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L-E.

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**RObust Header Compression (ROHC):  
Terminology and Examples for MIB's and Channel Mappings**  
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Abstract

[RFC 3095](#) defines a Proposed Standard framework with profiles for RObust Header Compression (ROHC). Various concepts are introduced within the standard, which might be difficult to understand, and especially how these relate to the surrounding environments where header compression may be used. This document aims at clarifying these aspects of ROHC, discussing terms such as ROHC instances, ROHC channels, ROHC feedback, ROHC contexts, and how these terms relate to other terms like network elements and IP interfaces, commonly used when for example addressing MIB issues.



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## [1.](#) Introduction

In [RFC 3095](#), the RObust Header Compression (ROHC) standard framework is defined along with 4 compression profiles [[RFC-3095](#)]. Various concepts are introduced within the standard, which might not all be very extensively defined and described, and that can easily be an obstacle when trying to understand the standard. This can especially be the case when one considers how the various parts of ROHC relate to the surrounding environments where header compression may be used.

The purpose of this document is to clarify these aspects of ROHC through examples and additional terminology, discussing terms such as

ROHC instances, ROHC channels, ROHC feedback, ROHC contexts. This especially means to clarify how these terms relate to other terms, such as network elements and IP interfaces, which are commonly used when for example addressing MIB issues. One explicit goal with this document is to support and simplify the ROHC MIB development work.

The main part of this document, [section 3](#) to 8, focuses on clarifying

the conceptual aspects, entity relationships, and terminology of

ROHC

[[RFC-3095](#)]. After that, [section 9](#) explains some implementation implications that arise from these conceptual aspects.

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## 2. Terminology

### ROHC instance

A logical entity that performs header compression or decompression according to one or several ROHC profiles can be referred to as a ROHC instance. A ROHC instance is either a ROHC compressor instance or a ROHC decompressor instance. See further [section 4.](#)

### ROHC compressor instance

A ROHC compressor instance is a logical entity that performs header compression according to one or several ROHC profiles. There is a one-to-one relation between a ROHC compressor instance and a ROHC channel, where the ROHC compressor sits on the input end of the ROHC channel. See further [section 4.1.](#)

### ROHC decompressor instance

A ROHC decompressor instance is a logical entity that performs header decompression according to one or several ROHC profiles. There is a one-to-one relation between a ROHC decompressor instance and a ROHC channel, where the ROHC decompressor sits on the output end of the ROHC channel. See further [section 4.2.](#)

### Corresponding decompressor

When talking about a compressors corresponding decompressor, this refers to the peer decompressor located at other end of the ROHC channel the compressor sends compressed header packets to, i.e. the decompressor that decompresses the headers compressed by the compressor.

### Corresponding compressor

When talking about a decompressors corresponding compressor, this refers to the peer compressor located at other end of the ROHC channel the decompressor receives compressed header packets from, i.e. the compressor that compresses the headers the decompressor decompresses.

### Bi-directional compression

If there are means to send feedback information from a decompressor to its corresponding compressor, the compression performance can be improved. This way of operating, utilizing the feedback possibility for improved compression performance, is referred to as bi-directional compression.



### Unidirectional compression

If there are no means to send feedback information from a decompressor to its corresponding compressor, the compression performance might not be as good as if feedback can be utilized. This way of operating, without making use of feedback for improved compression performance, is referred to as unidirectional compression.

### ROHC channel

When a ROHC compressor has transformed original packets into ROHC packets with compressed headers, these ROHC packets are sent to the corresponding decompressor through a logical point-to-point connection dedicated to that traffic. Such a logical channel, which only has to carry data in this single direction from compressor to decompressor, is referred to as a ROHC channel. See further [section 5](#).

### ROHC feedback channel

To allow for bi-directional compression operation, a logical point-to-point connection must be provided for feedback data from the decompressor to its corresponding compressor. Such a logical channel, which only has to carry data in the single direction from decompressor to compressor, is referred to as a ROHC feedback channel. See further [section 6](#).

### Co-located compressor/decompressor

A minimal ROHC instance is only a compressor or a decompressor, communicating with a corresponding decompressor or compressor on the other end of a ROHC channel, thus handling packet streams sent in one direction over the link. However, in many cases the link will carry packet streams in both directions, and it would then be desirable to also perform header compression in both directions. That would require both a ROHC compressor and a ROHC decompressor at each end of the link, which is what is referred to as a co-located compressor/decompressor pair.

