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Generic Fault-avoidance Routing Protocol for Data Center Networks
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Abstract

This draft proposes a generic routing method and protocol for a regular data center network, named as fault-avoidance routing (FAR) protocol. FAR protocol provides a generic routing method for all types of regular topology network architectures that are proposed for large-scale cloud-based data centers over the past few years. FAR protocol is well designed to fully leverage the regularity in the topology and compute its routing table in a simplistic manner. Fat-tree is taken as an example architecture to illustrate how FAR protocol can be applied in real operational scenarios.

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[1. Introduction](#)

In recent years, with the rapid development of cloud computing technologies, the widely deployed cloud services, such as Amazon EC2 and Google search, bring about huge challenges to data center networking (DCN). Today's cloud-based data centers (DCs) require large-scale networks with larger internal bandwidth and smaller transfer delay. However, conventional networks cannot meet such requirements due to limitations in their network architecture. In order to satisfy the requirements of cloud computing services, many new network architectures have been proposed for data centers, such as Fat-tree, MatrixDCN, and BCube. These new architectures can support non-blocking large-scale datacenter networks with more than tens of thousands of physical servers.

All of these architectures have regular topologies, which are common features. The regular topology refers to the network topology structure with obvious regularity and symmetry, which is conducive to automatic configuration of the network, such as the Fattree network. In a regular topology, each network node such as a switch or router can be addressed by its location and through a node's address, the node's connections to its neighbors in a network can be determined, and furthermore, the route to the node from other nodes in the network can be determined. So nodes can compute route entries without learning topology.

This draft proposes a generic routing method and protocol, fault-avoidance routing (FAR) protocol, for DCNs. This method leverages the regularity in the topologies of data center networks to simplify routing learning and accelerate the query of routing tables. This routing method has a better fault tolerance and can be applied to any DCN with a regular topology.

FAR is not a routing protocol to replace generic routing protocols such as OSPF and IS-IS. It cannot be used in general local networks whose topological structures are arbitrary, and whose scales are also not very large. OSPF works very well in such a network. But in a large-scale network with regular topology, FAR has a better performance. Compared with OSPF and IS-IS, FAR has shorter time of network convergence and lower PDU overhead. Furthermore, FAR requires less computing and storage resources, which let FAR routers to run at a lower cost of production than the generic routers.

In addition, for each type of network architecture, researchers designed a routing algorithm according to the features of its topology. Because these routing algorithms are different and lack compatibility with each other, it is very difficult to develop a routing protocol for network routers supporting multiple routing algorithms. FAR has better adaptability than these specified routing methods.

FAR consists of three components, i.e., link state learning unit, routing table building unit and routing table querying unit. In the link state learning unit, FAR exchanges link failures among routers to establish a consistent knowledge of the entire network. In this stage, the regularity in topology is exploited to infer failed links and routers. In the routing table building unit, FAR builds up two routing tables, i.e., a basic routing table (BRT) and a negative routing table (NRT), for each router according to the network topology and link states. In the last component, routers forward incoming packets by looking up the two routing tables. The matched entries in BRT minus the matched entries in NRT are the final route entries to be used to forward an incoming packet.

The remainder of this draft is organized as follows. The problem to be addressed by FAR is described in [Section 3](#). The framework of FAR routing protocol is described in [Section 4](#). [Section 5](#) and 6 introduce FAR's data format FAR and modules in detail. [Section 7](#) describe how FAR works by finite state machine (FSM). In [Section 8](#), we discussed how FAR works with variable network architectures. [Section 9](#) takes Fat-tree network as an example to illuminate how FAR works.

[1.1](#). Acronyms & Definitions

DCN - Data Center Network

FAR - Fault-Avoidance Routing

BRT - Basic Routing Table

NRT - Negative Routing Table

NDT - Neighbor Devices Table

ADT - All Devices Table

LFT - Link Failure Table

DA - Device Announcement

LFA - Link Failure Announcement

DLR - Device and Link Request

IP - Internet Protocol

UDP - User Datagram Protocol

VM - Virtual Machine

2. Conventions used in this document

The key words "MUST", "MUST NOT", "REQUIRED", "SHALL", "SHALL NOT", "SHOULD", "SHOULD NOT", "RECOMMENDED", "MAY", and "OPTIONAL" in this document are to be interpreted as described in [RFC-2119](#) [RFC2119]. In this document, these words will appear with that interpretation only when in ALL CAPS. Lower case uses of these words are not to be interpreted as carrying [RFC-2119](#) significance.

3. Problem Statement

The problem to be addressed by FAR as proposed in this draft is described in this section. The expansion of Cloud data center networks has brought significant challenges to the existing routing technologies. FAR mainly solves a series of routing problems faced by large-scale data center networks.

3.1. The Impact of Large-scale Networks on Route Calculation

In a large-scale cloud data center network, there may be thousands of routers. Running OSPF and other routing protocols in such network will encounter these two challenges: a) Network convergence time would be too long, which will cause a longer time to elapse for creating and updating the routes. The response time to network failures may be excessively long; b) a large number of routing protocol packets need to be sent. The routing information consumes too much network bandwidth and CPU resources, which easily leads to packet loss and makes the problem (a) more prominent.

