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## **Inter Stateful Path Computation Element (PCE) Communication Procedures.**

### **Abstract**

The Path Computation Element Communication Protocol (PCEP) provides mechanisms for Path Computation Elements (PCEs) to perform path computation in response to a Path Computation Client (PCC) request. The Stateful PCE extensions allow stateful control of Multi-Protocol Label Switching (MPLS) Traffic Engineering (TE) Label Switched Paths (LSPs) using PCEP.

A Path Computation Client (PCC) can synchronize an LSP state information to a Stateful Path Computation Element (PCE). A PCC can have multiple PCEP sessions towards multiple PCEs. There are some use cases, where an inter-PCE stateful communication can bring additional resiliency in the design, for instance when some PCC-PCE session fails.

This document describes the procedures to allow a stateful communication between PCEs for various use-cases and also the procedures to prevent computations loops.

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## 1. Introduction and Problem Statement

The Path Computation Element communication Protocol (PCEP) [[RFC5440](#)] provides mechanisms for Path Computation Elements (PCEs) to perform path computations in response to Path Computation Clients' (PCCs) requests.

A stateful PCE [[RFC8231](#)] is capable of considering, for the purposes of path computation, not only the network state in terms of links and nodes (referred to as the Traffic Engineering Database or TED) but also the status of active services (previously computed paths, and currently reserved resources, stored in the Label Switched Paths Database (LSP-DB).

[[RFC8051](#)] describes general considerations for a stateful PCE deployment and examines its applicability and benefits, as well as its challenges and limitations through a number of use cases.

A PCC can synchronize an LSP state information to a Stateful PCE. The stateful PCE extension allows a redundancy scenario where a PCC can have redundant PCEP sessions towards multiple PCEs. In such a case, a PCC gives control of a LSP to only a single PCE, and only one PCE is responsible for path computation for this delegated LSP.

There are some use cases, where an inter-PCE stateful communication can bring additional resiliency in the design, for instance when some PCC-PCE session fails. The inter-PCE stateful communication may also provide a faster update of the LSP states when such an event occurs. Finally, when, in a redundant PCE scenario, there is a need to compute a set of paths that are part of a group (so there is a dependency between the paths), there may be some cases where the computation of all paths in the group is not handled by the same PCE: this situation is called a split-brain. This split-brain scenario may lead to computation loops between PCEs or suboptimal path computation.

This document describes the procedures to allow a stateful communication between PCEs for various use-cases and also the procedures to prevent computations loops.

Further, the examples in this section are for illustrative purpose to showcase the need for inter-PCE stateful PCEP sessions.

## 1.1. Requirements Language

The key words "MUST", "MUST NOT", "REQUIRED", "SHALL", "SHALL NOT", "SHOULD", "SHOULD NOT", "RECOMMENDED", "NOT RECOMMENDED", "MAY", and "OPTIONAL" in this document are to be interpreted as described in BCP 14 [[RFC2119](#)] [[RFC8174](#)] when, and only when, they appear in all capitals, as shown here.

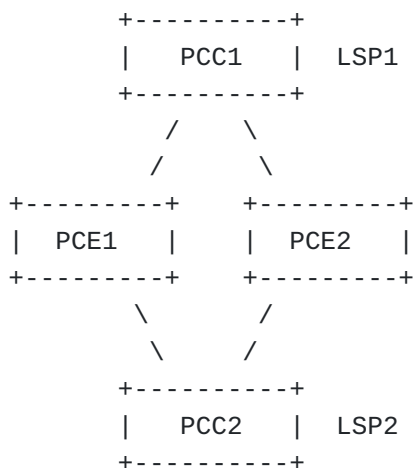
## 1.2. Reporting LSP Changes

When using a stateful PCE ([[RFC8231](#)]), a PCC can synchronize an LSP state information to the stateful PCE. If the PCC grants the control of the LSP to the PCE (called delegation [[RFC8231](#)]), the PCE can update the LSP parameters at any time.

In a multi PCE deployment (redundancy, loadbalancing...), with the current specification defined in [[RFC8231](#)], when a PCE makes an update, it is the PCC that is in charge of reporting the LSP status to all PCEs with LSP parameter change which brings additional hops and delays in notifying the overall network of the LSP parameter change.

This delay may affect the reaction time of the other PCEs if they need to take action after being notified of the LSP parameter change.

Apart from the synchronization from the PCC, it is also useful if there is a synchronization mechanism between the stateful PCEs. As stateful PCE make changes to its delegated LSPs, these changes (pending LSPs and the sticky resources [[RFC7399](#)]) can be synchronized immediately to the other PCEs.



In the figure above, we consider a load-balanced PCE architecture, so PCE1 is responsible to compute paths for PCC1 and PCE2 is responsible to compute paths for PCC2. When PCE1 triggers an LSP

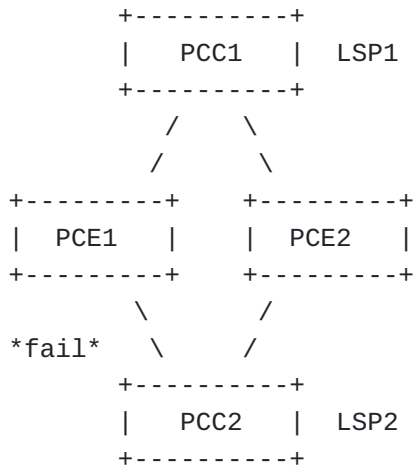
update for LSP1, it sends a PCUpd message to PCC1 containing the new parameters for LSP1. PCC1 will take the parameters into account and will send a PCRpt message to PCE1 and PCE2 reflecting the changes. PCE2 will so be notified of the change only after receiving the PCRpt message from PCC1.

Let's consider that the LSP1 parameters changed in such a way that LSP1 will take over resources from LSP2 with a higher priority. After receiving the report from PCC1, PCE2 will therefore try to find a new path for LSP2. If we consider that there is a round trip delay of about 150 milliseconds (ms) between the PCEs and PCC1 and a round trip delay of 10 ms between the two PCEs it will take more than 150 ms for PCE2 to be notified of the change.

Adding a PCEP session between PCE1 and PCE2 may allow to reduce the synchronization time, so PCE2 can react more quickly by taking the pending LSPs and attached resources into account during path computation and re-optimization.

