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YANG-Push Notification Capabilities
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Abstract

This document proposes a YANG module that allows a publisher to specify capabilities related to "Subscription to YANG Datastores" (YANG-Push). It proposes to use YANG Instance Data to document this information and make it already available at implementation-time, but also allow it to be reported at run-time.

Status of This Memo

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[1.](#) Terminology

The key words "MUST", "MUST NOT", "REQUIRED", "SHALL", "SHALL NOT", "SHOULD", "SHOULD NOT", "RECOMMENDED", "NOT RECOMMENDED", "MAY", and "OPTIONAL" in this document are to be interpreted as described in [BCP 14](#) [[RFC2119](#)] [[RFC8174](#)] when, and only when, they appear in all capitals, as shown here.

The terms YANG-Push, On-change subscription and Periodic subscription are used as defined in [[RFC8641](#)]

The terms Subscriber, Publisher and Receiver are used as defined in [[RFC8639](#)]

The term Server is used as defined in [[RFC8342](#)]

On-change Notification Capability: The capability of the publisher to send on-change notifications for a specific datastore or a specific data node.

Implementation-time information: Information about the publisher's behavior that is made available during the implementation of the publisher, available from a source other than a running server implementing the publisher.

Run-time information: Information about the publisher's behavior that is available from the running server (implementing the publisher) via management protocols such as NETCONF [[RFC6241](#)] or RESTCONF [[RFC8040](#)].

2. Introduction

As defined in [[RFC8641](#)] a publisher may allow subscribers to subscribe to updates from a datastore and subsequently push such update notifications to the receiver. Notifications may be sent periodically or on-change (more or less immediately after each change).

A publisher supporting YANG-Push has a number of capabilities defined in [[RFC8641](#)] that are often determined during the implementation of the publisher. These include:

- o Supported (reporting) periods for periodic subscriptions
- o Maximum number of objects that can be sent in an update
- o The set of datastores or data nodes for which periodic notification is supported

If the optional on-change feature is supported, additionally:

- o Supported dampening periods for on-change subscriptions
- o The set of datastores or data nodes for which on-change notification is supported

Publishers have limitations in how many update notifications and how many datastore node updates they can send out in a certain time-period.

Publishers might not support periodic subscriptions to all datastores.

In some cases, a publisher supporting on-change notifications will not be able to push updates for some object types on-change. Reasons for this might be that the value of the datastore node changes frequently (e.g. in-octets counter), that small object changes are frequent and irrelevant to the receiver (e.g., a temperature gauge changing 0.1 degrees within a predetermined and acceptable range), or that the implementation is not capable of on-change notification for a particular object. In those cases, it will be important for subscriber applications to have a way to identify which objects on-change notifications are supported and for which ones not.

Faced with the reality that support for on-change notification does not mean that such notifications will be sent for any specific data node, subscriber/management applications can not rely on the on-change functionality unless the subscriber has some means to identify which objects on-change notifications are supported. YANG models are meant to be used as an interface contract. Without identification of the data nodes actually supporting on-change, this contract would be incomplete.

This document proposes a YANG module that allows a subscriber to discover YANG-Push related capabilities both at implementation-time and run-time.

Implementation-time information is needed by Network Management System (NMS) implementers. A NMS implementation that wants to support notifications, needs the information about on-change notification capability. If the information is not documented in a way available to the NMS designer, but only as instance data from the network node once it is deployed, the NMS implementation will be delayed, because it has to wait for the network node to be ready. In addition, the assumption that all NMS implementers will have a correctly configured network node available to retrieve data from is an expensive proposition and may not always hold. (An NMS may need to be able to handle many dozens of network node types.) Often a fully functional NMS is a requirement for introducing a new network node type into a network, so delaying NMS readiness effectively also delays the time at which a new network node type can be introduced into the network.

Implementation-time information is needed by system integrators. When introducing a network node type into their network, operators often need to integrate the node type into their own management system. The NMS may have management functions that depend on on-change notifications. The network operator needs to plan his management practices and NMS implementation before he even decides to buy the specific network node type. Moreover the decision to buy the node type sometimes depends on these management possibilities.

Run-time information is needed:

- o for any "purely model driven" application, e.g. a NETCONF-browser. Such applications depend on reading models, capabilities in run-time to support all the publisher's available functionality.
- o in case the capability might change during run-time e.g. due to licensing, HW constraints etc.

- o to check that capability information provided early, already in implementation-time is indeed what the publisher implements (is the supplied documentation correct?)

