

Network Working Group  
Internet-Draft  
Intended status: Informational  
Expires: October 8, 2016

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April 6, 2016

**Use-cases for Resiliency in SPRING  
draft-ietf-spring-resiliency-use-cases-03**

Abstract

This document describes the use cases for resiliency in SPRING networks.

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1. Introduction

SPRING aims at providing a network architecture supporting services with tight SLA guarantees [1]. This document reviews various use cases for the protection of services in a SPRING network. Note that these use cases are in particular applicable to existing LDP based and pure IP networks.

Three key alternatives are described: path protection, local protection without operator management and local protection with operator management.

Path protection lets the ingress node be in charge of the failure recovery, as discussed in Section 2.

The rest of the document focuses on approaches where protection is performed by the node adjacent to the failed component, commonly referred to as local protection techniques or Fast Reroute techniques.

We discuss two different approaches to provide unmanaged local protection, namely link/node bypass protection and shortest path based protection, in Section 3.

In Section 5, we discuss the opportunity for the SPRING architecture to provide loop-avoidance mechanisms, such that transient forwarding state inconsistencies during routing convergence does not lead to traffic loss.

A case is then made to allow the operator to manage the local protection behavior in order to accommodate specific policies, in Section 4.

The purpose of this document is to illustrate the different approaches and explain how an operator could combine them in the same network (see Section 6). Solutions are not defined in this document.

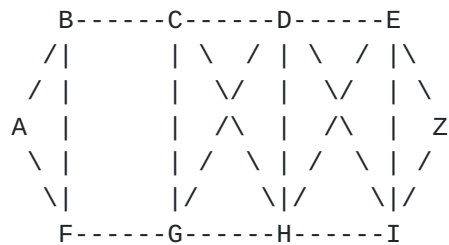


Figure 1: Reference topology

We use Figure 1 as a reference topology throughout the document. All



link metrics are equal to 1, with the exception of the links from/to A and Z, which are configured with a metric of 100.

## **2. Path protection**

A first protection strategy consists in excluding any local repair but instead use end-to-end path protection.

For example, a Pseudo Wire (PW) from A to Z can be "path protected" in the direction A to Z in the following manner: the operator configures two SPRING paths T1 and T2 from A to Z. The two paths are installed in the forwarding plane of A and hence are ready to forward packets. The two paths are made disjoint using the SPRING architecture.

T1 is established over path {AB, BC, CD, DE, EZ} and T2 over path {AF, FG, GH, HI, IZ}. When T1 is up, the packets of the PW are sent on T1. When T1 fails, the packets of the PW are sent on T2. When T1 comes back up, the operator either allows for an automated reversion of the traffic onto T1 or selects an operator-driven reversion. The solution to detect the end-to-end liveness of the path is out of the scope of this document.

From a SPRING viewpoint, we would like to highlight the following requirement: the two configured paths T1 and T2 MUST NOT benefit from local protection.

## **3. Management free local protection**

This section describes two alternatives to provide local protection without requiring operator management, namely bypass protection and shortest-path based protection.

For example, a demand from A to Z, transported over the shortest paths provided by the SPRING architecture, benefits from management-free local protection by having each node along the path automatically pre-compute and pre-install a backup path for the destination Z. Upon local detection of the failure, the traffic is repaired over the backup path in sub-50msec.

The backup path computation should support the following requirements:

- o 100% link, node, and SRLG protection in any topology



- o Automated computation by the IGP
- o Selection of the backup path such as to minimize the chance for transient congestion and/or delay during the protection period, as reflected by the IGP metric configuration in the network.

**3.1. Management free bypass protection**

One way to provide local repair is to enforce a failover along the shortest path around the failed component, ending at the protected nexthop, so as to bypass the failed component and re-join the pre-convergence path at the nexthop. In the case of node protection, such bypass ends at the next-nexthop.

In our example, C protects Z, that it initially reaches via CD, by enforcing the traffic over the bypass {CH, HD}. The resulting end-to-end path between A and Z, upon recovery against the failure of C-D, is depicted in Figure 2.

