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The CCAPI (COPS Client Application Programming Interface)

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Abstract

This document focuses on the Admission Control functionality performed

by the Edge Router in the IntServ/DiffServ interworking scenario described in [COPS-ISDS]. More precisely it describes the interaction between the RSVP and the COPS protocols in the Edge Router and

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introduces an API (Application Programming Interface) aimed at allowing the intercommunication between them. Anyway, the API described here is designed as a flexible interface, and should be able to support communication between a generic application and the COPS Client Type described in [COPS-ODRA].

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## Glossary

|       |   |
|-------|---|
| API   | Application Programming Interface             |
| BB    | Bandwidth Broker                              |
| CCAPI | COPS Client Application Programming Interface |
| COPS  | Common Open Policy Service                    |
| DSCP  | Differentiated Services Code Point            |
| ER    | Edge Router                                   |
| IPC   | Inter Process Communication                   |
| PDP   | Policy Decision Point.                        |
| PEP   | Policy Enforcement Point.                     |
| QoS   | Quality of Service                            |
| RSVP  | ReSerVation Protocol                          |
| SLS   | Service Level Specification                   |

## 1. Introduction

One of the possible scenarios for end-to-end QoS provisioning relies on a proper combination of both the Integrated Services (IntServ) ([[INTSERV](#)] and [[RFC2210](#)]) and the Differentiated Services (DiffServ) ([[2BIT](#)] and [[DSARCH](#)]) architectures. The description of such a model is beyond the scope of this document; a detailed explanation can be found in [[INTDIF](#)] and in [[COPS-ISDS](#)]. However it is worth observing that the router placed at the boundary between the IntServ stub domain and the

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DiffServ core, i.e. the Edge Router (ER), provides several interworking functionality (described in details in the references above).

One of the most important functionality managed by the ER is related to admission control. The original DiffServ architecture provides a sort of implicit admission control, in the form of SLS negotiated between neighboring domains. The introduction of end-to-end signaling by means of the RSVP protocol allows explicit admission control on micro-flow basis, as explained in details in [[INTDIF](#)].

Note, however, that there are at least two ways to perform Admission Control in the Edge Router. In fact, it can be realized either in a distributed way by means of information locally available, or in a centralized way by querying an Admission Control Server. As stated in [[COPS-ISDS](#)], the first approach is easier to implement, but it is nevertheless characterized by inaccuracy, since each ER does not have an overall knowledge of the network resource utilization. Moreover, in some situations (failures, etc.), consistency among information stored in different ERs could not be assured. For this reason [[COPS-ISDS](#)] focuses on the second solution. However, in such a scenario the communication between the ER and the centralized server must happen according to a proper protocol. COPS represents a possible choice, since it is a simple and extensible protocol; [[COPS-ODRA](#)] proposes an extension suited at the purpose.

Besides the COPS extension, needed for the communication between the centralized server and the Edge Router, another communication interface should be defined. In fact, the Edge Router supports both the COPS-ODRA PEP and the RSVP daemon. As explained in [[COPS-ISDS](#)], the entire mechanism requires proper interaction between them; for example the reception of a RSVP RESV message by the ingress ER should trigger an admission control query towards the server (PDP/BB). This observation leads to the definition of a new interface between the COPS-ODRA client and the RSVP daemon within the Edge Router.

This document describes an API that can be used at the purpose. This

API, called CCAPI (COPS Client API), is based on a client library statically linked with the RSVP daemon. The latter can trigger queries to the PDP/BB server when needed and can receive responses from it either synchronously or asynchronously, as explained in the following paragraph. Note, however, that the CCAPI is designed in a flexible way, in order to be usable with applications other than RSVP, that could need to interact with the COPS-ODRA PEP for whatever reason. For this reason in the remaining part of the document we will use the term `_CCAPI client_` to refer to such an application, thus avoiding to mention explicitly RSVP, even if it obviously represents the natural choice.

