOULD send a PathErr message reporting the error condition, and clears the corresponding Path and Resv (control plane) states. A direct implication is that the data plane resources of such a TE LSP are also released, thus resulting in traffic disruption. It should be noted, however, that in fatal error cases, the LSP has usually already failed in the data plane, and traffic has already been disrupted. When the error arises during LSP establishment, the implications are different to when it arises on an active LSP since no traffic flows until the LSP has been fully established. In the case of non-fatal errors, the detecting node should send a PathErr message, and must not clear control plane or data plane state.

2.2. Behavior at Receiving Nodes

Nodes that receive PathErr messages are all of the nodes along the path of the TE LSP upstream of the node that detected the error. This includes the head-end node. In accordance with [\[RFC2205\] Section 3.7.1](#), a node receiving a PathErr message takes no action upon it and consequently it must not clear Path or Resv control plane

or data plane state. This is true regardless of whether the error condition reported by the PathErr is fatal or non-fatal. RSVP states should only be affected upon receiving a PathTear or ResvTear message, or in the event of a Path or Resv state timeout. Further discussion of the processing of these events is outside the scope of this document.

Note that [[RFC3473](#)] defines a Path_State_Removed flag in the ERROR_SPEC object carried on a PathErr message. This field may be set to change the behavior of upstream nodes that receive the PathErr message. When set, the flag indicates that the message sender has removed Path state (and any associated Resv and data plane state) for the TE LSP. The message receiver should do likewise before forwarding the message, but may retain state and clear the flag before forwarding the message.

2.3. Data Plane Behavior

Any node clearing either or both the Path or the Resv state of a TE LSP MUST also free up the data plane resources allocated to the corresponding TE LSP.

3. RSVP PathErr Messages For a Preempted TE LSP

Two Error-code have been defined to report a preempted TE LSP:

- o As defined in [[RFC2750](#)]:Error Code=2: "Policy Control Failure", Error Value=5 "Flow was preempted"
- o As defined in [[RFC2205](#)], Error Code=12: "Service preempted"

In both cases, these are fatal errors.

4. IANA Considerations

This document does not define any new protocol extensions and thus no action is requested to IANA.

5. Security Considerations

This document does not define any new procedures, but clarifies those defined in other documents where security considerations are already specified in [[RFC3209](#)] and [[RFC3473](#)]. This document does not raise specific security issues beyond those of existing MPLS-TE. By clarifying the procedures, this document reduces the security risk

introduced by non-conformant implementations. See [\[I-D.ietf-mpls-mpls-and-gmpls-security-framework\]](#) for further discussion of MPLS security issues.

6. Acknowledgements

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