3. Notification Capability Model

It is a goal to provide YANG-Push notification capability information in a format that is:

- o vendor independent
- o machine readable
- o identical for implementation-time and run-time

The YANG module `ietf-notification-capabilities` is defined to provide the information. It contains:

- o a set of capabilities related to the throughput of notification data the publisher can send out.
- o specification of which data nodes support on-change notifications.

Capability values can be specified on publisher level, datastore level or on specific data nodes (and their contained sub-tree) of a specific datastore. Capability values on a smaller, more specific part of the publisher's data always override more generic values.

Note: The solution is usable for both NMDA and non-NMDA systems. For non-NMDA servers/publishers the `config=false` data is considered as if it was part of the running datastore.

The information SHOULD be provided in two ways both following the `ietf-notification-capabilities` module:

- o For the implementation-time use-case: It SHOULD be provided by the implementer as YANG instance data file complying to [\[I-D.ietf-netmod-yang-instance-file-format\]](#). The file SHALL be available already in implementation-time retrievable in a way that does not depend on a live network node. E.g. download from product website.
- o For the run-time use-case: It SHOULD be available via NETCONF [\[RFC6241\]](#) or RESTCONF [\[RFC8040\]](#) from the live server (implementing the publisher) during run-time. Implementations which support changing these capabilities at run-time SHOULD support on-change notifications about the publisher-subscription-capabilities container.

3.1. Tree Diagram

The following tree diagram [RFC8340] provides an overview of the data model.

```

module: ietf-notification-capabilities
  +--ro publisher-subscription-capabilities
    +--ro (update-period)?
      | +--:(minimum-update-period)
      | | +--ro minimum-update-period?      uint32
      | +--:(supported-update-period)
      |   +--ro supported-update-period*    uint32
    +--ro max-objects-per-update?          uint32
    +--ro minimum-dampening-period?        uint32 {yp:on-change}?
    +--ro on-change-supported?             notification-support
      |                                   {yp:on-change}?
    +--ro periodic-notifications-supported? notification-support
    +--ro supported-excluded-change-type*  union {yp:on-change}?
    +--ro datastore-capabilities* [datastore]
      +--ro datastore -> /yanglib:yang-library/datastore/name
      +--ro per-node-capabilities* [node-selector]
        +--ro node-selector                nacm:node-instance-identifier
        +--ro (update-period)?
          | +--:(minimum-update-period)
          | | +--ro minimum-update-period?      uint32
          | +--:(supported-update-period)
          |   +--ro supported-update-period*    uint32
        +--ro max-objects-per-update?          uint32
        +--ro minimum-dampening-period?        uint32
          |                                   {yp:on-change}?
        +--ro on-change-supported?             notification-support
          |                                   {yp:on-change}?
        +--ro periodic-notifications-supported? notification-support
        +--ro supported-excluded-change-type*  union {yp:on-change}?

```

3.2. YANG Module

<CODE BEGINS> file "ietf-notification-capabilities@2019-11-05.yang"

```

module ietf-notification-capabilities {
  yang-version 1.1;
  namespace
    "urn:ietf:params:xml:ns:yang:ietf-notification-capabilities";
  prefix inc;

  import ietf-netconf-acm { prefix nacm; }
  import ietf-yang-push   {
    prefix yp;

```



```
description
  "This module requires ietf-yang-push to be implemented.";
}
import ietf-yang-library {
  prefix yanglib;
  description "This module requires ietf-yang-library to
    be implemented. Revision 2019-01-04 or a
    revision derived from it is required.";
}

organization
  "IETF NETCONF (Network Configuration) Working Group";
contact
  "WG Web:   <https://datatracker.ietf.org/wg/netconf/>
   WG List:  <mailto:netconf@ietf.org>

   Editor:   Balazs Lengyel
             <mailto:balazs.lengyel@ericsson.com>";
description
  "This module specifies YANG-Push related publisher
  capabilities.

  The module contains
  - capabilities related to the throughput of notification data the
    publisher can support. (Note that for a specific subscription
    the publisher MAY still allow only longer periods or smaller
    updates depending on e.g. actual load conditions.)
  - specification of which data nodes support on-change or periodic
    notifications.

  Capability values can be specified on publisher level, datastore
  level or on specific data nodes (and their contained sub-tree) of
  a specific datastore.
  If a capability is specified on multiple levels, the
  specification on a more specific level overrides more
  generic capability specifications; thus
  - a publisher level specification is overridden by any other
    specification
  - a datastore level specification (with a node-selector '/') is
    overridden by a specification with a more specific node-selector.
  - a specification for a specific datastore and node-selector
    is overridden by a specification for the same datastore with
    a node-selector that describes more levels of containing lists
    and containers.

  If, different data nodes covered by a single subscription
  have different values for a specific capability, then using values
  that are only acceptable for some of these data nodes, but not for
```


others, may result in the rejection of the subscription.