### Associated compressor/decompressor

If there is a co-located ROHC compressor/decompressor pair at each end of a link, feedback messages can be transmitted from a ROHC decompressor to its corresponding compressor by creating a virtual ROHC feedback channel among the compressed header packets sent from the co-located ROHC compressor to the ROHC decompressor co-located with the compressor at the other end. When a co-

located

ROHC compressors/decompressor pair is connected for this purpose,  
they are said to be associated to each other.

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### Interspersed feedback

Feedback from a ROHC decompressor to a ROHC compressor can either be sent on a separate ROHC feedback channel dedicated to feedback packets, or sent among compressed header packets going in the opposite direction from a co-located (associated) compressor to a similarly co-located decompressor at the other end of the channel.

If feedback packets are transmitted in the latter way and sent as stand-alone packets, this is referred to as interspersed feedback.

See further [section 6.2](#) for an example.

### Piggybacked feedback

Feedback from a ROHC decompressor to a ROHC compressor can either be sent on a separate ROHC feedback channel dedicated to feedback packets, or sent among compressed header packets going in the opposite direction from a co-located (associated) compressor to a similarly co-located decompressor at the other end of the channel.

If feedback packets are transmitted in the latter way and sent encapsulated within compressed header packets going in the other direction, this is referred to as piggybacked feedback.

See further [section 6.2](#) for an example.

### Dedicated feedback channel

A dedicated feedback channel is a logical layer two channel from a ROHC decompressor to a ROHC compressor, used only to transmit feedback packets. See further [section 6.1](#) and 6.3 for examples.



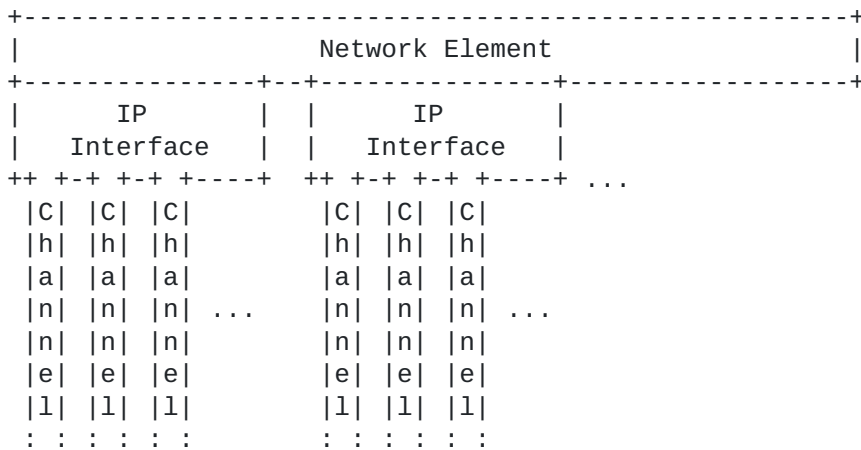


communication by different means. However, all link technologies provide the common capability to send and/or receive data to/from the

IP interface. A generic way of visualizing the common ability to communicate is to envision it as one or several logical communication

channels provided by the link, where each channel can be either bi-directional or unidirectional. Such logical point-to-point connections will throughout the rest of this document be referred to as "channels", either bi-directional or unidirectional. Note that this definition of "channels" is less restrictive than the definition of "ROHC channels", as given in [section 5](#).

Extending the above network element hierarchy with the concept of channels would then lead to the following:



Whether there is more than one channel, and whether the channel(s) is/are bi-directional or unidirectional (or a mix of both) is link technology dependent, as well as the way channels are logically created.