### **1.3. Split-Brain**

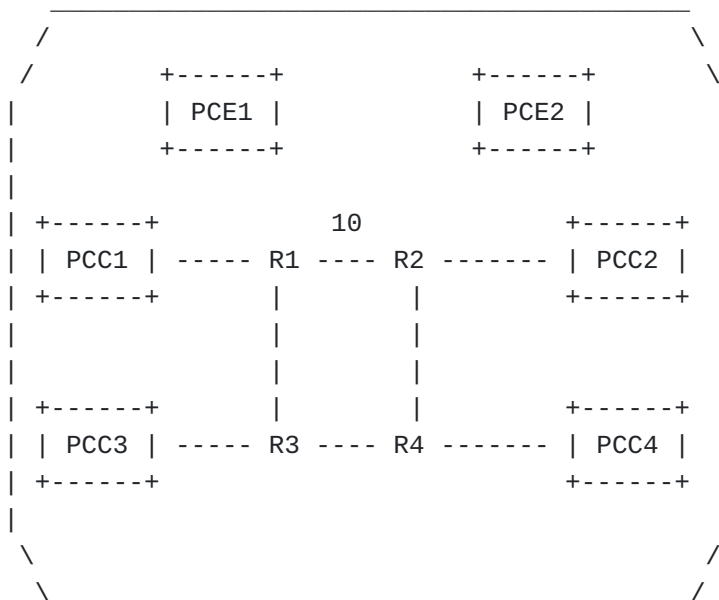
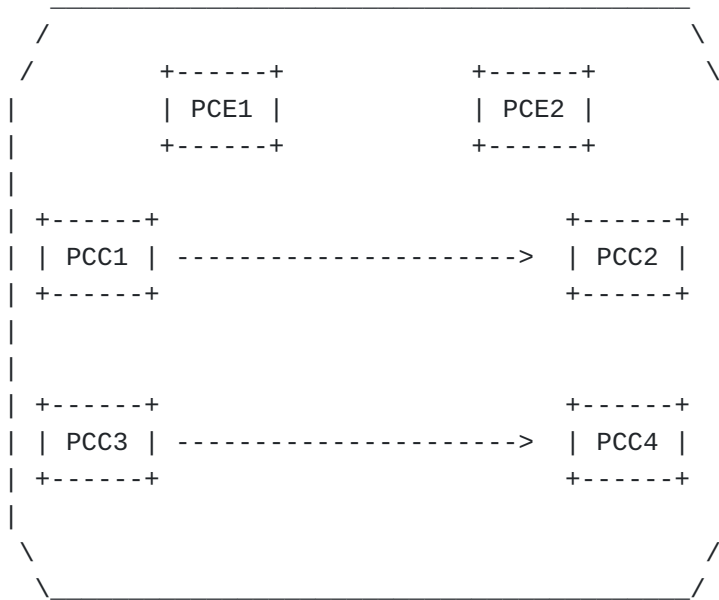
In a resiliency case, a PCC has redundant PCEP sessions towards multiple PCEs. In such a case, a PCC gives control on an LSP to a single PCE only, and only this PCE is responsible for the path computation for the delegated LSP: the PCC achieves this by setting the D flag only towards the active PCE [[RFC8231](#)] selected for delegation. The election of the active PCE to delegate an LSP is controlled by each PCC. The PCC usually elects the active PCE by a local configured policy (by setting a priority). Upon PCEP session failure, or active PCE failure, PCC may decide to elect a new active PCE by sending new PCRpt message with D flag set to this new active PCE. When the failed PCE or PCEP session comes back online, it will be up to the implementation to do preemption. Doing preemption may lead to some disruption on the existing path if path results from both PCEs are not exactly the same. By considering a network with multiple PCCs and implementing multiple stateful PCEs for redundancy purpose, there is no guarantee that at any time all the PCCs delegate their LSPs to the same PCE.



In the example above, we consider that by configuration, both PCCs will firstly delegate their LSPs to PCE1. So, PCE1 is responsible for computing a path for both LSP1 and LSP2. If the PCEP session between PCC2 and PCE1 fails, PCC2 will delegate LSP2 to PCE2. So PCE1 becomes responsible only for LSP1 path computation while PCE2 is responsible for the path computation of LSP2. When the PCC2-PCE1 session is back online, PCC2 will keep using PCE2 as active PCE (consider no preemption in this example). So the result is a permanent situation where each PCE is responsible for a subset of path computation.

This situation is called a split-brain scenario, as there are multiple computation brains running at the same time while a central computation unit was required in some deployments/use cases.

Further, there are use cases where a particular LSP path computation is linked to another LSP path computation: the most common use case is path disjointness (see [[RFC8800](#)]). The set of LSPs that are dependent to each other may start from a different head-end.



In the figure above, the requirement is to create two link-disjoint LSPs: PCC1->PCC2 and PCC3->PCC4. In the topology, all links cost metric is set to 1 except for the link 'R1-R2' which has a metric of 10. The PCEs are responsible for the path computation and PCE1 is the active primary PCE for all PCCs in the nominal case.

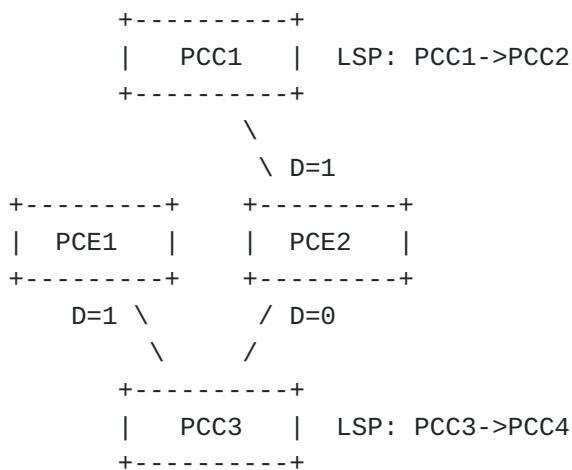
Scenario 1:

In the normal case (PCE1 as active primary PCE), consider that PCC1->PCC2 LSP is configured first with the link disjointness constraint,

PCE1 sends a PCUpd message to PCC1 with the ERO: R1->R3->R4->R2->PCC2 (shortest path). PCC1 signals and installs the path. When PCC3->PCC4 is configured, the PCEs already knows the path of PCC1->PCC2 and can compute a link-disjoint path: the solution requires to move PCC1->PCC2 onto a new path to let room for the new LSP. PCE1 sends a PCUpd message to PCC1 with the new ERO: R1->R2->PCC2 and a PCUpd to PCC3 with the following ERO: R3->R4->PCC4. In the normal case, there is no issue for PCE1 to compute a link-disjoint path.

Scenario 2:

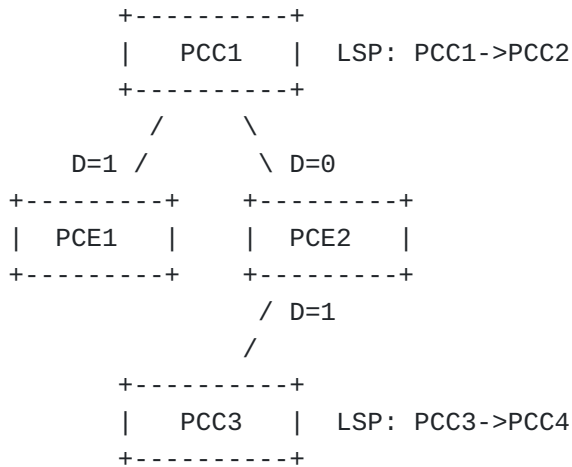
Consider that PCC1 lost its PCEP session with PCE1 (all other PCEP sessions are UP). PCC1 delegates its LSP to PCE2.



Consider that the PCC1->PCC2 LSP is configured first with the link disjointness constraint, PCE2 (which is the new active primary PCE for PCC1) sends a PCUpd message to PCC1 with the ERO: R1->R3->R4->R2->PCC2 (shortest path). When PCC3->PCC4 is configured, PCE1 is not aware of LSPs from PCC1 any more, so it cannot compute a disjoint path for PCC3->PCC4 and will send a PCUpd message to PCC3 with the shortest path ERO: R3->R4->PCC4. When PCC3->PCC4 LSP will be reported to PCE2 by PCC3, PCE2 will ensure disjointness computation and will correctly move PCC1->PCC2 (as it owns delegation for this LSP) on the following path: R1->R2->PCC2. With this sequence of event and these PCEP sessions, disjointness is ensured.