To find a capability value for a specific node in a specific datastore the user SHALL

- 1) consider the publisher level capabilities under the publisher-subscription-capabilities container if the capability value is specified.
- 2) search for a datastore-capabilities list entry for the specific datastore.
- 3) within that datastore entry search for a per-node-capabilities entry that specifies the specific capability and that has the node-selector selecting the specific data node and that specifies the most levels of containing containers and lists.
- 4) If no entries are found in the previous steps the publisher is not capable of providing a value because it is unknown, the capability is changing for some reason, there is no specified limit etc. In this case the publisher's behavior is unspecified.

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This version of this YANG module is part of RFC XXXX; see the RFC itself for full legal notices.";

```
revision 2019-11-05 {
  description
    "Initial version";
  reference
    "RFC XXX: YANG-Push Notification Capabilities";
}
```



```
grouping subscription-capabilities {
  description "Capabilities related to Yang-Push notifications";

  typedef notification-support {
    type enumeration {
      enum no-notifications-supported {
        description "The publisher is not capable of sending any
          notifications for the relevant scope and subscription
          type." ;
      }
      enum notifications-for-config-changes-supported {
        description "The publisher is capable of sending
          notifications for config=true nodes, but not
          for config=false nodes for the relevant scope
          and subscription type." ;
      }
      enum notifications-for-state-changes-supported {
        description "The publisher is capable of sending
          notifications for config=false nodes, but not
          for config=true nodes for the relevant scope
          and subscription type." ;
      }
      enum notifications-for-all-changes-supported {
        description "The publisher is capable of sending
          notifications for both config=false and config=true
          nodes for the relevant scope and subscription type." ;
      }
    }
    description "Type for defining whether on-change or
      periodic notifications are supported for no, only config=true,
      only config=false or all data nodes.";
  }

  choice update-period {
    description "Supported update period value or values for periodic
      subscriptions.";
    leaf minimum-update-period {
      type uint32;
      units "centiseconds";
      description "Indicates the minimal update period that is
        supported for a periodic subscription.
        A periodic subscription to the selected data nodes must
        specify a value that is at least as large or greater than
        this";
      reference
        "The period leaf in RFC 8641 ietf-yang-push YANG module";
    }
  }
}
```



```
leaf-list supported-update-period {
  type uint32;
  units "centiseconds";
  description "Supported update period values for a
    periodic subscription.
    A periodic subscription to the selected data nodes must
    specify one of the values in the list; other values
    are not supported.";
  reference
    "The period leaf in RFC 8641 ietf-yang-push YANG module";
}
}

leaf max-objects-per-update {
  type uint32 {
    range "1..max";
  }
  description
    "Maximum number of objects that can be sent
    in an update for the selected data nodes.";
}

leaf minimum-dampening-period {
  if-feature yp:on-change;
  type uint32;
  units "centiseconds";
  description
    "The minimum dampening period supported for on-change
    subscriptions for the selected data nodes.";
}

leaf on-change-supported {
  if-feature yp:on-change;
  type notification-support;
  description
    "Specifies whether the publisher is capable of
    sending on-change notifications for the selected
    data store or data nodes and the subtree below them.";
}

leaf periodic-notifications-supported {
  type notification-support;
  description
    "Specifies whether the publisher is capable of
    sending periodic notifications for the selected
    data store or data nodes and the subtree below them.";
}
```



```
leaf-list supported-excluded-change-type {
  if-feature yp:on-change;
  type union {
    type enumeration {
      enum none {
        description "None of the change types can be excluded.";
      }
      enum all {
        description
          "Any combination of change types can be excluded.";
      }
    }
    type yp:change-type;
  }
  description "The change types that can be excluded in
    YANG-Push subscriptions.";
}
}

container publisher-subscription-capabilities {
  config false;
  description "YANG-Push related publisher capabilities.
    Capability values specified here at the publisher level
    are valid for all datastores and
    are used when the capability is not specified on the
    datastore level or for specific data nodes. ";

  uses subscription-capabilities {
    refine supported-excluded-change-type {
      default none;
    }
  }
}

list datastore-capabilities {
  key datastore;

  description "Capabilities values per datastore.
    For non-NMDA servers/publishers the config=false data is
    considered as if it was part of the running datastore.";

  leaf datastore {
    type leafref {
      path /yanglib:yang-library/yanglib:datastore/yanglib:name;
    }
    description "The datastore for which capabilities are defined.
      Only individual datastores can be specified
      e.g. ds:conventional is not allowed.";
  }
}
```



```
list per-node-capabilities {
  key "node-selector";
  description
    "Each list entry specifies notification capabilities
    for the selected data nodes. The same capabilities apply for
    the data nodes in the subtree below them unless another list
    entry with a more specific node selector is present.";

  leaf node-selector {
    type nacm:node-instance-identifier;
    description
      "Selects the data nodes for which capabilities are
      specified. The special value '/' denotes all data nodes
      in the datastore.
      The system SHOULD order list entries according to
      the tree structure of the data models to make
      reading/parsing the data model more simple.";
  }

  uses subscription-capabilities;
}
}
```

