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**Implementation Recommendations to Improve the Scalability of RSVP-TE
Deployments
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Abstract

The scale at which RSVP-TE Label Switched Paths (LSPs) get deployed is growing continually and the onus is on RSVP-TE implementations across the board to keep up with this increasing demand.

This document makes a set of implementation recommendations to help RSVP-TE deployments push the envelope on scaling and advocates the use of a couple of techniques - "Refresh-Interval Independent RSVP (RI-RSVP)" and "Per-Peer Flow-Control" - for improving scaling.

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[1.](#) Introduction

The scale at which RSVP-TE [[RFC3209](#)] Label Switched Paths (LSPs) get deployed is growing continually and there is considerable onus on RSVP-TE implementations across the board to keep up with this increasing demand in scale.

The set of RSVP Refresh Overhead Reduction procedures [[RFC2961](#)] serves as a powerful toolkit for RSVP-TE implementations to help cover a majority of the concerns about soft-state scaling. However, even with these tools in the toolkit, analysis of existing implementations [[RFC5439](#)] indicates that the processing required under certain scale may still cause significant disruption to an LSR.

This document builds on the scaling work and analysis that has been done so far and makes a set of concrete implementation recommendations to help RSVP-TE deployments push the envelope further on scaling - push higher the threshold above which an LSR struggles to achieve sufficient processing to maintain LSP state.

This document advocates the use of a couple of techniques - "Refresh-Interval Independent RSVP (RI-RSVP)" and "Per-Peer Flow-Control" - for significantly cutting down the amount of processing cycles required to maintain LSP state. "RI-RSVP" helps completely eliminate RSVP's reliance on refreshes and refresh-timeouts while "Per-Peer Flow-Control" enables a busy RSVP speaker to apply back pressure to its peer(s). In order to reap maximum scaling benefits, it is strongly RECOMMENDED that implementations support both the techniques, but it is possible for an implementation to support just one but not the other.

[1.1.](#) Conventions used in this document

The key words "MUST", "MUST NOT", "REQUIRED", "SHALL", "SHALL NOT", "SHOULD", "SHOULD NOT", "RECOMMENDED", "MAY", and "OPTIONAL" in this document are to be interpreted as described in [[RFC2119](#)]

[2.](#) Recommendations

[2.1.](#) "[RFC2961](#) specific" Recommendations

The implementation recommendations discussed in this section are based on the proposals made in [[RFC2961](#)] and act as pre-requisites for implementing either or both of the techniques discussed in Sections [2.2](#) and [2.3](#).

[2.1.1.](#) Basic Pre-Requisites

An implementation that supports either or both of the techniques discussed in Sections [2.2](#) and [2.3](#):

- o SHOULD indicate support for RSVP Refresh Overhead Reduction extensions (as specified in [Section 2 of \[RFC2961\]\(#\)](#)) by default, with the ability to override the default via configuration.

- o MUST support reliable delivery of Path/Resv and the corresponding Tear/Err messages using the procedures specified in [\[RFC2961\]](#).
- o MUST support retransmit of all RSVP-TE messages using exponential-backoff, as specified in [Section 6 of \[RFC2961\]](#).

2.1.2. Making Acknowledgements mandatory

The reliable message delivery mechanism specified in [\[RFC2961\]](#) states that "Nodes receiving a non-out of order message containing a MESSAGE_ID object with the ACK_Desired flag set, SHOULD respond with a MESSAGE_ID_ACK object."

In an implementation that supports either or both of the techniques discussed in Sections [2.2](#) and [2.3](#), nodes receiving a non-out of order message containing a MESSAGE ID object with the ACK-Desired flag set, MUST respond with a MESSAGE_ID_ACK object. This improvement to the predictability of the system in terms of reliable message delivery is key for being able to take any action based on a non-receipt of an ACK.

2.1.3. Clarifications on reaching Rapid Retry Limit (Rl)

According to [section 6 of \[RFC2961\]](#) "The staged retransmission will continue until either an appropriate MESSAGE_ID_ACK object is received, or the rapid retry limit, Rl, has been reached." The following clarifies what actions, if any, a router should take once Rl has been reached.

If it is the retransmission of Tear/Err messages and Rl has been reached, the router need not take any further actions. If it is the retransmission of Path/Resv messages and Rl has been reached, then the router starts periodic retransmission of these messages. The retransmitted messages MUST carry MESSAGE_ID object with ACK_Desired flag set. This periodic retransmission SHOULD continue until an appropriate MESSAGE_ID ACK object is received indicating acknowledgement of the (retransmitted) Path/Resv message. The configurable periodic retransmission interval SHOULD be less than the regular refresh interval. A default periodic retransmission interval of 30 seconds is RECOMMENDED by this document.

2.2. Refresh-Interval Independent RSVP

The RSVP protocol relies on periodic refreshes for state synchronization between RSVP neighbors and for recovery from lost RSVP messages. It relies on refresh timeout for stale state cleanup. The primary motivation behind introducing the notion of "Refresh Interval Independent RSVP" (RI-RSVP) is to completely eliminate

RSVP's reliance on refreshes and refresh timeouts. This is done by simply increasing the refresh interval to a fairly large value. [RFC2961] and [RFC5439] do talk about increasing the value of the refresh-interval to provide linear improvement on transmission overhead, but also point out the degree of functionality that is lost by doing so. This section revisits this notion, but also proposes sufficient recommendations to make sure that there is no loss of functionality incurred by increasing the value of the refresh interval.