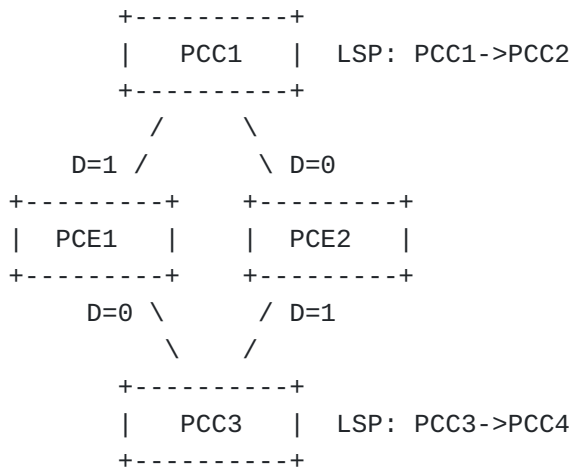
Scenario 3:





Consider the above PCEP sessions and the PCC1->PCC2 LSP is configured first with the link disjointness constraint, PCE1 computes the shortest path as it is the only LSP in the disjoint association group that it is aware of: R1->R3->R4->R2->PCC2 (shortest path). When PCC3->PCC4 is configured, PCE2 must compute a disjoint path for this LSP. The only solution found is to move PCC1->PCC2 LSP on another path, but PCE2 cannot do it as it does not have delegation for this LSP. In this set-up, PCEs are not able to find a disjoint path.

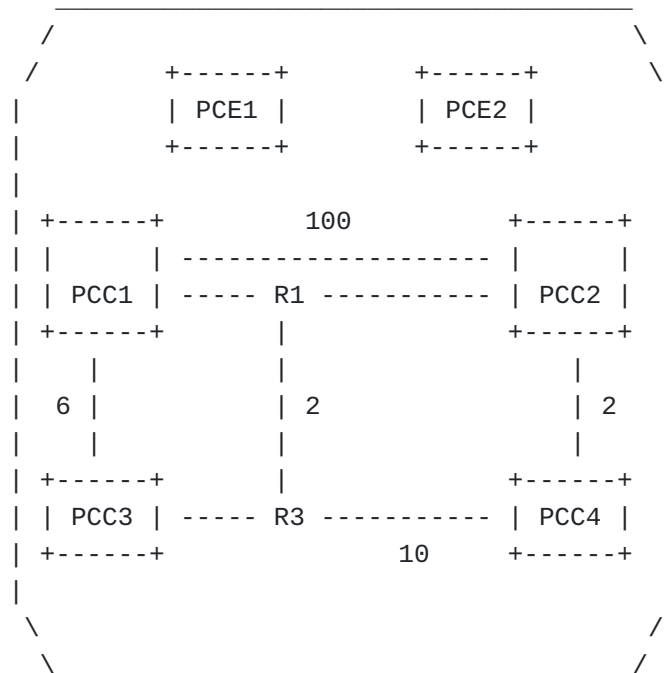
Scenario 4:



Consider the above PCEP sessions and that PCEs are configured to fall-back to the shortest path if disjointness cannot be found as described in [[RFC8800](#)]. The PCC1->PCC2 LSP is configured first, PCE1 computes the shortest path as it is the only LSP in the disjoint association group that it is aware of: R1->R3->R4->R2->PCC2 (shortest path). When PCC3->PCC4 is configured, PCE2 must compute a disjoint path for this LSP. The only solution found is to move PCC1->

>PCC2 LSP on another path, but PCE2 cannot do it as it does not have delegation for this LSP. PCE2 then provides the shortest path for PCC3->PCC4: R3->R4->PCC4. When PCC3 receives the ER0, it reports it back to both PCEs. When PCE1 becomes aware of the PCC3->PCC4 path, it recomputes the constrained shortest path first (CSPF) algorithm and provides a new path for PCC1->PCC2: R1->R2->PCC2. The new path is reported back to all PCEs by PCC1. PCE2 recomputes also CSPF to take into account the new reported path. The new computation does not lead to any path update.

Scenario 5:

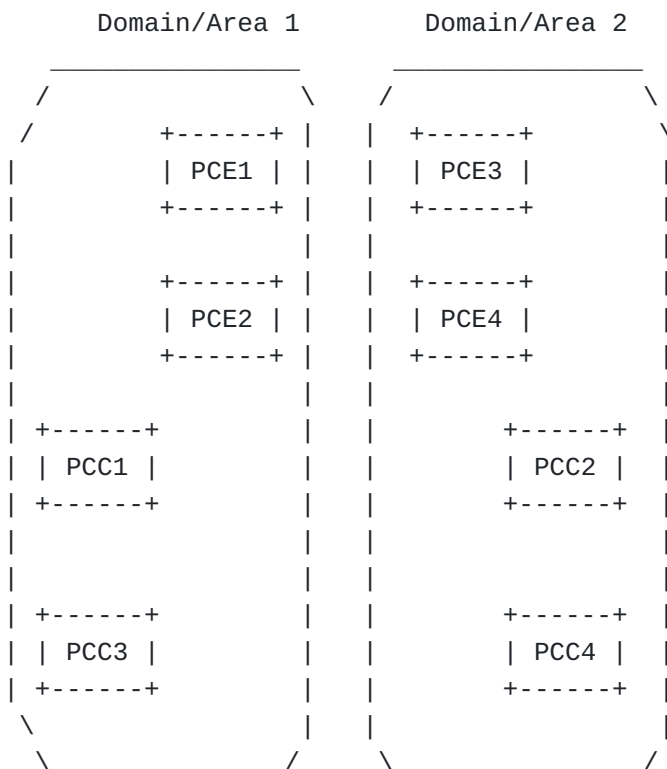


Now, consider a new network topology with the same PCEP sessions as the previous example. Suppose that both LSPs are configured almost at the same time. PCE1 will compute a path for PCC1->PCC2 while PCE2 will compute a path for PCC3->PCC4. As each PCE is not aware of the path of the second LSP in the association group (not reported yet), each PCE is computing the shortest path for the LSP. PCE1 computes ER0: R1->PCC2 for PCC1->PCC2 and PCE2 computes ER0: R3->R1->PCC2->PCC4 for PCC3->PCC4. When these shortest paths will be reported to each PCE. Each PCE will recompute disjointness. PCE1 will provide a new path for PCC1->PCC2 with ER0: PCC1->PCC2. PCE2 will provide also a new path for PCC3->PCC4 with ER0: R3->PCC4. When those new paths will be reported to both PCEs, this will trigger CSPF again. PCE1 will provide a new more optimal path for PCC1->PCC2 with ER0: R1->PCC2 and PCE2 will also provide a more optimal path for PCC3->PCC4 with ER0: R3->R1->PCC2->PCC4. So we come back to the initial state.

When those paths will be reported to both PCEs, this will trigger CSPF again. An infinite loop of CSPF computation is then happening with a permanent flap of paths because of the split-brain situation.

This permanent computation loop comes from the inconsistency between the state of the LSPs as seen by each PCE due to the split-brain: each PCE is trying to modify at the same time its delegated path based on the last received path information which de facto invalidates this received path information.

## Scenario 6: multi-domain



In the example above, suppose that the disjoint LSPs from PCC1 to PCC2 and from PCC4 to PCC3 are created. All the PCEs have the knowledge of both domain topologies (e.g. using BGP-LS [RFC7752]). For operation/management reasons, each domain uses its own group of redundant PCEs. PCE1/PCE2 in domain 1 have PCEP sessions with PCC1 and PCC3 while PCE3/PCE4 in domain 2 have PCEP sessions with PCC2 and PCC4. As PCE1/2 does not know about LSPs from PCC2/4 and PCE3/4 do not know about LSPs from PCC1/3, there is no possibility to compute the disjointness constraint. This scenario can also be seen as a split-brain scenario. This multi-domain architecture (with multiple groups of PCEs) can also be used in a single domain, where an operator wants to limit the failure domain by creating multiple groups of PCEs maintaining a subset of PCCs. As for the multi-domain

example, there will be no possibility to compute the disjoint path starting from head-ends managed by different PCE groups.