<CODE ENDS>

4. Security Considerations

The YANG module specified in this document defines a schema for data that is designed to be accessed via network management protocols such as NETCONF [[RFC6241](#)] or RESTCONF [[RFC8040](#)]. The lowest NETCONF layer is the secure transport layer, and the mandatory-to-implement secure transport is Secure Shell (SSH) [[RFC6242](#)]. The lowest RESTCONF layer is HTTPS, and the mandatory-to-implement secure transport is TLS [[RFC8446](#)].

The Network Configuration Access Control Model (NACM) [[RFC8341](#)] provides the means to restrict access for particular NETCONF or RESTCONF users to a preconfigured subset of all available NETCONF or RESTCONF protocol operations and content.

All protocol-accessible data nodes are read-only and cannot be modified. The data in this module is not security sensitive. Access control may be configured, to avoid exposing the read-only data.

When that data is in file format, data should be protected against modification or unauthorized access using normal file handling mechanisms.

5. IANA Considerations

5.1. The IETF XML Registry

This document registers one URI in the IETF XML registry [[RFC3688](#)]. Following the format in [[RFC3688](#)], the following registrations are requested:

URI: urn:ietf:params:xml:ns:yang:ietf-notification-capabilities
Registrant Contact: The NETCONF WG of the IETF.
XML: N/A, the requested URI is an XML namespace.

5.2. The YANG Module Names Registry

This document registers one YANG module in the YANG Module Names registry [[RFC7950](#)]. Following the format in [[RFC7950](#)], the the following registrations are requested:

name: ietf-notification-capabilities
namespace: urn:ietf:params:xml:ns:yang:ietf-notification-capabilities
prefix: inc
reference: RFC XXXX

6. References

6.1. Normative References

- [I-D.ietf-netmod-yang-instance-file-format]
Lengyel, B. and B. Claise, "YANG Instance Data File Format", [draft-ietf-netmod-yang-instance-file-format-04](#) (work in progress), August 2019.
- [RFC6241] Enns, R., Ed., Bjorklund, M., Ed., Schoenwaelder, J., Ed., and A. Bierman, Ed., "Network Configuration Protocol (NETCONF)", [RFC 6241](#), DOI 10.17487/RFC6241, June 2011, <<https://www.rfc-editor.org/info/rfc6241>>.
- [RFC6242] Wasserman, M., "Using the NETCONF Protocol over Secure Shell (SSH)", [RFC 6242](#), DOI 10.17487/RFC6242, June 2011, <<https://www.rfc-editor.org/info/rfc6242>>.
- [RFC7950] Bjorklund, M., Ed., "The YANG 1.1 Data Modeling Language", [RFC 7950](#), DOI 10.17487/RFC7950, August 2016, <<https://www.rfc-editor.org/info/rfc7950>>.