In order to solve these problems, a common practice is to partition a large network into some small areas, where the route calculation runs independently within different areas. However, nowadays the cloud data centers typically require very large internal bandwidth. To meet this requirement, a large number of parallel equivalent links are deployed in a network, such as a Fat-tree network. Partitioning such a network will affect the utilization of routing algorithm on equivalent multi-path and reduce internal network bandwidth requirements.

In the FAR routing calculation process, a Basic Routing Table (BRT) is built on local network topology leveraging the regularity of the network topologies. In addition to BRT, FAR also builds a Negative Routing Table (NRT). FAR gradually builds NRT in the process of learning network link failure information, which does not require learning a complete network fault information. FAR does not need to wait for the completion of the network convergence in the process of building these two tables. Therefore, it avoids the problem of excessive network convergence overheads in the route calculation process. In addition, FAR only needs to exchange a small amount of link change information between routers, and hence consumes less network bandwidth.

3.2. Dilemma of conventional routing methods in a large-scale network with giant number nodes of routers

There are many real world scenario where tens of thousands of nodes(or much more nodes) need to be deployed in a flat area, such as infiniband routing and switching system, high-performance computer network, and many IDC networks in China. The similar problems have been existed long ago. People have solved the problems through similar solutions, such as the traditional regular topology-based [RFC3619](#) protocol, the routing protocols of infiniband routing and switching system, and high-performance computer network routing protocol.

Infiniband defines a switch-based network to interconnect processing nodes and the I/O nodes. Infiniband can support very large scale networks, use the regularity in topology to simplify its routing algorithm, which is just the same to what we do in FAR.

Why OSPF and other conventional routing methods do not work well in a large-scale network with giant number nodes of routers?

As everyone knows, the OSPF protocol uses multiple databases, more topological exchange information (as seen in the following example) and complicated algorithm. It requires routers to consume more memory and CPU processing capability. But the processing rate of CPU on the protocol message per second is very limited. When the network expands, CPU will quickly approach its processing limits, and at this time OSPF can not continue to expand the scale of the management. The SPF algorithm itself does not thoroughly solve these problems.

On the contrary, FAR does not have the convergence time delay and the additional CPU overheads, which SPF requires. Because in the initial stage, FAR already knows the regular information of the whole network topology and does not need to periodically do SPF operation.

One of the examples of "more topological exchange information":

In the OSPF protocol, LSA floods every 1800 seconds. Especially in the larger network, the occupation of CPU and bandwidth will soon reach the router's performance bottleneck. In order to reduce these adverse effects, OSPF introduced the concept of Area, which still has not solved the problem thoroughly. By dividing the OSPF Area into several areas, the routers in the same area do not need to know the topological details outside their area. (In comparison with FAR, after OSPF introducing the concept of Area, the equivalent paths cannot be selected in the whole network scope)

OSPF can achieve the following results by Area : 1) Routers only need to maintain the same link state databases as other routers within the same Area, without the necessity of maintaining the same link state database as all routers in the whole OSPF domain. 2) The reduction of the link state databases means dealing with relatively fewer LSA, which reduces the CPU consumption of routers; 3) The large number of LSAs flood only within the same Area. But, its negative effect is that the smaller number of routers which can be managed in each OSPF area. On the contrary, because FAR does not have the above disadvantages, FAR can also manage large-scale network even without dividing Areas.

The aging time of OSPF is set in order to adapt to routing transformation and protocol message exchange happened frequently in the irregular topology. Its negative effect is: when the network does not change, the LSA needs to be refreshed every 1800 seconds to reset the aging time. In the regular topology, as the routings are fixed, it does not need the complex protocol message exchange and aging rules to reflect the routing changes, as long as LFA mechanism in the FAR is enough.

Compared with the LSVR protocol, the LSVR protocol has no special requirements for the network topology structure, however, the FAR draft is applicable to the regular topology network architecture and simplifies unnecessary processing. It is a solution proposed to greatly improve the routing efficiency of the regular network topology. The FAR solution is more efficient than the general methods such as LSVR in regular topology.

Therefore, in FAR, we can omit many unnecessary processing and the packet exchange. The benefits are fast convergence speed and much larger network scale than other dynamic routing protocol. Now there are some successful implementations of simplified routings in the regular topology in the HPC environment. Conclusion: As FAR needs few routing entries and the topology is regular, the database does not need to be updated regularly. Without the need for aging, there is no need for CPU and bandwidth overhead brought by LSA flood every

30 minutes, so the expansion of the network has no obvious effect on the performance of FAR, which is contrary to OSPF.

Comparison of convergence time: The settings of OSPF `spf_delay` and `spf_hold_time` can affect the change of convergence time. The convergence time of the network with 2480 nodes is about 15-20 seconds; while the FAR does not need to calculate the SFP, so there is no such convergence time.

These issues still exist in rapid convergence technology of OSPF, ISIS (such as I-SPF) and LSVR. The convergence speed and network scale constraint each other. FAR does not have the above problems, and the convergence time is almost negligible.