In this document, we propose a solution that addresses the possibility to compute LSP association based constraints (like disjointness) in split-brain scenarios while preventing computation loops.

#### **1.4. Applicability to H-PCE**

[[RFC8751](#)] describes general considerations and use cases for the deployment of Stateful PCE(s) using the Hierarchical PCE [[RFC6805](#)] architecture. In this architecture, there is a clear need to communicate between a child stateful PCE and a parent stateful PCE. The procedures and extensions as described in [Section 3](#) are equally applicable to the H-PCE scenario.

### **2. Proposed solution**

Our solution is based on :

- \*The creation of the inter-PCE stateful PCEP session with specific procedures.

- \*A Primary/Secondary relationship between PCEs.

#### **2.1. State-sync session**

This document proposes to set-up a PCEP session between the stateful PCEs. Creating such a session is already authorized by multiple scenarios like the one described in [[RFC4655](#)] (multiple PCEs that are handling part of the path computation) and [[RFC6805](#)] (hierarchical PCE) but was only focused on the stateless PCEP sessions. As stateful PCE brings additional features (LSP state synchronization, path update, delegation, ...), thus some new behaviors need to be defined.

This inter-PCE PCEP session will allow the exchange of LSP states between PCEs that would help some scenarios where PCEP sessions are lost between PCC and PCE. This inter-PCE PCEP session is henceforth called a state-sync session.

For example, in the scenario below, there is no possibility to compute disjointness as there is no PCE that is aware of both LSPs.

```

+-----+
|  PCC1  | LSP: PCC1->PCC2
+-----+
/
D=1 /
+-----+ +-----+
|  PCE1  | |  PCE2  |
+-----+ +-----+
/ D=1
/
+-----+
|  PCC3  | LSP: PCC3->PCC4
+-----+

```

If we add a state-sync session, PCE1 will be able to do state synchronization via PCRpt messages for its LSP to PCE2 and PCE2 will do the same. All the PCEs will be aware of all LSPs even if a PCC->PCE session is down. PCEs will then be able to compute disjoint paths.

```

+-----+
|  PCC1  | LSP : PCC1->PCC2
+-----+
/
D=1 /
+-----+ PCEP +-----+
|  PCE1  | ---- |  PCE2  |
+-----+ +-----+
/ D=1
/
+-----+
|  PCC3  | LSP : PCC3->PCC4
+-----+

```

The procedures associated with this state-sync session are defined in [Section 3](#).

By just adding this state-sync session, it does not ensure that a path with LSP association based constraints can always be computed and does not prevent the computation loop, but it increases resiliency and ensures that PCEs will have the state information for all LSPs. Also, this session will allow for a PCE to update the other PCEs providing a faster synchronization mechanism than relying on PCCs only.

## 2.2. Primary/Secondary relationship between PCE

As seen in [Section 1](#), performing a path computation in a split-brain scenario (multiple PCEs responsible for computation) may provide a non-optimal LSP placement, no path, or computation loops. To provide the best efficiency, an LSP association constraint-based computation requires that a single PCE performs the path computation for all LSPs in the association group. Note that, it could be all LSPs belonging to a particular association group, or all LSPs from a particular PCC, or all LSPs in the network that need to be delegated to a single PCE based on the deployment scenarios.

This document proposes to add a priority mechanism between PCEs to elect a single computing PCE. Using this priority mechanism, PCEs can agree on the PCE that will be responsible for the computation for a particular association group, or set of LSPs. The priority could be set per association, per PCC, or for all LSPs. How this priority is set or advertised is out of the scope of this document. The rest of the text considers the association group as an example.

When a single PCE is performing the computation for a particular association group, no computation loop can happen and an optimal placement will be provided. The other PCEs will only act as state collectors and forwarders.

In the scenario described in [Section 2.1](#), PCE1 and PCE2 will decide that PCE1 will be responsible for the path computation of both LSPs. If we first configure PCC1->PCC2, PCE1 computes the shortest path at it is the only LSP in the disjoint-group that it is aware of: R1->R3->R4->R2->PCC2 (shortest path). When PCC3->PCC4 is configured, PCE2 will not perform computation even if it has delegation but forwards the delegation via PCRpt message to PCE1 through the state-sync session. PCE1 will then perform disjointness computation and will move PCC1->PCC2 onto R1->R2->PCC2 and provides an ERO to PCE2 for PCC3->PCC4: R3->R4->PCC4. The PCE2 will further update the PCC3 with the new path.

## 3. Procedures and Protocol Extensions

### 3.1. Opening a state-sync session

#### 3.1.1. Capability Advertisement

A PCE indicates its support of state-sync procedures during the PCEP Initialization phase [[RFC5440](#)]. The OPEN object in the Open message MUST contains the "Stateful PCE Capability" TLV defined in [[RFC8231](#)]. A new P (INTER-PCE-CAPABILITY) flag is introduced to indicate the support of state-sync.

This document adds a new bit in the Flags field with :

\*P (INTER-PCE-CAPABILITY - 1 bit - TBD4): If set to 1 by a PCEP Speaker, the PCEP speaker indicates that the session MUST follow the state-sync procedures as described in this document. The P bit MUST be set by both speakers: if a PCEP Speaker receives a STATEFUL-PCE-CAPABILITY TLV with P=0 while it advertised P=1 or if both set P flag to 0, the session SHOULD be set-up but the state-sync procedures MUST NOT be applied on this session.

The U flag [[RFC8231](#)] MUST be set when sending the STATEFUL-PCE-CAPABILITY TLV with the P flag set. In case the U flag is not set along with the P flag, the state sync capability is not enabled and it is considered as if the P flag is not set. The S flag MAY be set if optimized synchronization is required as per [[RFC8232](#)].

### 3.2. State synchronization

When the state sync capability has been negotiated between stateful PCEs, each PCEP speaker will behave as a PCE and as a PCC at the same time regarding the state synchronization as defined in [[RFC8231](#)]. This means that each PCEP Speaker:

\*MUST send a PCRpt message towards its neighbor with S flag set for each LSP in its LSP database learned from a PCC. (PCC role)

\*MUST send the End Of Synchronization Marker towards its neighbor when all LSPs have been reported. (PCC role)

\*MUST wait for the LSP synchronization from its neighbor to end (receiving an End Of Synchronization Marker). (PCE role)

The process of synchronization runs in parallel on each PCE (with no defined order).

The optimized state synchronization procedures MAY be used, as defined in [[RFC8232](#)].

When a PCEP Speaker sends a PCRpt on a state-sync session, it MUST add the SPEAKER-IDENTITY-TLV (defined in [[RFC8232](#)]) in the LSP Object, the value used will refer to the 'owner' PCC of the LSP. If a PCEP Speaker receives a PCRpt on a state-sync session without this TLV, it MUST discard the PCRpt message and it MUST reply with a PCErr message using error-type=6 (Mandatory Object missing) and error-value=TBD1 (SPEAKER-IDENTITY-TLV missing).