The following [subsection 3.3-3.6](#) give a number of different link examples, and relate these to the general descriptions above. Further, each section discusses how header compression might be applied in that particular case. The core questions for header compression are:

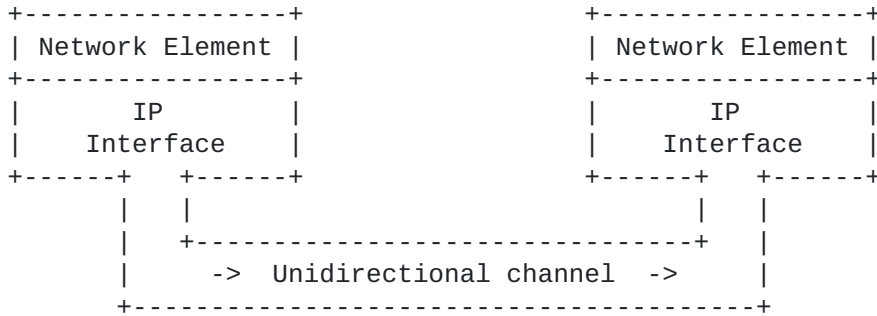
- Are channels bi- or unidirectional?
- Is the link point-to-point? If not, a lower layer addressing scheme is needed to create logical point-to-point channels.

Note that these subsections talk about header compression in general, while later sections will address the case of ROHC in more detail. Further, one should remember that in the later sections, the general channel definition is slightly enhanced for header compression by the definition of ROHC channels ([section 5](#)) and ROHC feedback channels ([section 6](#)), while here the basic channel concept from above is used.



### 3.3. A Unidirectional Point-to-Point Link Example

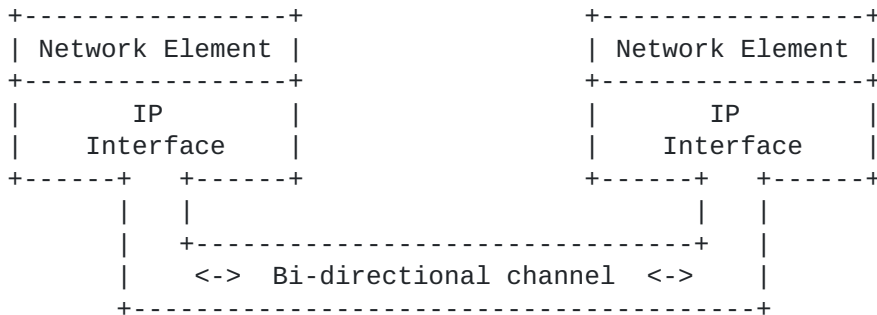
The simplest possible link example one can derive from the general overview above, is the case with one single unidirectional channel between two communicating network elements.



A typical example of a point-to-point link with one unidirectional channel like this is a satellite link. Since there is no return path present, only unidirectional header compression can be applied here.

### 3.4. A Bi-directional Point-to-Point Link Example

Taking the above example one step further, the natural extension would be an example with one single bi-directional channel between two communicating network elements. In this example, there is still only two endpoints and one single channel, but the channel is simply enhanced to allow bi-directional communication.



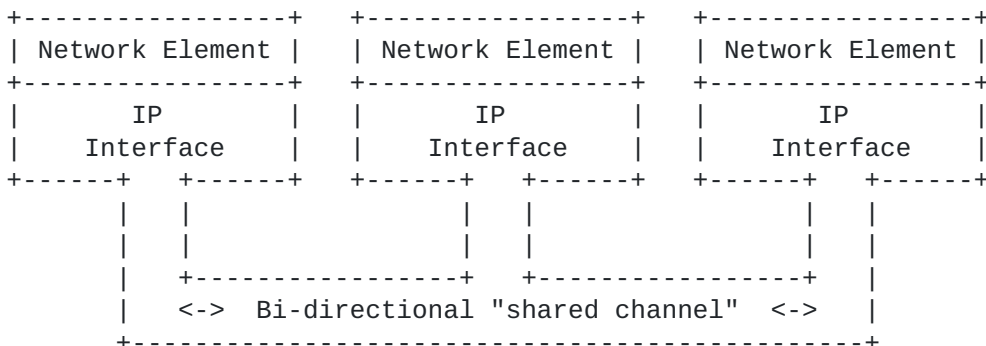
A typical example of a point-to-point link with such a bi-directional channel is a PPP modem connection over a regular telephone line. Header compression can easily be applied here as well, as usually done over e.g. PPP, and the compression scheme can make use of the return path to improve compression performance.





**3.5. A Bi-directional Multipoint Link Example**

Leaving the simple point-to-point link examples, this section addresses the case of a bi-directional link between more than two communicating network elements. To simplify the example, the case with three endpoints is used.