Can FRR solve these problems? IP FRR has some limitations. The establishment of IP FRR backup scheme will not affect the original topology and traffic forwarding which are established by protocol, however, we can not get the information of whereabouts and status when the traffic is switched to an alternate next hop.

3.3. Network Addressing Issues

Routers are typically configured with multiple network interfaces, each connected to a subnet. OSPF and other routing algorithms require that each interface of a router must be configured with an IP address. A large-scale data center network may contain thousands of routers and each router has dozens of network interfaces, thus, there are tens of thousands of IP addresses needed to be configured in a data center. It will be very complex to configure and manage a large number of network interfaces and will be difficult to troubleshoot network problems, then network maintenance will be costly and error-prone.

In FAR, the device position information is encoded in the IP address of the router. Each router only needs to be assigned a unique IP address according its location, which greatly solves complex network addressing issues in large-scale networks.

3.4. Big Routing Table Issues

There are a large number of subnets in the large-scale data center network. A router may build a routing entry for each subnet, and therefore the size of routing tables on each router may be very large. It will increase a router's cost and reduce the querying speed of the routing table.

FAR uses two measures to reduce the size of its routing tables: a)It builds a BRT on the regularity of the network topologies; b)It introduces a new routing table, i.e., a NRT. In this way FAR can

reduce the size of routing tables to only a few dozen routing entries.

3.5. Adaptivity Issues for Routing Algorithms

To implement efficient routing in large-scale datacenters, besides FAR, some other routing methods are proposed for some specific network architectures, such as Fat-tree and BCube. These routing methods are different (from both design and implementation viewpoints) and not compatible with the conventional routing methods, which brings big troubles to network equipment providers to develop new routers supporting various new routing methods.

FAR is a generic routing method. With slight modification, FAR method can be applied to most of regular datacenter networks. Furthermore, the structure of routing tables and querying a routing table in FAR are the same as conventional routing method. If FAR is adopted, the workload of developing a new type of router will be significantly decreased.

3.6. Virtual Machine Migration Issues

Supporting VM migration is very important for cloud-based datacenter networks. However, in order to support layer-3 routing, routing methods including OSPF and FAR require limiting VM migration within a subnet. For this paradox, the mainstream methods still utilize layer-3 routing on routers or switches, transmit packets encapsulated by IPinIP or MACinIP between hosts by tunnels passing through network to the destination access switch, and then extract original packet out and send it to the destination host.

By utilizing the aforementioned methods, FAR can be applied to Fat-tree, MatrixDCN or BCube networks for supporting VM migration in entire network.

4. The FAR Framework

FAR requires that a DCN has a regular topology, and network devices, including routers, switches, and servers, are assigned IP addresses according to their locations in the network. In other word, we can locate a device in the network according to its IP address.

FAR is a distributed routing method. In order to support FAR, each router needs to have a routing module that implements the FAR algorithm. FAR algorithm is composed of three parts, i.e., link-state learning, routing table building and routing table querying, as shown in Fig. 1.