- [RFC8040] Bierman, A., Bjorklund, M., and K. Watsen, "RESTCONF Protocol", [RFC 8040](#), DOI 10.17487/RFC8040, January 2017, <<https://www.rfc-editor.org/info/rfc8040>>.
- [RFC8342] Bjorklund, M., Schoenwaelder, J., Shafer, P., Watsen, K., and R. Wilton, "Network Management Datastore Architecture (NMDA)", [RFC 8342](#), DOI 10.17487/RFC8342, March 2018, <<https://www.rfc-editor.org/info/rfc8342>>.
- [RFC8446] Rescorla, E., "The Transport Layer Security (TLS) Protocol Version 1.3", [RFC 8446](#), DOI 10.17487/RFC8446, August 2018, <<https://www.rfc-editor.org/info/rfc8446>>.
- [RFC8639] Voit, E., Clemm, A., Gonzalez Prieto, A., Nilsen-Nygaard, E., and A. Tripathy, "Subscription to YANG Notifications", [RFC 8639](#), DOI 10.17487/RFC8639, September 2019, <<https://www.rfc-editor.org/info/rfc8639>>.
- [RFC8641] Clemm, A. and E. Voit, "Subscription to YANG Notifications for Datastore Updates", [RFC 8641](#), DOI 10.17487/RFC8641, September 2019, <<https://www.rfc-editor.org/info/rfc8641>>.

6.2. Informative References

- [RFC2119] Bradner, S., "Key words for use in RFCs to Indicate Requirement Levels", [BCP 14](#), [RFC 2119](#), DOI 10.17487/RFC2119, March 1997, <<https://www.rfc-editor.org/info/rfc2119>>.
- [RFC3688] Mealling, M., "The IETF XML Registry", [BCP 81](#), [RFC 3688](#), DOI 10.17487/RFC3688, January 2004, <<https://www.rfc-editor.org/info/rfc3688>>.
- [RFC8174] Leiba, B., "Ambiguity of Uppercase vs Lowercase in [RFC 2119](#) Key Words", [BCP 14](#), [RFC 8174](#), DOI 10.17487/RFC8174, May 2017, <<https://www.rfc-editor.org/info/rfc8174>>.
- [RFC8340] Bjorklund, M. and L. Berger, Ed., "YANG Tree Diagrams", [BCP 215](#), [RFC 8340](#), DOI 10.17487/RFC8340, March 2018, <<https://www.rfc-editor.org/info/rfc8340>>.

Appendix A. Instance data examples

The following example is instance-data describing the notification capabilities of a hypothetical "acme-switch". The switch implements the running, candidate and operational datastores. Every change can be reported on-change from running, nothing from candidate and all

config=false data from operational. Periodic subscriptions are supported for running and operational, but not for candidate.

```
<?xml version="1.0" encoding="UTF-8"?>
<instance-data-set xmlns=
  "urn:ietf:params:xml:ns:yang:ietf-yang-instance-data">
  <name>acme-switch-notification-capabilities</name>
  <yid-version>1</yid-version>
  <content-schema>
    <module>ietf-notification-capabilities@2019-10-22.yang</module>
  </content-schema>
  <!-- revision date, contact, etc. -->
  <description>Notification capabilities of acme-switch.
    Acme-switch implements the running, candidate and operational
    datastores. Every change can be reported on-change from running,
    nothing from candidate and all config=false data from operational.
    Periodic subscriptions are supported for running and
    operational, but not for candidate.
  </description>
  <content-data>
    <publisher-subscription-capabilities
      xmlns="urn:ietf:params:xml:ns:yang:ietf-notification-capabilities"
      xmlns:ds="urn:ietf:params:xml:ns:yang:ietf-datastores">
      <minimum-update-period>500</minimum-update-period>
      <max-objects-per-update>2000</max-objects-per-update>
      <minimum-dampening-period>100</minimum-dampening-period>
      <periodic-notifications-supported>
        notifications-for-all-changes-supported
      </periodic-notifications-supported>
      <datastore-capabilities>
        <datastore>ds:operational</datastore>
        <per-node-capabilities>
          <node-selector>/</node-selector>
          <on-change-supported>
            notifications-for-state-changes-supported
          </on-change-supported>
        </per-node-capabilities>
      </datastore-capabilities>
      <datastore-capabilities>
        <datastore>ds:candidate</datastore>
        <per-node-capabilities>
          <node-selector>/</node-selector>
          <on-change-supported>no-notifications-supported
          </on-change-supported>
          <periodic-notifications-supported>no-notifications-supported
          </periodic-notifications-supported>
        </per-node-capabilities>
      </datastore-capabilities>
    </publisher-subscription-capabilities>
  </content-data>
</instance-data-set>
```



```

    <datastore-capabilities>
      <datastore>ds:running</datastore>
      <per-node-capabilities>
        <node-selector>/</node-selector>
        <on-change-supported>notifications-for-all-changes-supported
          </on-change-supported>
      </per-node-capabilities>
    </datastore-capabilities>
  </publisher-subscription-capabilities>
</content-data>
</instance-data-set>