A typical example of a multipoint link with a bi-directional "shared channel" like this is an Ethernet. Since the channel is shared, applying header compression would require a lower layer addressing scheme, to provide logical point-to-point channels, according to the definition of "channels".

As a side point, it should be noted that a case of unidirectional multipoint links is basically the same as a number of unidirectional point-to-point links. In such a case, each receiver only sees one single sender, and the senders behavior is independent of the number of receivers and unaffected by their behavior.

**3.6. A Multi-Channel Point-to-Point Link Example**

This final example addresses a scenario which is expected to be typical in many environments where ROHC will be applied. The key point with the example is the multi-channel property, which is common in for example cellular environments. Data through the same IP interface might here be transmitted on different channels, depending on characteristics. In the following example, there are three channels present, one bi-directional, and one unidirectional in each direction, but the channel configuration could of course be arbitrary.





rotated

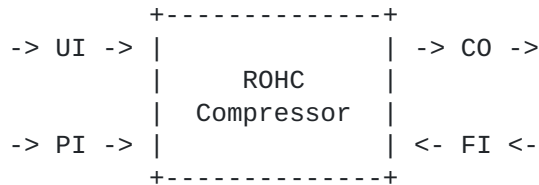
90 degrees to simplify drawing, i.e. they do not show a "stack view".

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#### 4.1. ROHC Compressors

A ROHC compressor instance supports header compression according to one or several ROHC profiles. Apart from potential configuration or control interfaces, a compressor instance receives and sends data through 3 inputs and 1 output, as illustrated by the figure below:



Uncompressed Input (UI): Uncompressed packets are delivered from higher layers to the compressor through the UI.

Compressed Output (CO): Compressed packets are sent from the compressor through the CO, which is always connected to the input end of a ROHC channel (see [section 5](#)).

Feedback Input (FI): Feedback from the corresponding decompressor is received by the compressor through the FI, which (if present) is connected to the output end of a ROHC feedback channel of some kind (see [section 6](#)). When there are no means to transmit feedback from decompressor to compressor, FI is not used and bi-directional compression will not be possible.

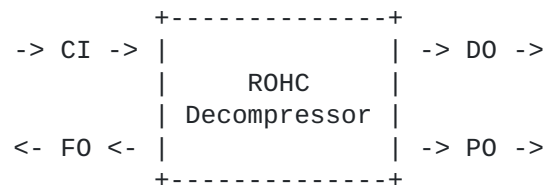
Piggyback Input (PI): If the compressor is associated with a co-located decompressor, for which the compressor delivers feedback to the other end of the channel, feedback data for piggybacking is delivered to the compressor through the PI. If this input is used, it is connected to the FO of the co-located decompressor (see [section](#)

[4.2](#)).



## 4.2. ROHC Decompressors

A ROHC decompressor instance supports header decompression according to one or several ROHC profiles. Apart from potential configuration or control interfaces, a decompressor instance receives and sends data through 1 input and 3 outputs, as illustrated by the figure below:



**Compressed Input (CI):** Compressed packets are received by the decompressor through the CI, which is always connected to the output end of a ROHC channel (see [section 5](#)).

**Decompressed Output (DO):** Decompressed packets are delivered from the decompressor to higher layers through the DO.

**Feedback Output (FO):** Feedback to the corresponding compressor is sent by the compressor through the FO, which (if present) is connected to the input end of a ROHC feedback channel of some kind (see [section 6](#)). When there are no means to transmit feedback from decompressor to compressor, FO is not used and bi-directional compression will not be possible.

**Piggyback Output (PO):** If the decompressor is associated with a co-located compressor, to which the decompressor delivers feedback it receives piggybacked from the other end of the channel, the received feedback data is delivered from the decompressor through the PO. If this output is used, it is connected to the FI of the co-located compressor (see [section 4.1](#)).

## 5. ROHC Channels

In [section 3](#), a general concept of channels was introduced. According to that definition, a channel is basically a logical point-to-point connection between IP interfaces at two communicating network elements. By that definition, a channel represents the kind of

logical connection needed to make header compression generally

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applicable, and then the channel properties control whether compression can operate in a unidirectional or bi-directional manner.

