Fast Failover in Protocol Independent Multicast - Sparse Mode (PIM-SM) Using Bidirectional Forwarding Detection (BFD) for Multipoint Networks

Abstract

This document specifies how Bidirectional Forwarding Detection for multipoint networks can provide sub-second failover for routers that participate in Protocol Independent Multicast - Sparse Mode (PIM-SM). An extension to the PIM Hello message used to bootstrap a point-to-multipoint BFD session is also defined in this document.

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Table of Contents

1. Introduction

Faster convergence in the control plane minimizes the periods of
traffic blackholing, transient routing loops, and other situations
that may negatively affect service data flow. Faster convergence in
the control plane is beneficial to unicast and multicast routing
protocols.

[RFC7761] is the current specification of the Protocol Independent
Multicast - Sparse Mode (PIM-SM) for IPv4 and IPv6 networks. A
conforming implementation of PIM-SM elects a Designated Router (DR)
on each PIM-SM interface. When a group of PIM-SM nodes is connected
to a shared media segment, e.g., Ethernet, the node elected as DR
acts on behalf of directly connected hosts in the context of the
PIM-SM protocol. Failure of the DR impacts the quality of the
multicast services it provides to directly connected hosts because
the default failure detection interval for PIM-SM routers is 105
seconds.

Bidirectional Forwarding Detection (BFD) [RFC5880] had been
originally defined to detect a failure of a point-to-point (p2p)
path, single-hop [RFC5881] or multihop [RFC5883]. In some PIM-SM
deployments, a p2p BFD can be used to detect a failure and enable
faster failover. [RFC8562] extends the BFD base specification
[RFC5880] for multipoint and multicast networks, and it precisely
characterizes deployment scenarios for PIM-SM over a LAN segment.
Among specific characteristics of p2mp BFD that particularly benefit
PIM-SM over a LAN segment is a faster transition to the Up state of

the p2mp BFD session due to avoidance of the three-way handshake required in p2p BFD [RFC5880]. Also, because the router that transmits BFD Control messages uses the BFD Demand mode [RFC5880], it maintains less BFD state than the Asynchronous mode. Point-to-multipoint (p2mp) BFD can enable faster detection of PIM-SM router failure and thus minimize multicast service disruption. The monitored PIM-SM router acts as the head and other routers as tails of a p2mp BFD session. This document defines the monitoring of a PIM-SM router using p2mp BFD. The document also defines the extension to PIM-SM [RFC7761] to bootstrap a PIM-SM router to join in p2mp BFD session over shared media segment.

1.1. Conventions used in this document

1.1.1. Terminology

This document uses terminology defined in [RFC5880], [RFC8562], and [RFC7761]. Familiarity with these specifications and the terminology used is expected.

1.1.2. Requirements Language

The key words "MUST", "MUST NOT", "REQUIRED", "SHALL", "SHALL NOT", "SHOULD", "SHOULD NOT", "RECOMMENDED", "NOT RECOMMENDED", "MAY", and "OPTIONAL" in this document are to be interpreted as described in BCP 14 [RFC2119] [RFC8174] when, and only when, they appear in all capitals, as shown here.

2. BFD Discriminator PIM Hello Option

Figure 1 displays the new optional BFD Discriminator PIM Hello option to bootstrap a tail of the p2mp BFD session.

```
 0                   1                   2                   3
 0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1
+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+
|           OptionType           |         OptionLength          |
+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+
|                       HeadDiscriminator                       |
+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+
```
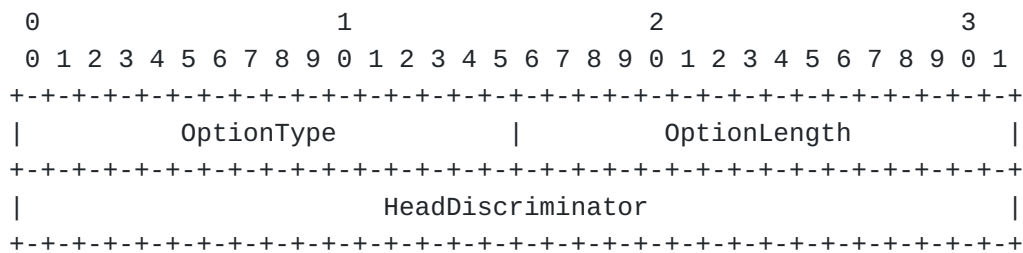
              Figure 1: BFD Discriminator PIM Hello Option

where new fields are interpreted as:

   OptionType: TBA.