### 3.3. Incremental updates and report forwarding rules

During the life of an LSP, its state may change (path, constraints, operational state...) and a PCC will advertise a new PCRpt to the PCE for each such change.

When propagating LSP state changes from a PCE to other PCEs, it is mandatory to ensure that a PCE always uses the freshest state coming from the PCC.

When a PCE receives a new PCRpt from a PCC with the LSP-DB-VERSION, the PCE MUST forward the PCRpt to all its state-sync sessions and MUST add the appropriate SPEAKER-IDENTITY-TLV in the PCRpt. In addition, it MUST add a new ORIGINAL-LSP-DB-VERSION TLV (described below). The ORIGINAL-LSP-DB-VERSION contains the LSP-DB-VERSION coming from the PCC.

When a PCE receives a new PCRpt from a PCC without the LSP-DB-VERSION, it SHOULD NOT forward the PCRpt on any state-sync sessions and log such an event on the first occurrence.

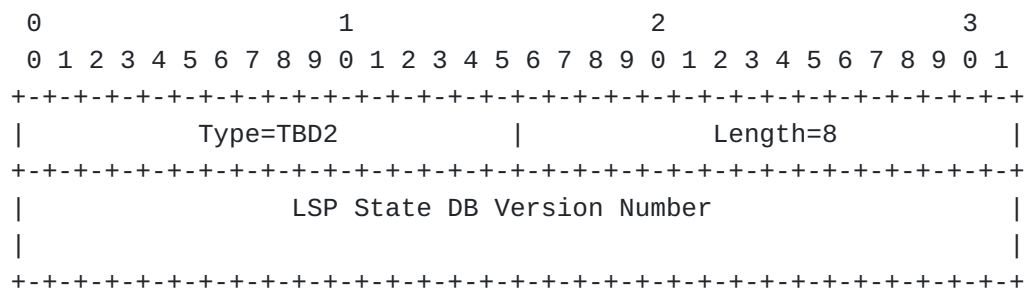
When a PCE receives a new PCRpt from a PCC with the R flag (Remove) set and an LSP-DB-VERSION TLV, the PCE MUST forward the PCRpt to all its state-sync sessions keeping the R flag set (Remove) and MUST add the appropriate SPEAKER-IDENTITY-TLV and ORIGINAL-LSP-DB-VERSION TLV in the PCRpt message.

When a PCE receives a PCRpt from a state-sync session, it MUST NOT forward the PCRpt to other state-sync sessions. This helps to prevent message loops between PCEs. As a consequence, a full mesh of PCEP sessions between PCEs are REQUIRED.

When a PCRpt is forwarded, all the original objects and values are kept. As an example, the PLSP-ID used in the forwarded PCRpt will be the same as the original one used by the PCC. Thus an implementation supporting this document MUST consider SPEAKER-IDENTITY-TLV and PLSP-ID together to uniquely identify an LSP on the state-sync session.

The ORIGINAL-LSP-DB-VERSION TLV is encoded as follows and MUST always contain the LSP-DB-VERSION received from the owner PCC of the LSP:





Using the ORIGINAL-LSP-DB-VERSION TLV allows a PCE to keep using optimized synchronization ([[RFC8232](#)]) with another PCE. In such a case, the PCE will send a PCRpt to another PCE with both ORIGINAL-LSP-DB-VERSION TLV and LSP-DB-VERSION TLV. The ORIGINAL-LSP-DB-VERSION TLV will contain the version number as allocated by the PCC while the LSP-DB-VERSION will contain the version number allocated by the local PCE.

### 3.4. Maintaining LSP states from different sources

When a PCE receives a PCRpt on a state-sync session, it stores the LSP information into the original PCC address context (as the LSP belongs to the PCC). A PCE SHOULD maintain a single state for a particular LSP and SHOULD maintain the list of sources it learned a particular state from.

A PCEP speaker may receive state information for a particular LSP from different sources: the PCC that owns the LSP (through a regular PCEP session) and some PCEs (through PCEP state-sync sessions). A PCEP speaker MUST always keep the freshest state in its LSP database, overriding the previously received information.

A PCE, receiving a PCRpt from a PCC, updates the state of the LSP in its LSP-DB with the newly received information. When receiving a PCRpt from another PCE, a PCE SHOULD update the LSP state only if the ORIGINAL-LSP-DB-VERSION present in the PCRpt is greater than the current ORIGINAL-LSP-DB-VERSION of the stored LSP state. This ensures that a PCE never tries to update its stored LSP state with an old information. Each time a PCE updates an LSP state in its LSP-DB, it SHOULD reset the source list associated with the LSP state and SHOULD add the source speaker address in the source list. When a PCE receives a PCRpt which has an ORIGINAL-LSP-DB-VERSION (if coming from a PCE) or an LSP-DB-VERSION (if coming from the PCC) equals to the current ORIGINAL-LSP-DB-VERSION of the stored LSP state, it SHOULD add the source speaker address in the source list.

When a PCE receives a PCRpt requesting an LSP deletion from a particular source, it SHOULD remove this particular source from the list of sources associated with this LSP.

When the list of sources becomes empty for a particular LSP, the LSP state MUST be removed. This means that all the sources must send a PCRpt with R=1 for an LSP to make the PCE remove the LSP state.

### **3.5. Computation priority between PCEs and sub-delegation**

A computation priority is necessary to ensure that a single PCE will perform the computation for all the LSPs in an association group: this will allow for a more optimized LSP placement and will prevent computation loops.

All PCEs in the network that are handling LSPs in a common LSP association group SHOULD be aware of each other including the computation priority of each PCE. Note that there is no need for PCC to be aware of this. The computation priority is a number and the PCE having the highest priority SHOULD be responsible for the computation. If several PCEs have the same priority value, their IP address SHOULD be used as a tie-breaker to provide a rank: the highest IP address has more priority. How PCEs are aware of the priority of each other is out of the scope of this document, but as example learning priorities could be done through PCE discovery or local configuration.

The definition of the priority could be global so the highest priority PCE will handle all path computations or more granular, so a PCE may have the highest priority for only a subset of LSPs or association-groups.

A PCEP Speaker receiving a PCRpt from a PCC with the D flag set that does not have the highest computation priority, SHOULD forward the PCRpt on all state-sync sessions (as per [Section 3.3](#)) and SHOULD set D flag on the state-sync session towards the highest priority PCE, D flag will be unset to all other state-sync sessions. This behavior is similar to the delegation behavior handled at the PCC side and is called a sub-delegation (the PCE sub-delegates the control of the LSP to another PCE). When a PCEP Speaker sub-delegates an LSP to another PCE, it loose control of the LSP and cannot update it anymore by its own decision. When a PCE receives a PCRpt with D flag set on a state-sync session, as a regular PCE, it is granted control over the LSP.

If the highest priority PCE is failing or if the state-sync session between the local PCE and the highest priority PCE failed, the local PCE MAY decide to delegate the LSP to the next highest priority PCE or to take back control of the LSP. It is a local policy decision.

When a PCE has the delegation for an LSP and needs to update this LSP, it MUST send a PCUpd message to all state-sync sessions and to the PCC session on which it received the delegation. The D-Flag

would be unset in the PCUpd for state-sync sessions whereas the D-Flag would be set for the PCC. In the case of sub-delegation, the computing PCE will send the PCUpd only to all state-sync sessions (as it has no direct delegation from a PCC). The D-Flag would be set for the state-sync session to the PCE that sub-delegated this LSP and the D-Flag would be unset for other state-sync sessions.