The channel concept thus facilitates general header compression discussions, but since it groups unidirectional and bi-directional connections together it does not provide the means for describing details of how ROHC logically works. Therefore, for the case of ROHC, the channel concept is enhanced and a more restricted concept of "ROHC channels" is defined.

A ROHC channel has the same properties as a channel, with the difference that a ROHC channel is always unidirectional. A ROHC channel therefore has one single input endpoint, connected to the CO of one single ROHC compressor instance, and one single output endpoint, connected to the CI of one single ROHC decompressor instance. A ROHC channel must thus in this way be logically dedicated to one ROHC compressor/decompressor pair, hereafter referred to as ROHC peers, creating a one-to-one mapping between a ROHC channel and a pair of ROHC compressor/decompressor instances.



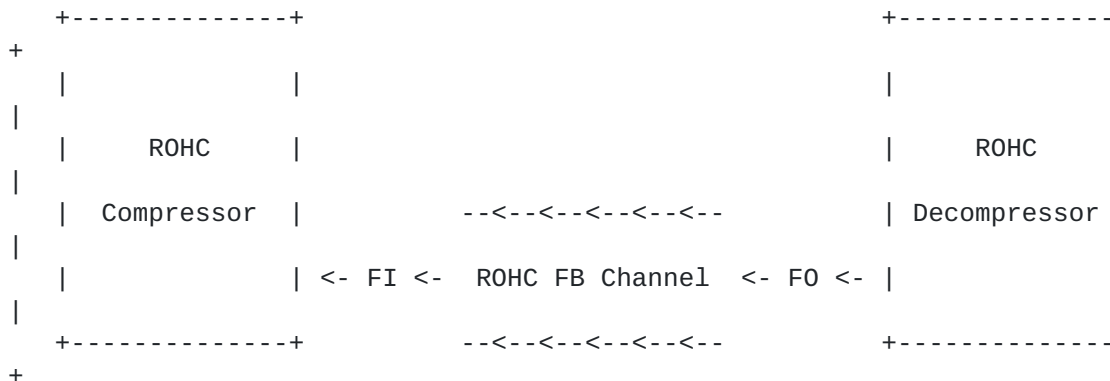
In many cases the lower layer channel is by nature bi-directional, but for ROHC communication over that channel, a ROHC channel would only represent one communication direction of that channel. For bi-directional channels, a common case would be to logically allocate one ROHC channel in each direction, allowing ROHC compression to be performed in both directions. The reason for defining ROHC channels as unidirectional is basically to separate and generalize the concept of feedback, as described and exemplified in [section 6](#).

**6. ROHC Feedback Channels**

Since ROHC can be implemented over various kind of links, unidirectional or bi-directional one-channel links as well as multi-channel links, the logical transmission of feedback from decompressor to compressor has been separated out from the transport of actual ROHC packets through the definition of ROHC channels as always being unidirectional from compressor to decompressor. This means an additional channel concept must be defined for feedback, which is what further will be referred to as "ROHC feedback channels".

In the same way as a ROHC channel is a logically dedicated unidirectional channel from a ROHC compressor to its corresponding ROHC peer decompressor, a ROHC feedback channel is a logically

dedicated unidirectional channel from a ROHC decompressor to its corresponding ROHC peer compressor. A ROHC feedback channel thus has one single input endpoint, connected to the FO of one single ROHC decompressor instance, and one single output endpoint, connected to the FI of one single ROHC compressor instance.