   OptionLength: MUST be set to 4.

HeadDiscriminator: equals the value of My Discriminator
   ([RFC5880]) allocated by the head.

If the value of the OptionLength field is not equal to 4, the BFD
Discriminator PIM Hello option is considered malformed, and the
receiver MUST stop processing PIM Hello options. If the value of the
HeadDiscriminator field equals zero, then the BFD Discriminator PIM
Hello option MUST be considered invalid, and the receiver MUST
ignore it. The receiver SHOULD log a notification regarding the
malformed or invalid BFD Discriminator Hello option under the
control of a throttling logging mechanism.

2.1. Using P2MP BFD in PIM Router Monitoring

If the head is no longer serving the function that prompted it to be
monitored, then it MUST cease including the BFD Discriminator PIM
Hello option in its PIM-Hello message, and it SHOULD shut down the
BFD session following the procedures described in Section 5.9
[RFC8562].

The head MUST create a BFD session of type MultipointHead [RFC8562].
Note that any PIM-SM router, regardless of its role, MAY become a
head of a p2mp BFD session. To control the volume of BFD control
traffic on a shared media segment, an operator should carefully
select PIM-SM routers configured as a head of a p2mp BFD session.
The head MUST include the BFD Discriminator option in its Hello
messages, and it MUST include a 4-byte HeadDiscriminator with a
value other than zero.

If a PIM-SM router is configured to monitor the head by using p2mp
BFD, referred to through this document as 'tail', receives a PIM-
Hello packet with the BFD Discriminator PIM Hello option, the tail
MAY create a p2mp BFD session of type MultipointTail, as defined in
[RFC8562].

The node that includes the BFD Discriminator PIM Hello option
transmits BFD Control packets periodically. For the tail to
correctly demultiplex BFD [RFC8562], the source address, and My
Discriminator values of the BFD packets MUST be the same as those of
the HeadDiscriminator in the PIM Hello message. If that is not the
case, the tail BFD node would not be able to monitor the state of
the PIM-SM node, that is, the head of the p2mp BFD session, though
the regular PIM-SM mechanisms remain fully operational.

If the tail detects a MultipointHead failure [RFC8562], it MUST
delete the corresponding neighbor state and follow procedures
defined in [RFC7761].

If the head ceases to include the BFD Discriminator PIM Hello option
in its PIM-Hello message, tails SHOULD close the corresponding

MultipointTail BFD session without affecting the PIM state in any way. Thus the tail stops using BFD to monitor the head and reverts to the procedures defined in [RFC7761].

2.2. P2MP BFD in PIM DR Load Balancing

[RFC8775] specifies the PIM Designated Router Load Balancing (DRLB) functionality. Any PIM router that advertises the DRLB-Cap Hello Option can become the head of a p2mp BFD session, as specified in Section 2.1. The head router administratively sets the bfd.SessionState to Up in the MultipointHead session [RFC8562] only if it is a Group Designated Router (GDR) Candidate, as specified in Sections 5.5 and 5.6 of [RFC8775]. If the router is no longer the GDR, then it MUST shut down following the procedures described in Section 5.9 [RFC8562]. For each GDR Candidate that includes BFD Discriminator option in its PIM Hello, the PIM DR creates a MultipointTail session [RFC8562]. PIM DR demultiplexes BFD sessions based on the value of the My Discriminator field and the source IP address. If PIM DR detects a failure of one of the sessions, it MUST remove that router from the GDR Candidate list and immediately transmit a new DRLB-List option.

2.3. Multipoint BFD Encapsulation

The MultipointHead of a p2mp BFD session when transmitting BFD Control packets:

    MUST set TTL or Hop Limit value to 255 (Section 5 [RFC5881]);

    MUST use the group address ALL-PIM-ROUTERS ('224.0.0.13' for IPv4 and 'ff02::d' for IPv6) as destination IP address

3. IANA Considerations

IANA is requested to allocate a new OptionType value from PIM-Hello Options registry according to:

Value	Length	Name	Reference
TBA	4	BFD Discriminator Option	This document

Table 1: BFD Discriminator option type

4. Security Considerations

This document defines a way to accelerate detecting a failure that affects PIM functionality by using BFD. The operation of either protocol is not changed.

The security considerations discussed in [RFC7761], [RFC5880], [RFC8562], and [RFC8775] apply to this document.

5. Acknowledgments

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