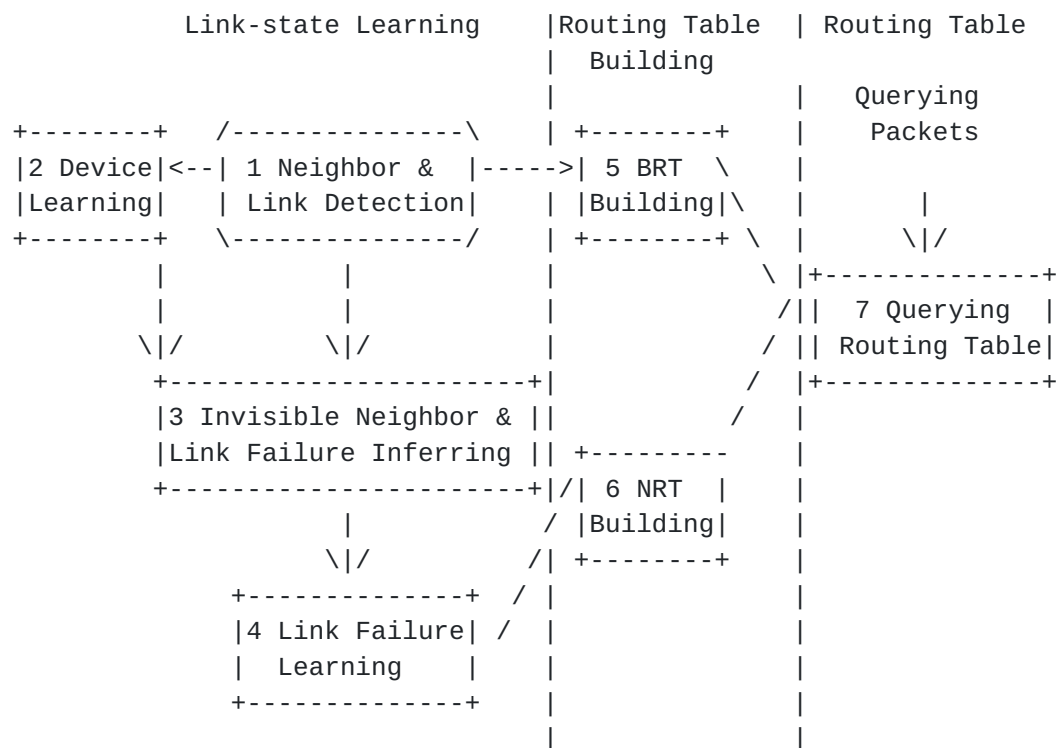


Figure 1: The FAR framework

Link-state learning is responsible for a router to detect the states of its connected links and learn the states of all the other links in the entire network. The second part builds two routing tables, a basic routing table (BRT) and an negative routing table (NRT), according to the learned link states in the first part. The third part queries the BRT and the NRT to decide a next forwarding hop for the received (ingress) packets.

5. Data Format

5.1. Data Tables

Some data tables are maintained on each router in FAR. They are:

Neighbor Device Table (NDT): To store neighbor routers and related links.

All Devices Table (ADT): To store all routers in the entire network.

Link Failures Table (LFT): To store all link failures in the entire network.

Basic Routing Table (BRT): To store the candidate routes.

Negative Routing Table(NRT): To store the avoiding routes.

The format of NDT

```
-----  
Device ID | Device IP | Port ID | Link State | Update Time  
-----
```

Device ID: The ID of a neighbor router.

Device IP: The IP address of a neighbor router.

Port ID: The port ID that a neighbor router is attached to.

Link State: The state of the link between a router and its neighbor router. There are two states: Up and Down.

Update Time: The time of updating the entry.

The format of ADT

```
-----  
Device ID | Device IP | Type | State | Update Time  
-----
```

Device ID: The ID of a neighbor router.

Device IP: The IP address of a neighbor router.

Type: The type of a neighbor router.

State: The state of a neighbor router. There are two states: Up and Down.

Update Time: The time of updating the entry.

The format of LFT

```
-----  
No | Router 1 IP | Router 2 IP | Timestamp  
-----
```

No: The entry number.

Router 1 IP: The IP address of one router that a failed link connects to.

Router 2 IP: The IP address of another router that a failed link connects to.

Timestamp: It identifies when the entry is created.

The format of BRT

```
-----  
Destination | Mask | Next Hop | Interface | Update Time  
-----
```

Destination: A destination network

Mask: The subnet mask of a destination network.

Next Hop: The IP address of a next hop for a destination.

Interface: The interface related to a next hop.

Update Time: The time of updating the entry.

The format of NRT

```
-----  
Destination| Mask| Next Hop| Interface| Failed Link No| Timestamp  
-----
```

Destination: A destination network.

Mask: The subnet mask of a destination network.

Next Hop: The IP address of a next hop that should be avoided for a destination.

Interface: The interface related to a next hop that should be avoided.

Failed Link No: A group of failed link numbers divided by "/", for example 1/2/3.

Timestamp: The time of updating the entry.

5.2. Messages

Some protocol messages are exchanged between routers in FAR.

Hello Message: This message is exchanged between neighbor routers to learn adjacency.

Device Announcement (DA): Synchronize the knowledge of routers between routers.

Link Failure Announcement (LFA): Synchronize link failures between routers.

Device and Link Request (DLR): When a router starts, it requests the knowledge of routers and links from its neighbors by a DLR message.

A FAR Message is directly encapsulated in an IP packet. The protocol field of IP header indicates an IP packet is an FAR message. The protocol of IP for FAR should be assigned by IANA.

The four types of FAR messages have same format of packet header, called FAR header (as shown in Figure 2).

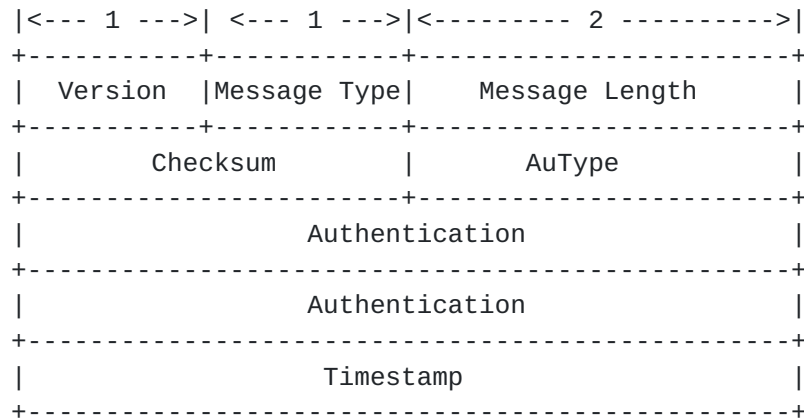


Figure 2: The format of FAR header

Version: FAR version

Message Type: The type of FAR message.

Packet Length: The packet length of the total FAR message.

Checksum: The checksum of an entire FAR message.

AuType: Authentication type. 0: no authentication, 1: Plaintext Authentication, 2: MD5 Authentication.

Authentication: Authentication information. 0: undefined, 1: Key, 2: key ID, MD5 data length and packet number. MD5 data is appended to the backend of the packet.