An implementation that supports RI-RSVP:

- o MUST support all the recommendations made in [Section 2.1](#).
- o MUST make the default value of the configurable refresh interval be a large value (10s of minutes). A default value of 20 minutes is RECOMMENDED by this document.
- o MUST implement coupling the state of individual LSPs with the state of the corresponding RSVP-TE signaling adjacency. When an RSVP-TE speaker detects RSVP-TE signaling adjacency failure, the speaker MUST act as if the all the Path and Resv state learnt via the failed signaling adjacency has timed out.
- o MUST make use of Node-ID based Hello Session ([RFC3209], [RFC4558]) for detection of RSVP-TE signaling adjacency failures; A default value of 9 seconds is RECOMMENDED by this document for the configurable node hello interval (as opposed to the 5ms default value proposed in [Section 5.3 of \[RFC3209\]](#)).
- o MUST indicate support for RI-RSVP via the CAPABILITY object in Hello messages.

[2.2.1](#). Capability Advertisement

An implementation supporting the RI-RSVP recommendations MUST set a new flag "RI-RSVP Capable" in the CAPABILITY object signaled in Hello messages.

The new flag that will be introduced to CAPABILITY object is specified below.

The set of recommendations discussed in this section provide an RSVP speaker with the ability to apply back pressure to its peer(s) to reduce/eliminate RSVP-TE control plane congestion.

- o MUST indicate support for all recommendations in this section via the CAPABILITY object in Hello messages.

2.3.1. Capability Advertisement

An implementation supporting the "Per-Peer Flow-Control" recommendations MUST set a new flag "Per-Peer Flow-Control Capable" in the CAPABILITY object signaled in Hello messages.

The new flag that will be introduced to CAPABILITY object is specified below.

```

      0               1               2               3
      0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1
+---+---+---+---+---+---+---+---+---+---+---+---+---+---+---+---+
|               Length               | Class-Num(134) | C-Type (1) |
+---+---+---+---+---+---+---+---+---+---+---+---+---+---+---+---+
|               Reserved               | F | I | T | R | S |
+---+---+---+---+---+---+---+---+---+---+---+---+---+---+---+---+

```

F bit

Indicates that the sender supports Per-Peer RSVP Flow-Control

Any node that sets the new I-bit in its CAPABILITY object MUST also set Refresh-Reduction-Capable bit in common header of all RSVP-TE messages.

2.3.2. Compatibility

The "Per-Peer Flow-Control" functionality MUST be activated only if both peers support it. If a peer hasn't indicated that it is capable of participating in "Per-Peer Flow-Control", then it is risky to assume that the peer would always acknowledge a non-out of order message containing a MESSAGE ID object with the ACK-Desired flag set.

3. Acknowledgements

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5. IANA Considerations

5.1. Capability Object Values

IANA maintains all the registries associated with "Resource Reservation Protocol (RSVP) Parameters" (see <http://www.iana.org/assignments/rsvp-parameters/rsvp-parameters.xhtml>). "Capability Object Values" Registry (introduced by [RFC5063]) is one of them.

IANA is requested to assign two new Capability Object Value bit flags as follows:

Bit Number	Hex Value	Name	Reference

TBA	TBA	RI-RSVP Capable (I)	Section 2.2.1
TBA	TBA	Per-Peer Flow-Control Capable (F)	Section 2.3.1

6. Security Considerations

This document does not introduce new security issues. The security considerations pertaining to the original RSVP protocol [RFC2205] and RSVP-TE [RFC3209] and those that are described in [RFC5920] remain relevant.

7. References

7.1. Normative References

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7.2. Informative References

- [RFC5439] Yasukawa, S., Farrel, A., and O. Komolafe, "An Analysis of Scaling Issues in MPLS-TE Core Networks", [RFC 5439](#), DOI 10.17487/RFC5439, February 2009, <<http://www.rfc-editor.org/info/rfc5439>>.
- [RFC5920] Fang, L., Ed., "Security Framework for MPLS and GMPLS Networks", [RFC 5920](#), DOI 10.17487/RFC5920, July 2010, <<http://www.rfc-editor.org/info/rfc5920>>.

Appendix A. Recommended Defaults

(a) Refresh-Interval (R)- 20 minutes ([Section 2.2](#)) Given that an implementation supporting RI-RSVP doesn't rely on refreshes for state sync between peers, the RSVP refresh interval is sort of analogous to IGP refresh interval, the default of which is typically in the order of 10s of minutes. Choosing a default of 20 minutes allows the refresh timer to be randomly set to a value in the range [10 minutes (0.5R), 30 minutes (1.5R)].

(b) Node Hello-Interval - 9 Seconds ([Section 2.2](#)) [[RFC3209](#)]
defines the hello timeout as 3.5 times the hello interval.
Choosing 9 seconds for the node hello-interval gives a hello
timeout of $3.5 \times 9 = 31.5$ seconds. This puts the hello timeout
value to be in the same ballpark as the IGP hello timeout value.

(c) Retry-Limit (Rl) - 7 ([Section 2.3](#)) Choosing 7 as the retry-
limit results in an overall rapid retransmit phase of 31.5
seconds. This nicely matches up with the 31.5 seconds hello
timeout.

(d) Periodic Retransmission Interval - 30 seconds ([Section 2.1.3](#))
If the Retry-Limit (Rl) is 7, then it takes about 30 (31.5 to be
precise) seconds for the 7 rapid retransmit steps to max out.
(The last delay from message 6 to message 7 is 16 seconds). The
30 seconds interval also matches the traditional default refresh
time.

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