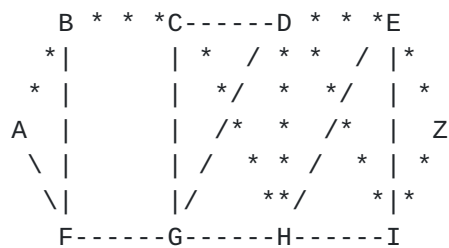


Figure 2: Bypass protection around link C-D

**3.2. Management-free shortest path based protection**

An alternative protection strategy consists in management-free local protection, aiming at providing a repair for the destination based on shortest path state for that destination.

In our example, C protects Z, that it initially reaches via CD, by enforcing the traffic over its shortest path to Z, considering the failure of the protected component. The resulting end-to-end path between A and Z, upon recovery against the failure of C-D, is depicted in Figure 3.

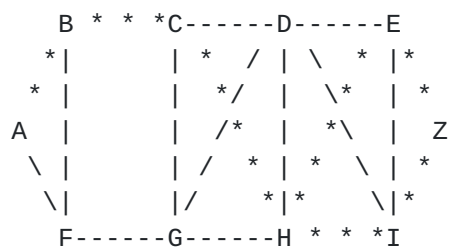






Figure 3: Reference topology

4. Managed local protection

There may be cases where a management free repair does not fit the policy of the operator. For example, in our illustration, the operator may want to not have C-D and C-H used to protect each other, in fear of a shared risk among the two links.

In this context, the protection mechanism must support the explicit configuration of the backup path either under the form of high-level constraints (end at the next-hop, end at the next-next-hop, minimize this metric, avoid this SRLG...) or under the form of an explicit path.

We discuss such aspects for both bypass and shortest path based protection schemes.

4.1. Managed bypass protection

Let us illustrate the case using our reference example. For the demand from A to B, the operator does not want to use the shortest failover path to the nexthop, {CH, HD}, but rather the path {CG,GH,HD}, as illustrated in Figure 4.

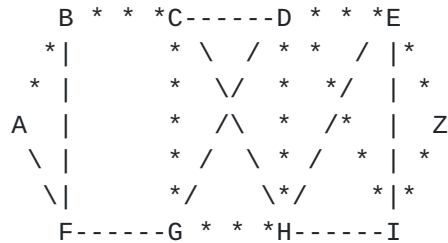


Figure 4: Managed bypass protection

4.2. Managed shortest path protection

In the case of shortest path protection, the case is the one of an operator who does not want to use the shortest failover via link C-H, but rather reach H via {CG, GH}.

The resulting end-to-end path upon activation of the protection is illustrated in Figure 5.



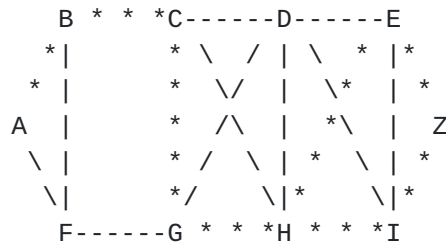


Figure 5: Managed shortest path protection

**5. Loop avoidance**

Transient inconsistencies among the Forwarding Information Bases of routers converging after a change in the state of links of the network can occur. Such inconsistencies (some nodes forwarding traffic according to the past network topology while some other nodes are forwarding packets according to the new topology) may lead to forwarding loops.

The SPRING architecture SHOULD provide solutions to prevent the occurrence of micro-loops during convergence following a change in the network state. A SPRING enabled router could take advantage of the increased packet steering capabilities offered by SPRING in order to steer packets in a way that packets do not enter such loops.

**6. Co-existence**

The operator may want to support several very-different services on the same packet-switching infrastructure. As a result, the SPRING architecture SHOULD allow for the co-existence of the different use cases listed in this document, in the same network.

Let us illustrate this with the following example.

- o Flow F1 is supported over path {C, C-D, E}
- o Flow F2 is supported over path {C, C-D, I}
- o Flow F3 is supported over path {C, C-D, Z}
- o Flow F4 is supported over path {C, C-D, Z}
- o It should be possible for the operator to configure the network to achieve path protection for F1, management free shortest path local protection for F2, managed protection over path {C-G, G-H, Z} for F3, and management free bypass protection for F4.



## **7. References**

- [1] Filsfils, C., Previdi, S., Decraene, B., Litkowski, S., and R. Shakir, "Segment Routing Architecture", [draft-ietf-spring-segment-routing-07](#) (work in progress), December 2015.

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