AuType and Authentication can refer to the definition of OSPF packet.

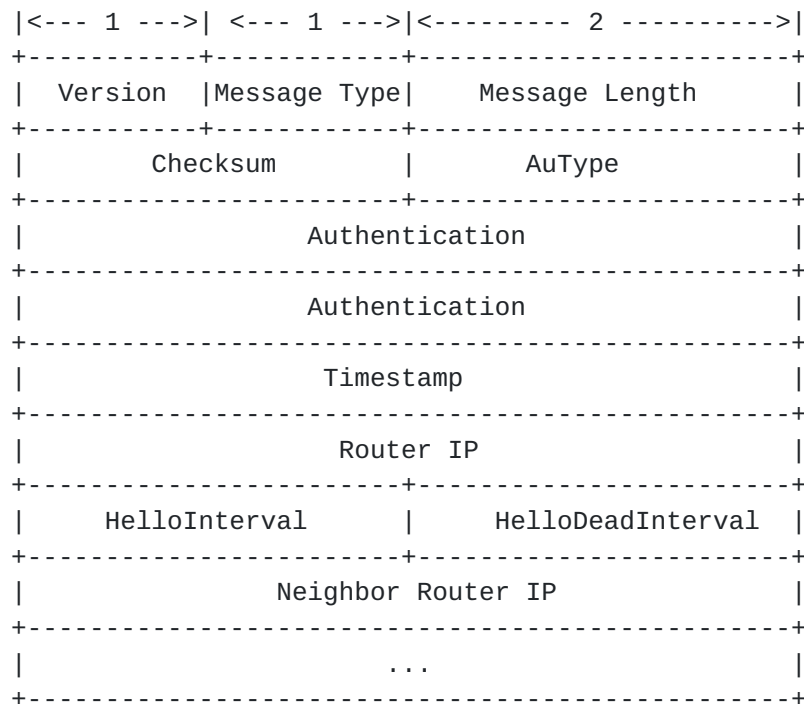


Figure 3: The Format of Hello Messages

For Hello messages, the Message Type in FAR header is set to 1. Besides FAR header, a Hello message (Fig. 3) requires the following fields:

Router IP: The router IP address.

HelloInterval: The interval of sending Hello messages to neighbor routers.

RouterDeadInterval: The interval to set a neighbor router dead (out-of-service). If in the interval time, a router doesn't receive a Hello message from its neighbor router, the neighbor router is treated as dead.

Neighbor Router IP: The IP address of a neighbor router. All the neighbor router's addresses should be included in a Hello message.

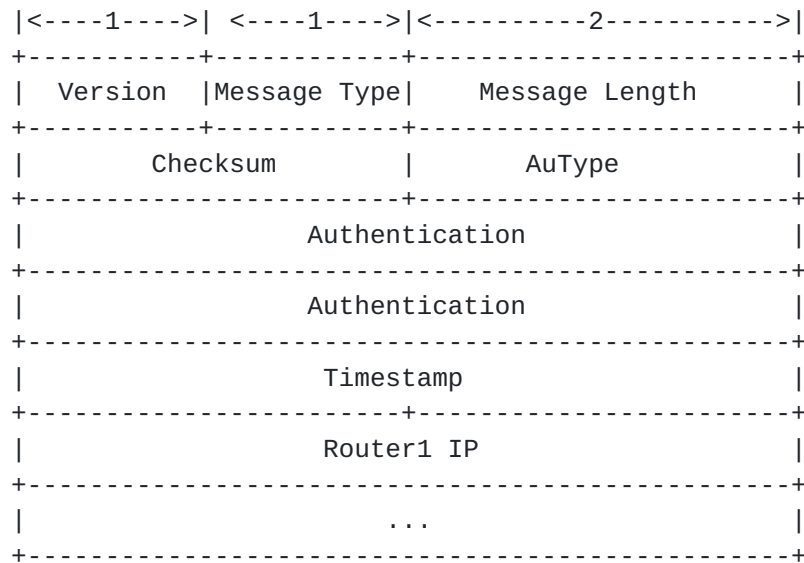


Figure 4: The Format of DA Messages

For DA messages(Fig. 4), the Message Type in FAR header is set to 2. Besides FAR header, a DA message includes IP addresses of all the announced routers.