## 2. CCAPI generalities

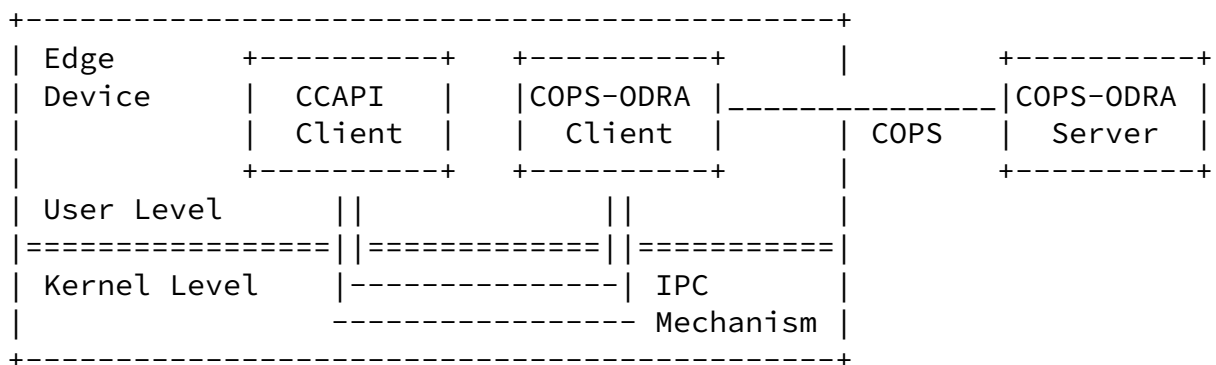
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As stated above, the CCAPI is realized by means of a client library statically linked with the CCAPI client. The procedures implemented in the CCAPI library use a proper inter-process communication (IPC) mechanism to interact with the COPS client, which in turn relies on the COPS protocol to communicate with the server. The situation is depicted in the following figure:



Note that there is no need to standardize the inter-process communication mechanism, since it could vary due to several reasons, such as Operating System characteristics. The CCAPI proposed here does not assume anything about it, even if the actual implementation relies on the Linux socket mechanism. The definition of the interface specifies only the visible part of it, i.e. the set of routines made available to the CCAPI client. They are listed and explained in the following.

The API can be used to manage events both in a synchronous and in an asynchronous way. In the first case the CCAPI client triggers a query to the PDP/BB and blocks indefinitely waiting for a response. This is the easiest way to use the CCAPI, but it could lead to undesirable behavior in the case of no response from the server. Let us consider as an example the case of an admission control request from RSVP; if the server does not respond for whatever reason, the daemon would wait indefinitely. This is obviously undesirable, since normal processing of other requests should not be blocked by a pending request (e.g. timeout of installed PATH and RESV states would expire, and so on).

For this reason the CCAPI has been designed to manage events asynchronously, by means of an `_upcall_` or `_callback_` mechanism. In this way the CCAPI client triggers the request from the PEP to the PDP/BB without waiting for response. When a response from the PDP/BB is available, the PEP notifies the CCAPI client (e.g. the RSVP daemon) that, in turn, manages it by calling a proper callback routine.

A synchronous error in a CCAPI library routine returns an appropriate error code. Asynchronous errors are delivered to the application via the CCAPI upcall routine. Text messages for synchronous and asynchronous error codes can be found in the file `cops_err.h`.

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### [3. CCAPI Description](#)

This paragraph reports a brief description of the sequence of operations needed by the CCAPI client and lists all the CCAPI calls along with their explanation.

#### [3.1. CCAPI Outline](#)

The CCAPI client must include `cops_api.h` and `cops_err.h` and must be linked with `cops_api.c`. It begins by opening the session to the COPS-ODRA PEP via the `cops_api_open_session()` call; when it issues this call it can optionally specify a pointer to an appropriate callback routine (if any). The session associates the CCAPI Client with the PEP, meaning that the latter cannot have more sessions opened at the same time. If this is the need, several PEP processes should be instantiated together on the same Edge Router, and each of them should have a single session opened towards the CCAPI client.

After the `cops_api_open_session()` call, the CCAPI client can ask for resource request, release and/or modify by means of the `bandwidth_request()`, `bandwidth_release()` and `bandwidth_modify()` calls, with proper parameters. In order to get a response the `cops_api_dispatch()` call can be used. In the `_blocking_` case, the `cops_api_dispatch()` can be preceded by a `select()` system call, in order to wait indefinitely for an event; when such an event occurs, the `select` is unblocked and the `cops_api_dispatch()` can be used to obtain the response. No callback routine is needed in this case. In contrast, in the `_non blocking_` case, a proper callback routine is specified in the `cops_api_open_session()`. The `cops_api_dispatch()` is periodically called inside the CCAPI client main loop, and it polls the PEP to see if a response has arrived; if so, the callback routine is executed. The latter receives also an optional argument that can be specified when opening the session through the `cops_api_open_session()` call.

Whatever the mechanism we choose, `_blocking_` or `_non blocking_`, at the end of all the operations the session can be closed via the `cops_api_release_session()` call. In the following a brief description of all the CCAPI calls is reported.