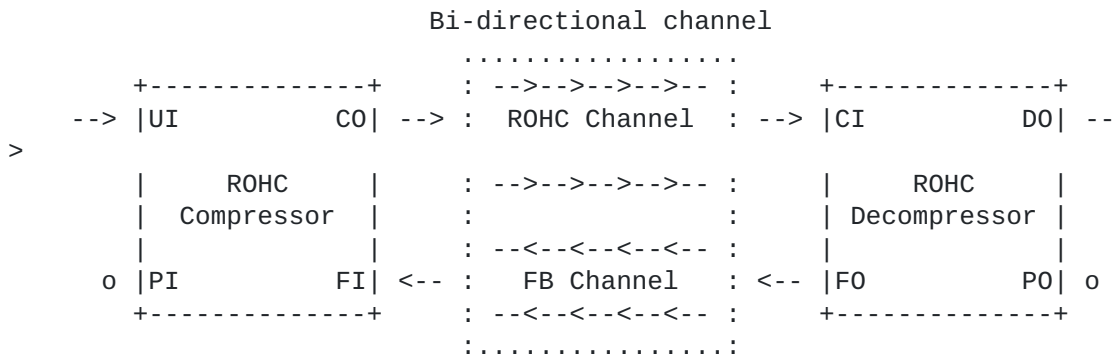


The reason for making this simplification and logically separate ROHC channels from ROHC feedback channels is generality for handling of feedback. ROHC has been designed with the assumption of logical separation, which creates flexibility for how to realize feedback transport, as discussed in [RFC-3095, [section 5.2.1](#)]. There are no restrictions on how to implement a ROHC feedback channel, more than that it must be made available and be logically dedicated to the ROHC peers, if bi-directional compression operation is to be allowed.

The following subsections provide some, not at all exclusive, examples of how a ROHC feedback channel might possibly be realized.

### 6.1. Single-Channel Dedicated ROHC Feedback Channel Example

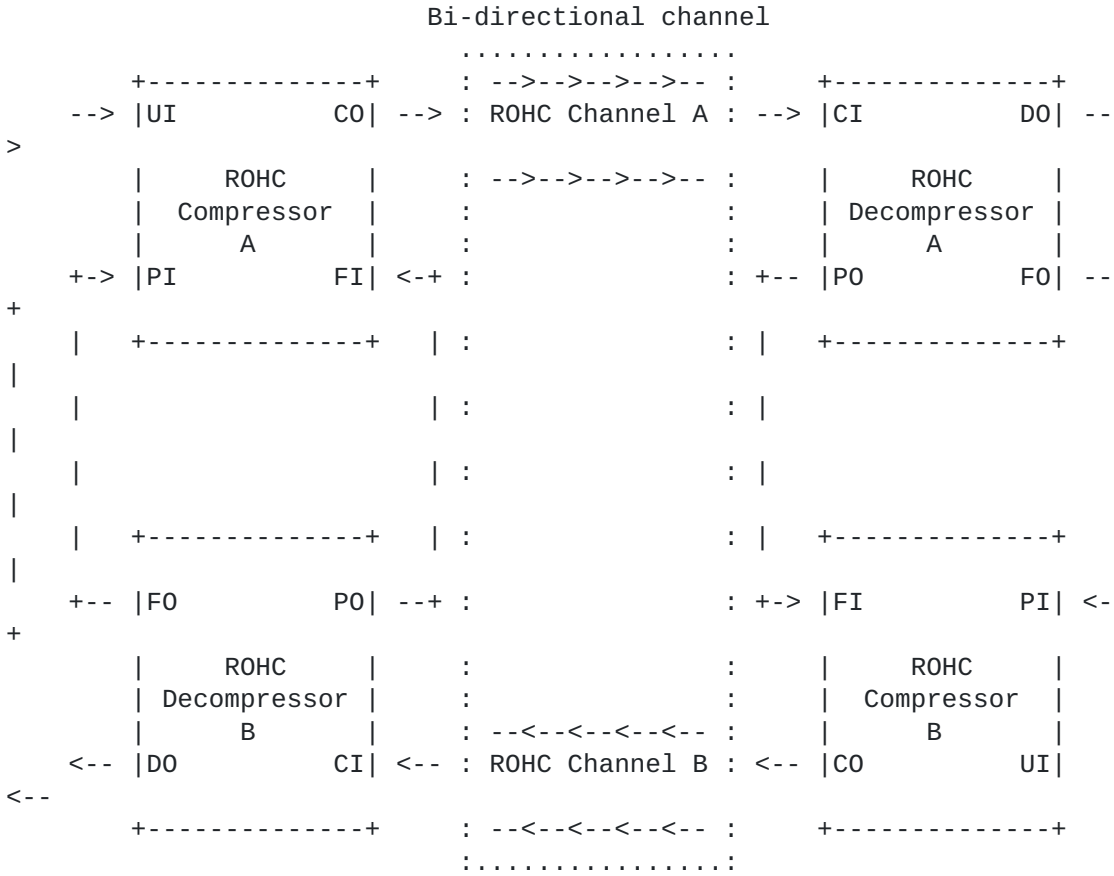
This section illustrates a one-way compression example where one bi-directional channel has been configured to represent a ROHC channel in one direction and a dedicated ROHC feedback channel in the other direction.