```

Figure 1: Notification Capabilities with datastore level settings

The following is the instance-data describing the notification capabilities of a hypothetical "acme-router". The router implements the running, and operational datastores. Every change can be reported on-change from running, but only config=true nodes and some config=false data from operational. Interface statistics are not reported on-change only 2 important counters. Datastore subscription capabilities are not reported on-change as they never change on the acme-router during run-time.

```

<?xml version="1.0" encoding="UTF-8"?>
<instance-data-set xmlns=
  "urn:ietf:params:xml:ns:yang:ietf-yang-instance-data">
  <name>acme-router-notification-capabilities</name>
  <yid-version>1</yid-version>
  <content-schema>
    <module>ietf-notification-capabilities@2019-10-22.yang</module>
  </content-schema>
  <!-- revision date, contact, etc. -->
  <description>Defines the notification capabilities of an acme-router.
    The router only has running, and operational datastores.
    Every change can be reported on-change from running, but
    only config=true nodes and some config=false data from operational.
    Statistics are not reported on-change only 2 important counters,
    for these a smaller dampening period is possible.
  </description>
  <content-data>
    <publisher-subscription-capabilities
      xmlns="urn:ietf:params:xml:ns:yang:ietf-notification-capabilities"
      xmlns:ds="urn:ietf:params:xml:ns:yang:ietf-datastores">
      <minimum-update-period>500</minimum-update-period>
      <max-objects-per-update>2000</max-objects-per-update>
      <minimum-dampening-period>100</minimum-dampening-period>
      <periodic-notifications-supported>
        notifications-for-all-changes-supported

```



```
</periodic-notifications-supported>
<on-change-supported>
  notifications-for-all-changes-supported
</on-change-supported>
<supported-excluded-change-type>
  all
</supported-excluded-change-type>
<datastore-capabilities>
  <datastore>ds:operational</datastore>
  <per-node-capabilities>
    <node-selector>
      /if:interfaces/if:interface/if:statistics</node-selector>
    <on-change-supported>
      no-notifications-supported
    </on-change-supported>
  </per-node-capabilities>
  <per-node-capabilities>
    <node-selector>
      /if:interfaces/if:interface/if:statistics/if:in-octets
    </node-selector>
    <minimum-dampening-period>10</minimum-dampening-period>
    <on-change-supported>
      notifications-for-all-changes-supported
    </on-change-supported>
  </per-node-capabilities>
  <per-node-capabilities>
    <node-selector>
      /if:interfaces/if:interface/if:statistics/if:out-octets
    </node-selector>
    <minimum-dampening-period>10</minimum-dampening-period>
    <on-change-supported>
      notifications-for-all-changes-supported
    </on-change-supported>
  </per-node-capabilities>
</datastore-capabilities>
</publisher-subscription-capabilities>
</content-data>
</instance-data-set>
```

Figure 2: Notification Capabilities with data node specific settings

Appendix B. Changes between revisions

v06 - v07

- o Updated examples according to [draft-ietf-netmod-yang-instance-file-format-05](#).

v05 - v06

- o Providing the capability data is only a "SHOULD" recommendation. Some reviewers wanted MUST some wanted much less.
- o The YANG module import statements now indicate the imported modules that must be implemented not just available as import as requested by the YangDoctors review.

v04 - v05

- o Added new capabilities periodic-notifications-supported and supported-excluded-change-type.
- o Restructured YANG module to make the node-selector's usage similar to how NACM uses it: "/" means the whole datastore.
- o Small corrections, spelling, rewording
- o Replaced the term server with the term publisher except in cases where we speak about datastores and functionality based on get, getconfig operations. In this latter case it is really the server functionality that is discussed

v03 - v04

- o Clarified recommended support for on-change notifications about the datastore-subscription-capabilities.

v02 - v03

- o Allow throughput related capabilities to be defined on top, datastore or data node level. Described that specific capability values always override generic ones.
- o Indicate that non-NMDA servers can also use this model.
- o Updated according to [draft-ietf-netmod-yang-instance-file-format-04](#)

v01 - v02

- o Added instance data examples
- o On-change capability can be defined per datastore
- o Added "if-feature yp:on-change" where relevant

- o Unified units used

v00 - v01

- o Add more capabilities: minimum period, supported period max-number of objects, min dampening period, dampening supported

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