The PCUpd sent over a state-sync session MUST contain the SPEAKER-IDENTITY-TLV in the LSP Object (the value used must identify the target PCC). The PLSP-ID used is the original PLSP-ID generated by the PCC and learned from the forwarded PCRpt. If a PCE receives a PCUpd on a state-sync session without the SPEAKER-IDENTITY-TLV, it MUST discard the PCUpd and MUST reply with a PCErr message using error-type=6 (Mandatory Object missing) and error-value=TBD1 (SPEAKER-IDENTITY-TLV missing).

When a PCE receives a valid PCUpd on a state-sync session, it SHOULD forward the PCUpd to the appropriate PCC (identified based on the SPEAKER-IDENTITY-TLV value) that delegated the LSP originally and SHOULD remove the SPEAKER-IDENTITY-TLV from the LSP Object. The acknowledgment of the PCUpd is done through a cascaded mechanism, and the PCC is the only responsible for triggering the acknowledgment: when the PCC receives the PCUpd from the local PCE, it acknowledges it with a PCRpt as per [\[RFC8231\]](#). When receiving the new PCRpt from the PCC, the local PCE uses the defined forwarding rules on the state-sync session so the acknowledgment is relayed to the computing PCE.

A PCE SHOULD NOT compute a path using an association-group constraint if it has delegation for only a subset of LSPs in the group. In this case, an implementation MAY use a local policy on PCE to decide if PCE does not compute path at all for this set of LSP or if it can compute a path by relaxing the association-group constraint.

### **3.6. Passive stateful procedures**

In the passive stateful PCE architecture, the PCC is responsible for triggering a path computation request using a PCReq message to its PCE. Similarly to PCRpt Message, which remains unchanged for passive mode, if a PCE receives a PCReq for an LSP and if this PCE finds that it does not have the highest computation priority of this LSP, or groups..., it MUST forward the PCReq message to the highest priority PCE over the state-sync session. When the highest priority PCE receives the PCReq, it computes the path and generates a PCRep message towards the PCE that made the request. This PCE will then forward the PCRep to the requesting PCC. The handling of LSP object and the SPEAKER-IDENTITY-TLV in PCReq and PCRep is similar to PCRpt/PCUpd messages.

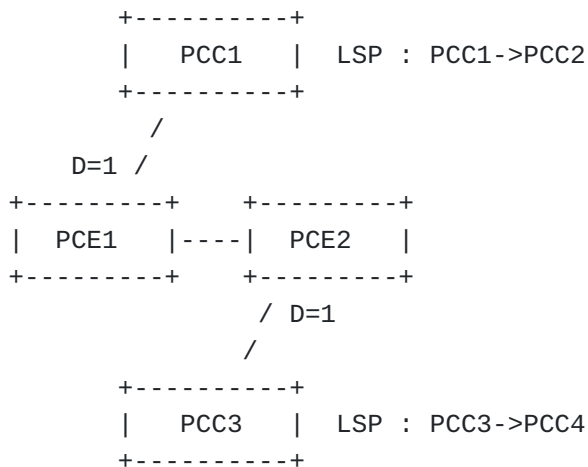
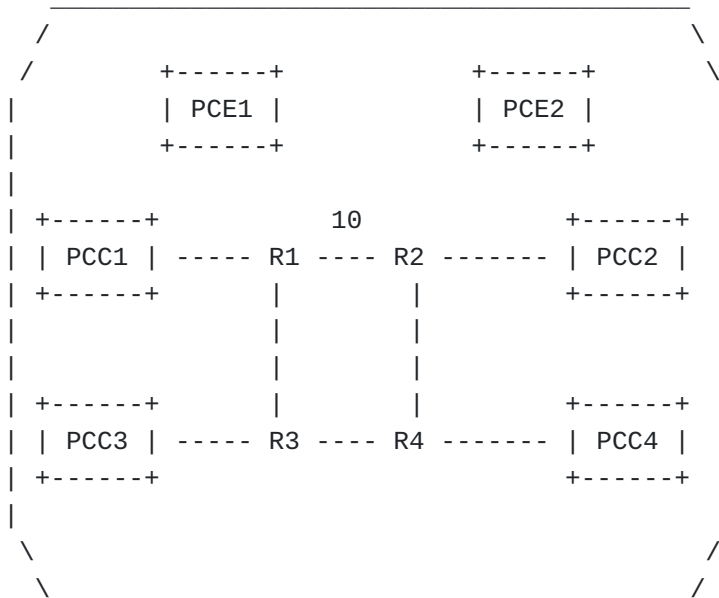
### 3.7. PCE initiation procedures

It is possible that a PCE does not have a PCEP session with the headend to initiate a LSP as per [[RFC8281](#)]. A PCE could send the PCInitiate message on the state-sync sessions to other PCE to request it to create a PCE-Initiated LSP on its behalf. If the PCE is able to initiate the LSP it would report it on the state-sync session via PCRpt message. If the PCE does not have a session to the headend, it MUST send a PCErr message with Error-type=24 (PCE instantiation error) and Error-value=TBD5 (No PCEP session with the headend). PCE could try to initiate via another state-sync PCE if available.

### 4. Examples

The examples in this section are for illustrative purpose to show how the behavior of the state sync inter-PCE sessions.

#### 4.1. Example 1



PCE1 computation priority 100

PCE2 computation priority 200

Consider the PCEP sessions as shown above, where computation priority is global for all the LSPs and link disjoint between LSPs PCC1->PCC2 and PCC3->PCC4 is required.

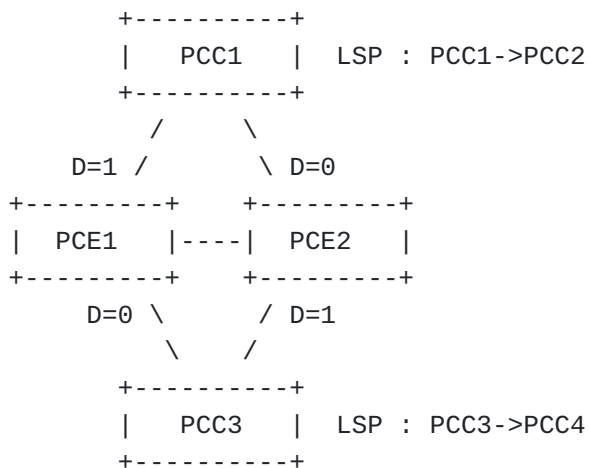
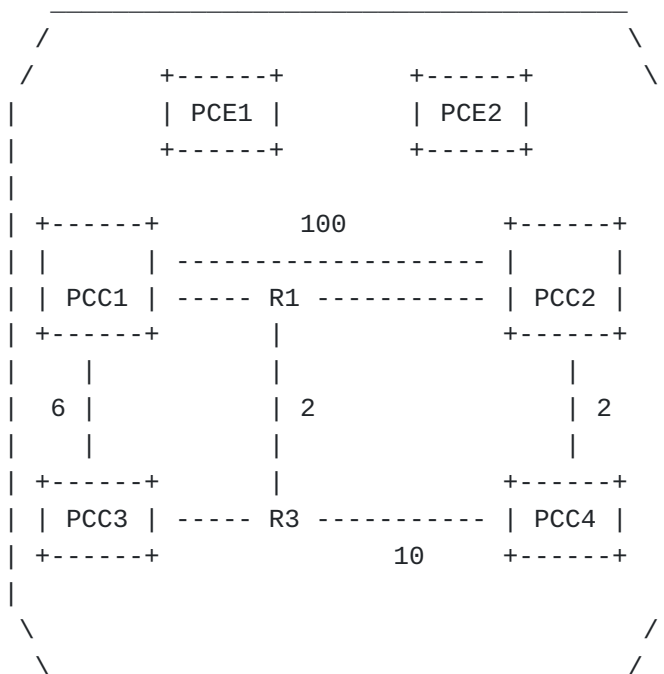
Consider the PCC1->PCC2 is configured first and PCC1 delegates the LSP to PCE1, but as PCE1 does not have the highest computation priority, it sub-delegates the LSP to PCE2 by sending a PCRpt with D=1 and including the SPEAKER-IDENTITY-TLV over the state-sync session. PCE2 receives the PCRpt and as it has delegation for this LSP, it computes the shortest path: R1->R3->R4->R2->PCC2. It then sends a PCUpd to PCE1 (including the SPEAKER-IDENTITY-TLV) with the