In this example, feedback is sent on its own dedicated channel, as discussed in e.g. feedback realization example 1-3 of ROHC [RFC-3095, page 44]. This means that the piggybacking/interspersing mechanism of ROHC is not used, and the PI/PO connections are thus left open (marked with a "o"). To facilitate communication with ROHC compression in a two-way manner using this approach, an identical configuration must be provided for the other direction, i.e. making use of four logical unidirectional channels.

**6.2. Piggybacked/Interspersed ROHC Feedback Channel Example**

This chapter illustrates how a bi-directional channel has been configured to represent one ROHC channel in each direction, while still allowing feedback to be transmitted through ROHC piggybacking and interspersing.

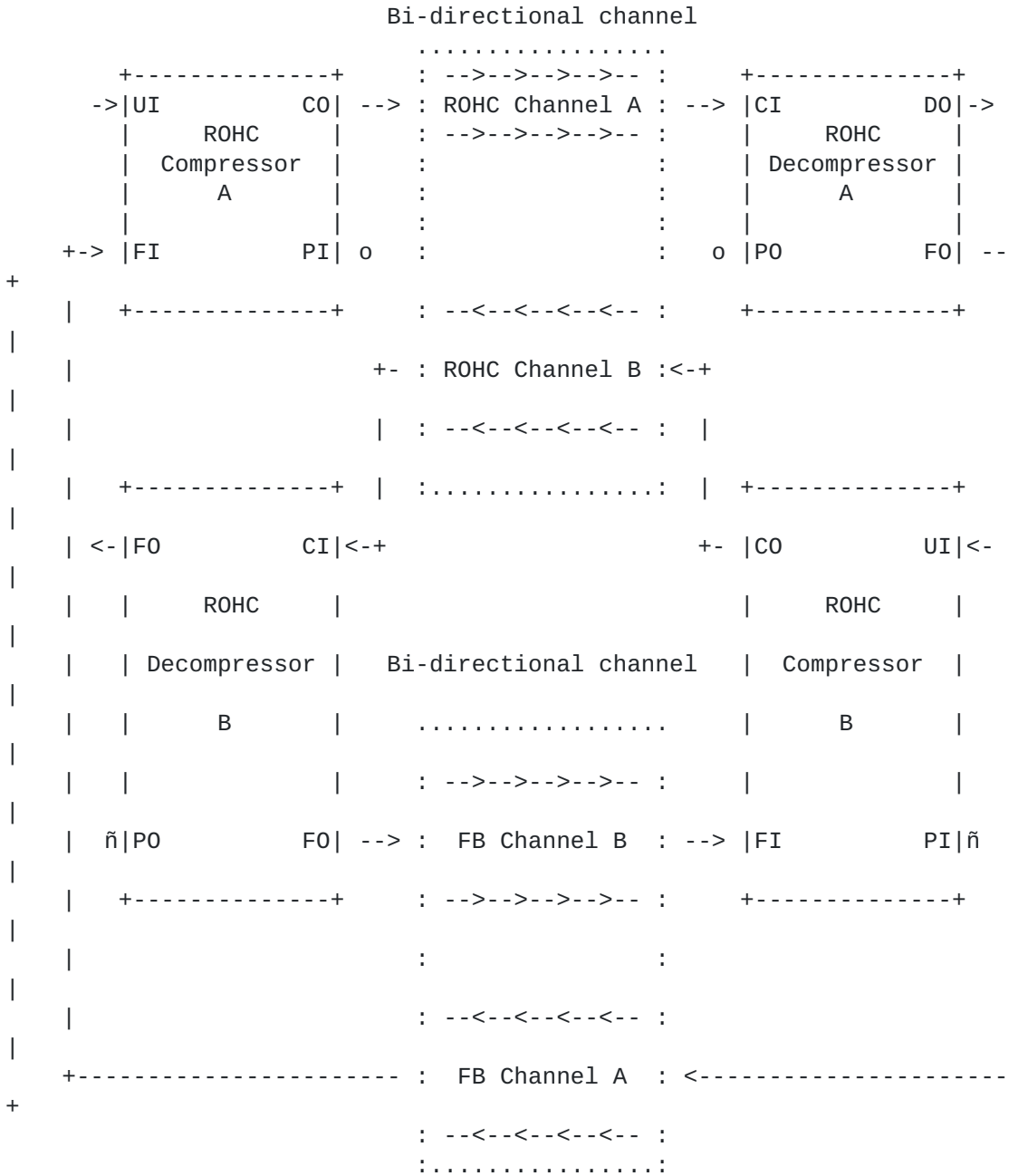


In this example, feedback is transmitted piggybacked or interspersed among compressed header packets in the ROHC channels, as discussed in e.g. feedback realization example 4-6 of ROHC [RFC-3095, page 44]. Feedback from decompressor A to compressor A is here sent through FO(A)->PI(B), piggybacked on a compressed packet over ROHC channel B, and delivered to compressor A through PO(B)->FI(A). A logical ROHC feedback channel is thus provided from the PI input at compressor B to the PO output at decompressor B. It should be noted that in this picture, PO and FO at the decompressors have been swapped to simplify drawing.



**6.3. Dual-Channel Dedicated ROHC Feedback Channel Example**

This chapter illustrates how two bi-directional channels have been configured to represent two ROHC channels and two dedicated ROHC feedback channels, respectively.



In this example, feedback is in both directions sent on its own dedicated channel, as discussed in e.g. feedback realization example 1-3 of ROHC [RFC-3095, page 44]. With this configuration, the piggybacking/interspersion mechanism of ROHC is not used, and the PI/PO connections are thus left open (marked with a "o"). It should

be noted that also in this picture, P0 and F0 at the decompressors have been swapped to simplify drawing, as well as the B-instances have been vertically mirrored.





the most important relationship conclusions are repeated:

- A network element may have one or several IP interfaces.

- Each IP interface is connected to one or several logical layer two channels.
- Each IP interface may have one or several ROHC instances, either compressors, decompressors, or an arbitrary mix of both.
- For each ROHC instance, there is exactly one ROHC channel, and optionally exactly one ROHC feedback channel.