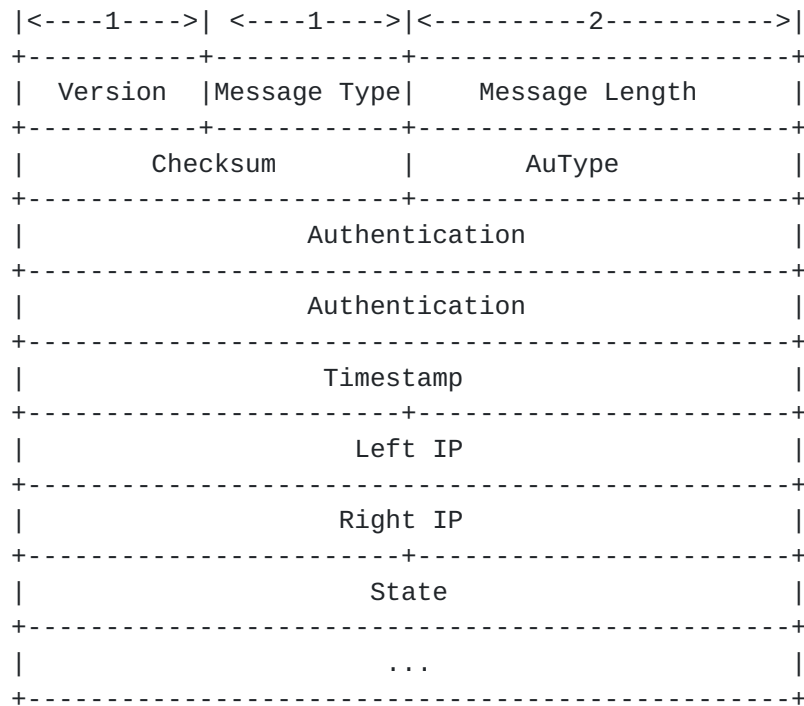


Figure 5: The Format of LFA Messages

For LFA messages(Fig. 5), the Message Type in FAR header is set to 3. Besides FAR header, a LFA message includes all the announced link failures.

Left IP: The IP address of the left endpoint router of a link.

Right IP: The IP address of the right endpoint router of a link.

State: Link state. 0: Up, 1: down

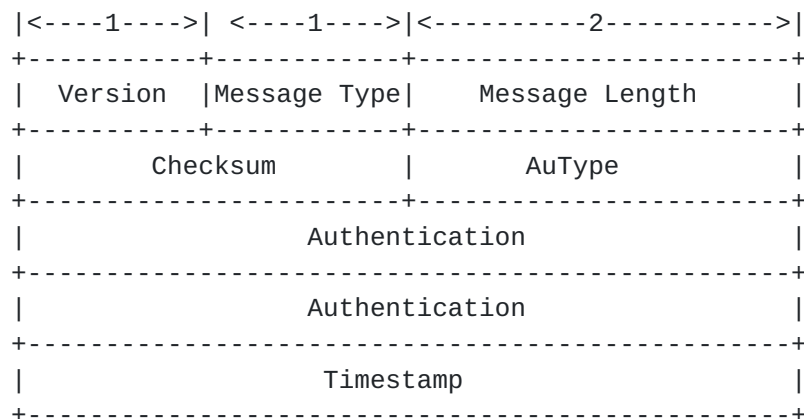


Figure 6: The Format of DLR Messages

For DLR messages(Fig. 6), the Message Type in FAR header is set to 1.Except for FAR header, DLR has no additional fields.

6. FAR Modules

6.1. Neighbor and Link Detection Module(M1)

M1 is responsible for sending and receiving Hello messages, and detecting directly-connected links and neighbor routers. Each Hello message is encapsulated in a UDP packet. M1 sends Hello messages periodically to all the active router ports and receives Hello messages from its neighbor routers. M1 detects neighbor routers and directly-connected links according to received Hello Messages and stores these neighbors and links into a Neighbor Devices Table (NDT). Additionally, M1 also stores neighbor routers into an All Devices Table (ADT).

6.2. Device Learning Module(M2)

M2 is responsible for sending, receiving, and forwarding device announcement (DA) messages, learning all the routers in the whole network, and deducing faulted routers. When a router starts, it sends a DA message announcing itself to its neighbors and a DLR message requesting the knowledge of routers and links from its neighbors. If M2 module of a router receives a DA message, it checks whether the router encapsulated in the message is in an ADT. If the router is not in the ADT, M2 puts this router into the ADT and forwards this DA message to all the active ports except for the incoming one, otherwise, M2 discards this message directly. If M2 module of a router receives a DLR message, it replies a DA message that encapsulates all of the learned routers.

6.3. Invisible Neighbor and Link Failure Inferring Module(M3)

M3 is responsible for inferring invisible neighbors of the current router by means of the ADT. If the link between a router A and its neighbor B breaks, which results in that M1 module of A cannot detect the existence of B, then B is an invisible neighbor of A. Since a device's location is coded into its IP address, it can be judged whether two routers are adjacent, according to their IP addresses. Based on this idea, M3 infers all of the invisible neighbors of the current router and the related link failures. The results are stored into a NDT. Moreover, link failures also are added into a link-failure table (LFT). LFT stores all of the failed links in the entire network.

6.4. Link Failure Learning Module(M4)

M4 is responsible for sending, receiving and forwarding link failure announcement (LFA) and learning all the link failures in the whole network. M4 broadcasts each newly inferred link failure to all the routers in the network. Each link failure is encapsulated in a LFA message and one link failure is broadcasted only once. If a router receives a DLR request from its neighbor, it will reply a LFA message that encapsulates all the learned link failures through M4 module. If M4 receives a LFA message, it checks whether the link failure encapsulated in the message is in a LFT by comparing two link ends and timestamp. If the link failure is not in the LFT or timestamp is different, M4 puts this link failure into the LFT (or update timestamp only) and forwards this LFA message to all the active ports except for the incoming one, otherwise, M4 discards this message directly.