## [3.2. CCAPI calls](#)

### [3.2.1. cops\\_api\\_open\\_session\(\)](#)

The `cops_api_open_session()` call is used to open a session with the COPS-ODRA PEP. It returns a `cops_api_error` (i.e. an unsigned int), which could be any of the following values:

`COPS_API_OK` - session opened without problems

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`COPS_API_NOCOPS` - COPS-ODRA PEP is not running on the ER

`COPS_API_OPEN` - session already opened

The definition of the function is the following:

```
cops_api_error  
cops_api_open_session ( cops_event_rtn event_rtn,  
                        void *event_rtn_arg)
```

The parameters are:

`event_rtn` - is a pointer to the callback function specified by the CCAPI client. It could be NULL if the latter is not interested in managing asynchronous events by the upcall mechanism.

event\_rtn\_arg - is a pointer to an optional parameter that is passed to the callback routine whenever it is called.

### [3.2.2. cops\\_api\\_getfd\(\)](#)

It may be used by the CCAPI client to retrieve a file descriptor; this, in turn, could be used in a select() call immediately before the dispatch(), so as to realize a blocking mechanism. The function is specified as follows:

```
int  
cops_api_getfd()
```

It doesn't require parameters and returns the file descriptor, or `_1` if the session has not been opened before.

### [3.2.3. cops\\_api\\_release\\_session\(\)](#)

The `cops_api_release_session()` is used to close the session with the COPS-ODRA PEP. It returns a `cops_api_error` of the following types:

```
COPS_API_OK      - session closed without problems  
COPS_API_CLOSE  - session already closed  
COPS_API_SYSERR - system error
```

The function prototype is:

```
cops_api_error  
cops_api_release_session ()
```

No parameters are requested.

### [3.2.4. bandwidth\\_request\(\)](#)

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The `bandwidth_request()` library call is used by the CCAPI client in order to instruct the PEP to query the PDP/BB for bandwidth request; referring to RSVP as an example, this could happen whenever a new flow is admitted at the ingress Edge Router. The function prototype is the following:

```
cops_api_error  
bandwidth_request ( cops_req *request)
```

It takes in input a pointer to a `cops_req` structure, that contains information about the request. The definition of the `cops_req` structure is reported in paragraph 5. Note that it also contains a request identifier, that is used in the `_non-blocking_` case to associate requests made by the CCAPI client to responses provided by the PEP. In fact, in such a case, the CCAPI client can issue several requests to the PEP, and a way to relate them to corresponding responses is obviously needed. The library call can return one of the following values:

```
COPS_API_OK      - request successfully delivered to the PEP
COPS_API_INVREQ  - invalid request; session not in place
COPS_API_INVRID  - invalid request identifier (already in use)
COPS_API_TOOMF   - excessive number of pending requests
COPS_API_SYSERR  - system error
```

### [3.2.5. bandwidth\\_release\(\)](#)

This is the complementary function to the previous one. The CCAPI client uses it in order to instruct the PEP to communicate bandwidth release to the PDP/BB. If the CCAPI client is represented by RSVP, `bandwidth_release()` is called when a reservation is released, e.g. upon the reception of a RESV TEAR message by the ingress Edge Router.

```
cops_api_error
bandwidth_release ( cops_req *request)
```

The parameters and the return values of this function are the same of the `bandwidth_request()`.

### [3.2.6. bandwidth\\_modify\(\)](#)

The `bandwidth_modify()` call has been introduced with reference to the situation where the CCAPI client is represented by RSVP. It can be used to change dynamically a reservation without first releasing resources and then allocating them again. In this way there are two advantages: first of all the reservation is changed with a single message. Moreover, in the case of rejection of the new request, the old one remains in place. The function is defined as follows:

```
cops_api_error
bandwidth_modify ( cops_req *request)
```

The parameter is a pointer to a `cops_req` structure; differently from the



case of `bandwidth_request()` and `bandwidth_release()` this request now contains a pair of bandwidth values, instead of a single one. The return values are the same of `bandwidth_request()`.