computed ERO. PCE1 forwards the PCUpd to PCC1 (removing the SPEAKER-IDENTITY-TLV). PCC1 acknowledges the PCUpd by a PCRpt to PCE1. PCE1 forwards the PCRpt to PCE2.

When PCC3->PCC4 is configured, PCC3 delegates the LSP to PCE2, PCE2 can compute a disjoint path as it has knowledge of both LSPs and has delegation also for both. The only solution found is to move PCC1->PCC2 LSP on another path, PCE2 can move PCC1->PCC2 as it has sub-delegation for it. It creates a new PCUpd with a new ERO: R1->R2-PCC2 towards PCE1 which forwards to PCC1. PCE2 sends a PCUpd to PCC3 with the path: R3->R4->PCC4.

In this set-up, PCEs are able to find a disjoint path while without state-sync and computation priority they could not.

#### 4.2. Example 2

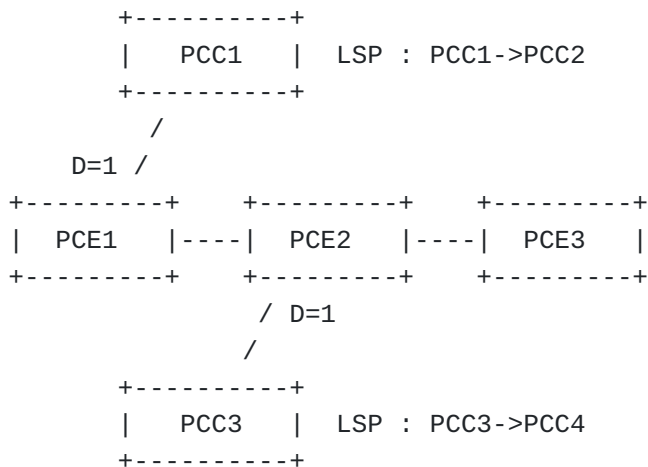
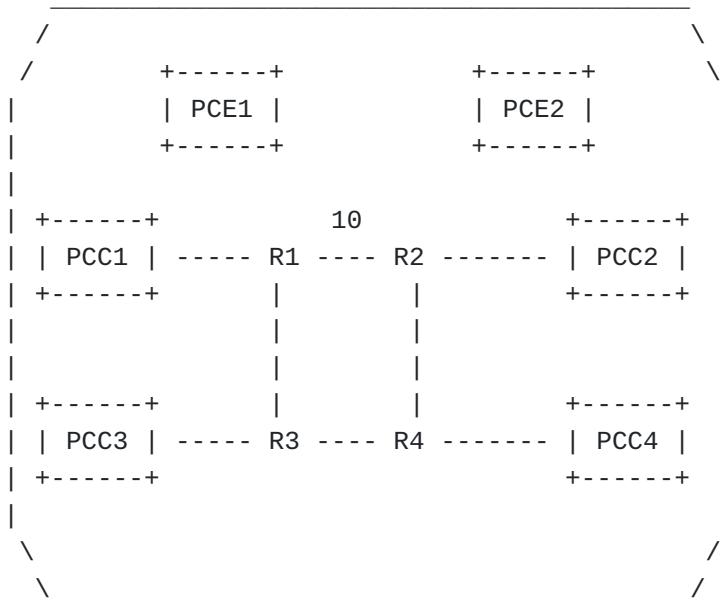


```
PCE1 computation priority 200
```

```
PCE2 computation priority 100
```

In this example, suppose both LSPs are configured almost at the same time. PCE1 sub-delegates PCC1->PCC2 to PCE2 while PCE2 keeps delegation for PCC3->PCC4, PCE2 computes a path for PCC1->PCC2 and PCC3->PCC4 and can achieve disjointness computation easily. No computation loop happens in this case.

### 4.3. Example 3



PCE1 computation priority 100  
PCE2 computation priority 200  
PCE3 computation priority 300

With the PCEP sessions as shown above, consider the need to have link disjoint LSPs PCC1->PCC2 and PCC3->PCC4.

Suppose PCC1->PCC2 is configured first, PCC1 delegates the LSP to PCE1, but as PCE1 does not have the highest computation priority, it will sub-delegate the LSP to PCE2 (as it not aware of PCE3 and has no way to reach it). PCE2 cannot compute a path for PCC1->PCC2 as it does not have the highest priority and is not allowed to sub-delegate the LSP again towards PCE3 as per [Section 3](#).

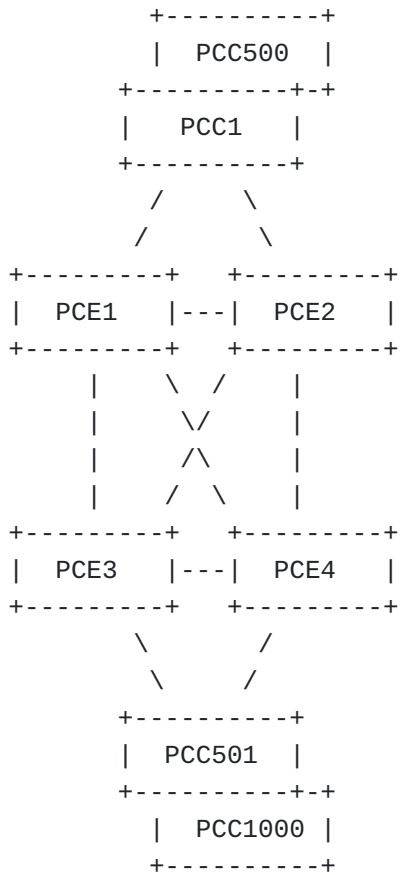


When PCC3->PCC4 is configured, PCC3 delegates the LSP to PCE2 that performs sub-delegation to PCE3. As PCE3 will have knowledge of only one LSP in the group, it cannot compute disjointness and can decide to fall-back to a less constrained computation to provide a path for PCC3->PCC4. In this case, it will send a PCUpd to PCE2 that will be forwarded to PCC3.

Disjointness cannot be achieved in this scenario because of lack of state-sync session between PCE1 and PCE3, but no computation loop happens. Thus it is advised for all PCEs that support state-sync to have a full mesh sessions between each other.

## **5. Using Primary/Secondary Computation and State-sync Sessions to increase Scaling**

The Primary/Secondary computation and state-sync sessions architecture can be used to increase the scaling of the PCE architecture. If the number of PCCs is really high, it may be too resource consuming for a single PCE to maintain all the PCEP sessions while at the same time performing all path computations. Using primary/secondary computation and state-sync sessions may allow to create groups of PCEs that manage a subset of the PCCs and perform some or no path computations. Decoupling PCEP session maintenance and computation will allow increasing scaling of the PCE architecture.