There is a special case a router will rebroadcast a link failure. If a router receives a data packet and must forward the packet going ahead to destination through a failed link, it means some previous router should avoid this failed link according to its NRT but it doesn't. In this case, maybe the previous router missed the LFA message of the link failure due to some uncertain reasons. So the forwarding router rebroadcasts the LFA message.

6.5. BRT Building Module(M5)

M5 is responsible for building a BRT for the current router. By leveraging the regularity in topology, M5 can calculate the routing paths for any destination without the knowledge of the topology of whole network, and then build the BRT based on a NDT. Since the IP addresses of network devices are continuous, M5 only creates one route entry for a group of destination addresses that have the same network prefix by means of route aggregation technology. Usually,

the size of a BRT is very small. The detail of how to build a BRT is described in [section 5](#).

6.6. NRT Building Module(M6)

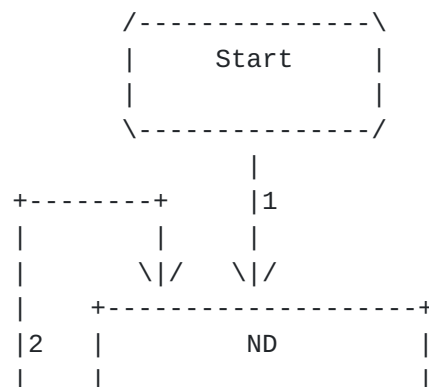
M6 is responsible for building a NRT for the current router. Because M5 builds a BRT without considering link failures in network, the routing paths calculated by the BRT cannot avoid failed links. To solve this problem, a NRT is used to exclude the routing paths that include some failed links from the paths calculated by a BRT. M6 calculate the routing paths that include failed links and stored them into the NRT. The details of how to build a NRT is described in [section 5](#).

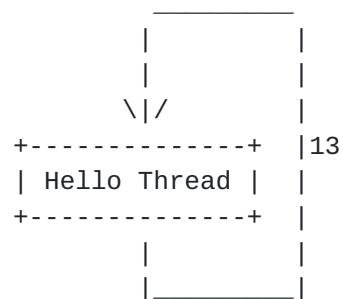
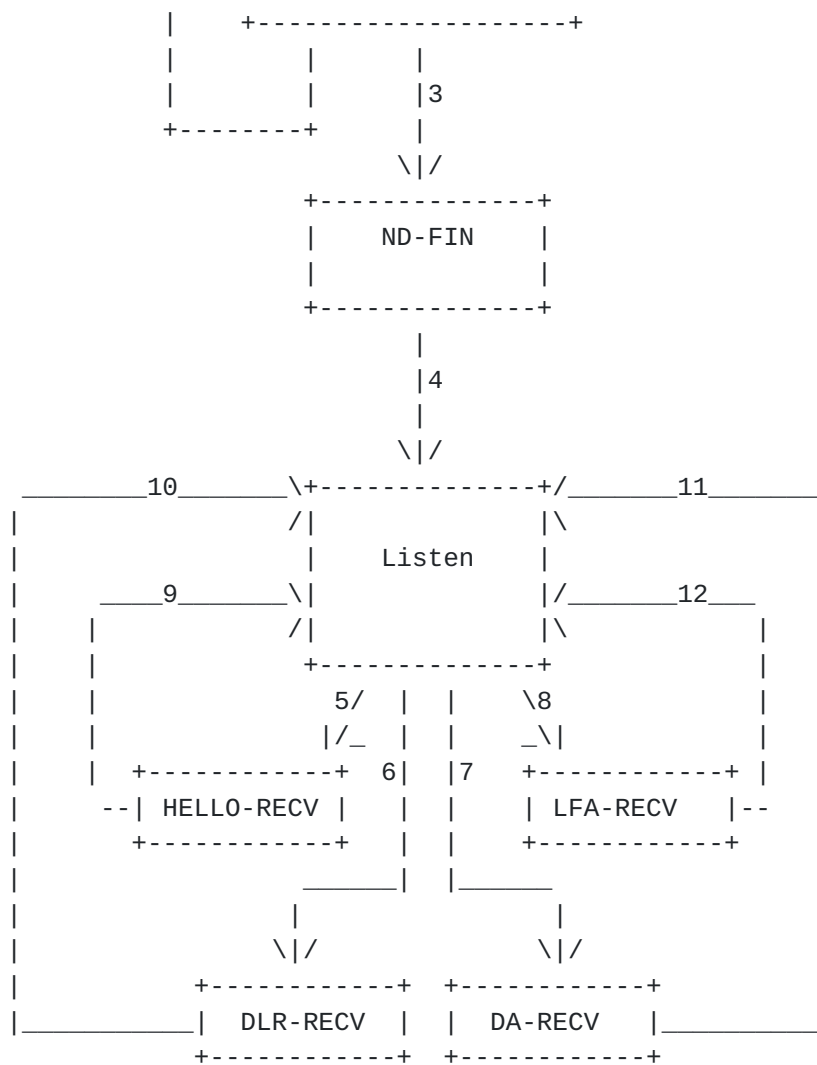
6.7. Routing Table Lookup(M7)