### [3.2.7.](#) `cops_api_dispatch()`

Applications use the `cops_api_dispatch()` library call to receive notifications of COPS events, e.g. responses to their queries. The function prototype is the following:

```
cops_api_error  
cops_api_dispatch ( cops_resp *response)
```

The `cops_api_dispatch()` polls the PEP for a response and retrieves it for the CCAPI client. The parameter is a pointer to a `cops_resp` structure; if not NULL, it is eventually filled with the response. If the latter is not available the object referenced by this parameter is left unchanged. Moreover the callback function specified in the `cops_api_open_session()` (if any) is called. An explanation of the upcall mechanism can be found in paragraph 4. Note however that the `cops_api_dispatch()` is a non blocking call; if a response is not available, it immediately returns control to the calling function. Possible return values of `cops_api_dispatch()` are:

```
COPS_API_OK      - dispatch successfully executed  
COPS_API_NOCOPS - COPS-ODRA PEP is not running on the ER  
COPS_API_INVREQ - invalid request; session not in place  
COPS_API_SYSERR - system error
```

### [3.2.8.](#) `cops_api_version()`

The `cops_api_version()` call returns the version number of the CCAPI in the form `major*100+minor`. Current version is 1.00.

## [4.](#) Upcall mechanism

An upcall is invoked by `cops_api_dispatch()`, which executes the procedure specified by the `event_rtn` parameter of the `cops_api_open_session()` call (if specified).

The upcall function has the following synopsis:

```
int  
ccapi_callback ( cops_resp *response,  
                void *arg)
```

It receives from `cops_api_dispatch()` the response just arrived and the user specified parameter (represented by the `event_rtn_arg` parameter in the `cops_api_open_session()` call). Based on these parameters it executes an application specified routine. There are basically two types of events that can trigger an upcall:

- DECISION EVENT: this event notifies the CCAPI client about a response from the PDP/BB, which could be either positive (i.e. request accepted) or negative (i.e. the request was rejected for some reason, e.g. bandwidth unavailability or unsupported service).
- ERROR EVENT: it is used to signal error events directly recognized by the PEP, e.g. invalid request or excessive number or pending requests.

The type of event is contained in the response that is passed to the `ccapi_callback()` (see paragraph 5). It also contains a code that specifies the particular reason for that event. Possible codes for both DECISION EVENTS and ERROR EVENTS are contained in tables 1 and 2 below:

| Code        | Reason that triggered the event     |
|-------------|-------------------------------------|
| COPS_OK     | Request accepted                    |
| COPS_NOBW   | Unavailable resources               |
| COPS_NODSCP | Unsupported service                 |
| COPS_NOIED  | Invalid Ingress Edge Device Address |
| COPS_NOEED  | Invalid Egress Edge Device Address  |

Table 1: Codes for DECISION EVENTS (PDP/BB responses)

| Code            | Reason that triggered the event         |
|-----------------|---|
| COPS_API_OK     | Operation successfully completed        |
| COPS_API_INVRID | Invalid Request Identifier              |
| COPS_API_INVREQ | Invalid Request or Session not in place |
| COPS_API_NOCOPS | COPS Client (PEP) not running on the ER |
| COPS_API_OPEN   | Session already opened                  |
| COPS_API_CLOSE  | Session already closed                  |
| COPS_API_TOOMF  | Excessive number of requests            |



- IED\_addr: IP address of the ingress Edge Device
- EED\_addr: IP address of the egress Edge Device
- dscp[]: two-element vector. In the case of bandwidth\_request() and bandwidth\_release() calls, the first element contains the DSCP of the requested service, while the second is unspecified. In the case of bandwidth\_modify() the two elements contains respectively the old and the new value for the DSCP.
- token\_size[], msr\_interval[]: a pair of two element vectors. The corresponding bandwidth is given by the ratio:
 
$$\text{token\_size}[n]/\text{msr\_interval}[n] \quad n=0,1$$
 In the case of bandwidth\_request() and

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bandwidth\_release() only the first two elements are meaningful; they contains the bandwidth to be requested/released. In the case of bandwidth\_modify() the values token\_size[0]/msr\_interval[0] and token\_size[1]/msr\_interval[1] contains respectively the old and the new value for the bandwidth.

- cops\_resp object

```
typedef struct Cops_Resp {
    unsigned int request_ID;
    cops_event_type resp_type;
    cops_error resp_errcode;
} cops_resp;
```

This object contains the responses received by the CCAPI Client. The fields have the following meaning:

- request\_ID: is the same value contained in the request. It is returned by the PEP to the CCAPI Client in order to associate the response to the corresponding request.
- resp\_type: specifies the type of response. Two types are currently supported:

```
DECISION_EVENT
ERROR_EVENT
```

The difference is explained in the previous paragraph.

-resp\_errcode: depending on resp\_type, it gives detailed information about the event that triggered the response. Possible values are reported in table 1 and table 2.

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## 7. Author Information and Acknowledgements

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