In the figure above, two groups of PCEs are created: PCE1/2 maintain PCEP sessions with PCC1 up to PCC500, while PCE3/4 maintain PCEP sessions with PCC501 up to PCC1000. A granular primary/secondary policy is set-up as follows to load-share computation between PCEs:

\*PCE1 has priority 200 for association ID 1 up to 300, association source 0.0.0.0. All other PCEs have a decreasing priority for those associations.

\*PCE3 has priority 200 for association ID 301 up to 500, association source 0.0.0.0. All other PCEs have a decreasing priority for those associations.

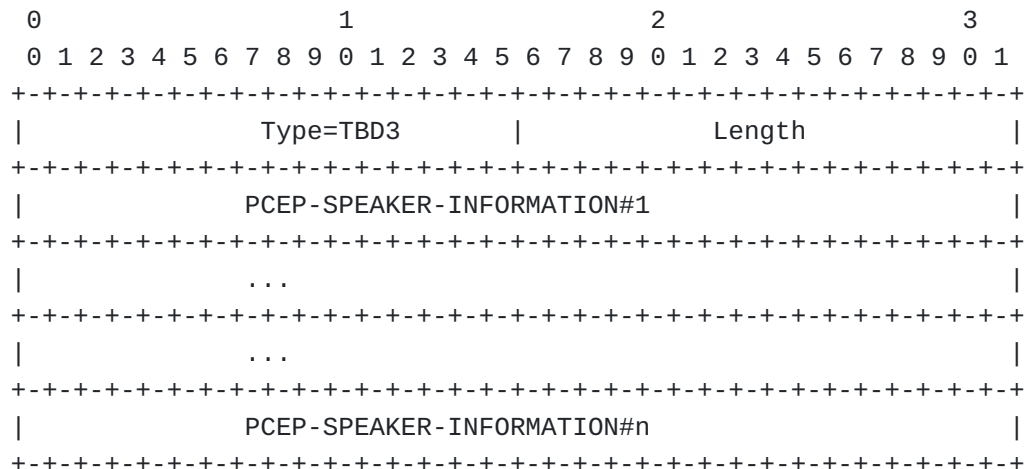
If some PCCs delegate LSPs with association ID 1 up to 300 and association source 0.0.0.0, the receiving PCE (if not PCE1) will sub-delegate the LSPs to PCE1. PCE1 becomes responsible for the computation of these LSP associations while PCE3 is responsible for the computation of another set of associations.

The procedures described in this document could help greatly in load-sharing between a group of stateful PCEs.

## 6. PCEP-PATH-VECTOR TLV

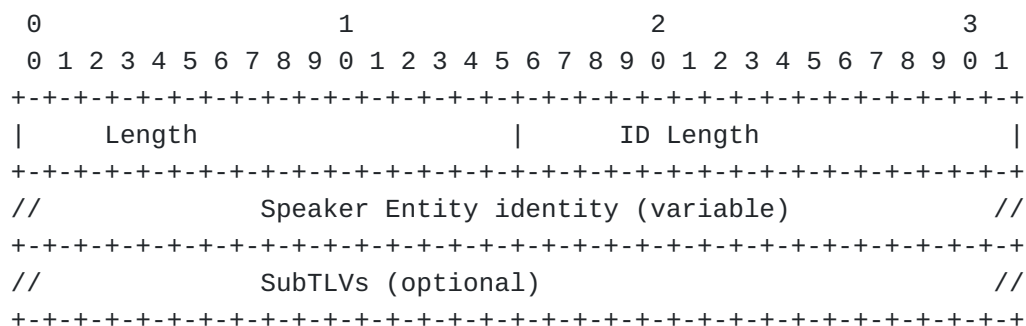
This document allows PCEP messages to be propagated among PCEP speaker. It may be useful to track information about the propagation of the messages. One of the use cases is a message loop detection mechanism, but other use cases like hop by hop information recording may also be implemented.

This document introduces the PCEP-PATH-VECTOR TLV (type TBD3) with the following format:



The TLV format and padding rules are as per [\[RFC5440\]](#).

The PCEP-SPEAKER-INFORMATION field has the following format:



\*Length: defines the total length of the PCEP-SPEAKER-INFORMATION field.

\*ID Length: defines the length of the Speaker identity actual field (non-padded).

\*Speaker Entity identity: same possible values as the SPEAKER-IDENTIFIER-TLV. Padded with trailing zeros to a 4-byte boundary.

\*The PCEP-SPEAKER-INFORMATION may also carry some optional subTLVs so each PCEP speaker can add local information that could be recorded. This document does not define any sub-TLV.

The PCEP-PATH-VECTOR TLV MAY be carried in the LSP Object. Its usage is purely optional.

The list of speakers within the PCEP-PATH-VECTOR TLV MUST be ordered. When sending a PCEP message (PCRpt, PCUpd, or PCInitiate), a PCEP Speaker MAY add the PCEP-PATH-VECTOR TLV with a PCEP-SPEAKER-INFORMATION containing its own information. If the PCEP message sent is the result of a previously received PCEP message, and if the PCEP-PATH-VECTOR TLV was already present in the initial message, the PCEP speaker MAY append a new PCEP-SPEAKER-INFORMATION containing its own information.

## 7. Security Considerations

The security considerations described in [[RFC8231](#)] and [[RFC5440](#)] apply to the extensions described in this document as well. Additional considerations related to state synchronization and sub-delegation between stateful PCEs are introduced, as it could be spoofed and could be used as an attack vector. An attacker could attempt to create too much state in an attempt to load the PCEP peer. The PCEP peer responds with a PCErr message as described in [[RFC8231](#)]. An attacker could impact LSP operations by creating bogus state. Further, state synchronization between stateful PCEs could provide an adversary with the opportunity to eavesdrop on the network. Thus, securing the PCEP session using Transport Layer Security (TLS) [[RFC8253](#)], as per the recommendations and best current practices in [[RFC7525](#)], is RECOMMENDED.

## 8. Acknowledgements

Thanks to [[I-D.knodel-terminology](#)] urging for better use of terms.

## 9. IANA Considerations

This document requests IANA actions to allocate code points for the protocol elements defined in this document.

### 9.1. PCEP-Error Object

IANA is requested to allocate a new Error Value for the Error Type 9.

Error-Type	Meaning	Reference
6	Mandatory Object Missing	[ <a href="#">RFC5440</a> ]

Error-Type	Meaning	Reference
	Error-value=TBD1: SPEAKER-IDENTITY-TLV missing	This document
24	LSP instantiation error	[RFC8281]
	Error-value=TBD5: No PCEP session with the headend	This document

Table 1

## 9.2. PCEP TLV Type Indicators

IANA is requested to allocate new TLV Type Indicator values within the "PCEP TLV Type Indicators" sub-registry of the PCEP Numbers registry, as follows:

Value	Meaning	Reference
TBD2	ORIGINAL-LSP-DB-VERSION TLV	This document
TBD3	PCEP-PATH-VECTOR TLV	This document

Table 2

## 9.3. STATEFUL-PCE-CAPABILITY TLV

IANA is requested to allocate a new bit value in the STATEFUL-PCE-CAPABILITY TLV Flag Field sub-registry.

Bit	Description	Reference
TBD4	INTER-PCE-CAPABILITY	This document

Table 3

## 10. References

### 10.1. Normative References

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