- How ROHC channels and ROHC feedback channels are realized through the logical layer two channels available will differ, and there are therefore no general relation between ROHC instances and logical layer two channels. ROHC instances map only to ROHC channels and ROHC feedback channels.
- Each compressor owns its own context identifier (CID) space, which is the multiplexing mechanism it uses when sending compressed header packets to its corresponding decompressor. That CID space thus defines how many compressed packet streams can be concurrently sent over the ROHC channel allocated to the compressor/decompressor pair.

## **9. Implementation Implications**

This section will address some questions related to how the conceptual aspects discussed above affect implementations of ROHC.

ROHC is defined as a general header compression framework on top of which compression profiles can be defined for each specific set of headers to compress. Although the framework holds a number of important mechanisms, the separation between framework and profiles is mainly a standardization wise separation, to indicate what must be

common for all profiles, what must be defined by all profiles, and what is profile-specific details. To implement the framework as a separate module is thus not an obvious thing to do, especially if one

wants to use profile implementations from different vendors.

However,

optimized implementations will probably separate the common parts and

implement those separately, and add profile modules to that.

A ROHC instance might thus consist of various pieces of implementation modules, profiles and potentially also a common ROHC module, possibly from different vendors. If vendor and implementation

version information is made available for network management purposes, this should thus be done on a per-profile basis, and in addition to that potentially also for the instance as a whole.



## **10. Security Considerations**

This document is of informative nature, and does not have any security aspects to address.

## **11. Acknowledgements**

Thanks to Juergen Quittek, Hans Hannu, Carsten Bormann and Ghyslain Pelletier for fruitful discussions, improvement suggestions, and review.

## **12. References**

[RFC-3095] Bormann, C., Burmeister, C., Degermark, M., Fukushima, H., Hannu, H., Jonsson, L-E., Hakenberg, R., Koren, T., Le, K., Liu, Z., Martensson, A., Miyazaki, A., Svanbro, K., Wiebke, T., Yoshimura, T. and H. Zheng, "Robust Header Compression (ROHC)", [RFC 3095](#), July 2001.

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