M7 is responsible for querying routing tables and selecting the next hop for forwarding the packets. Firstly, M7 takes the destination address of a forwarding packet as a criterion to look up route entries in a BRT based on longest prefix match. All of the matched entries are composed of a candidate hops list. Secondly, M7 look up negative route entries in a NRT taking the destination address of the forwarding packet as criteria. This lookup is not limited to the longest prefix match, any entry that matches the criteria would be selected and composed of an avoiding hops list. Thirdly, the candidate hops minus avoiding hops are composed of an applicable hops list. At last, M7 sends the forwarding packet to any one of the applicable hops. If the applicable list is empty, the forwarding packet will be dropped.

7. How a FAR Router Works

Figure 7 shows how a FAR router works by its FSM.





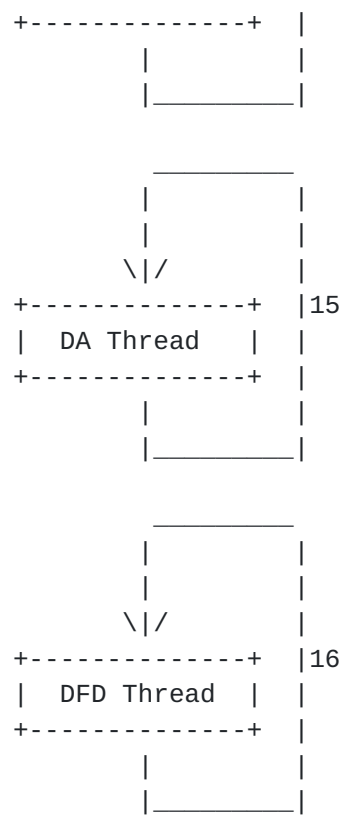


Figure 7: The Finite State Machine of FAR Router

- 1) When a router starts up, it starts a Hello thread and then starts ND (neighbor detection) timer (3 seconds). Next the router goes into ND (neighbor detection) state.
- 2) In the ND state, if a router received a Hello message, then it performs a Hello-message processing and goes back to the ND state.
- 3) When the ND timer is over, a router goes into ND-FIN (neighbor detection finished) state.
- 4) A router starts the LFD (link failure detection) thread and DFD (device failure detection) state, and sends DA message and DLR message to all of its active ports. Then the router goes into Listen state.
- 5) If a router receives a Hello message, then goes into HELLO-RECV state.
- 6) If a router receives a DLR message, then goes into DLR-RECV state.
- 7) If a router receives a DA message, then goes into DA-RECV state.
- 8) If a router receives a LFA message, then goes into LFA-RECV state.
- 9) A router performs the Hello-message processing. After that, it goes back to Listen state.
- 10) A router performs the DLR-message processing. After that, it goes back to Listen state.
- 11) A router performs the DA-message processing. After that, it goes back to Listen state.

- 12) A router performs the LFA-message processing. After that, it goes back to Listen state.
- 13) Hello thread produces and sends Hello messages to all its ports periodically.
- 14) LFD thread calls link-failure-detection processing to check link failures in all links periodically
- 15) DA thread produces and sends DA messages periodically (30 minutes).
- 16) When DFD thread starts up, it sleep a short time (30 seconds) to wait for a router learning all the active routers in the network. Then the thread calls the device-failure-detection processing to check device failures periodically (30 minutes).

8. Compatible Architecture

As a generic routing protocol, FAR can be run in various DCNs with regular topology. Up to now, we have implemented the FAR protocol for 4 types of DCN, including Fat-tree, BCube, MatrixDCN and Diamond.

For different network architectures, most processing of FAR is same besides calculation of routing tables. BRT routing tables are calculated based on Hello messages and NRT routing tables are calculated based on LFA messages in FAR. To extend FAR to support a new network architecture, only processing of Hello and LFA messages need providing to build BRT and NRT routing tables.

In this protocol, FAR can support maximally 12 network architectures and at least support 1 built-in network architecture, such as Fat-tree, BCube and MatrixDCN, etc. Each network architecture is assigned a unique number from 1 to 12. For example, if the 1 built-in architectures are assigned 1, and other customized architectures are assigned 2 to 12.

- 1: Fat-tree
- 2: BCube
- 3: MatrixDCN.
- 4: xxx.
-
- 12: xxx.

9. Application Example

In this section, we take a Fat-tree network(Fig. 7) as an example to describe how to apply FAR routing. Since M1 to M4 are very simple, we only introduce how the modules M5, M6, and M7 work in a Fat-tree network.

A Fat-tree network is composed of 4 layers. The top layer is core layer, and the other layers are aggregation layer, edge layer and

server layer. There are k pods, each one containing two layers of $k/2$ switches. Each k -port switch in the edge layer is directly connected to $k/2$ hosts. The remaining $k/2$ ports are connected to $k/2$ of the k -port switches in the aggregation layer. There are $(k/2)^2$ k -port core switches. Each core switch has one port connected to each of the k pods.

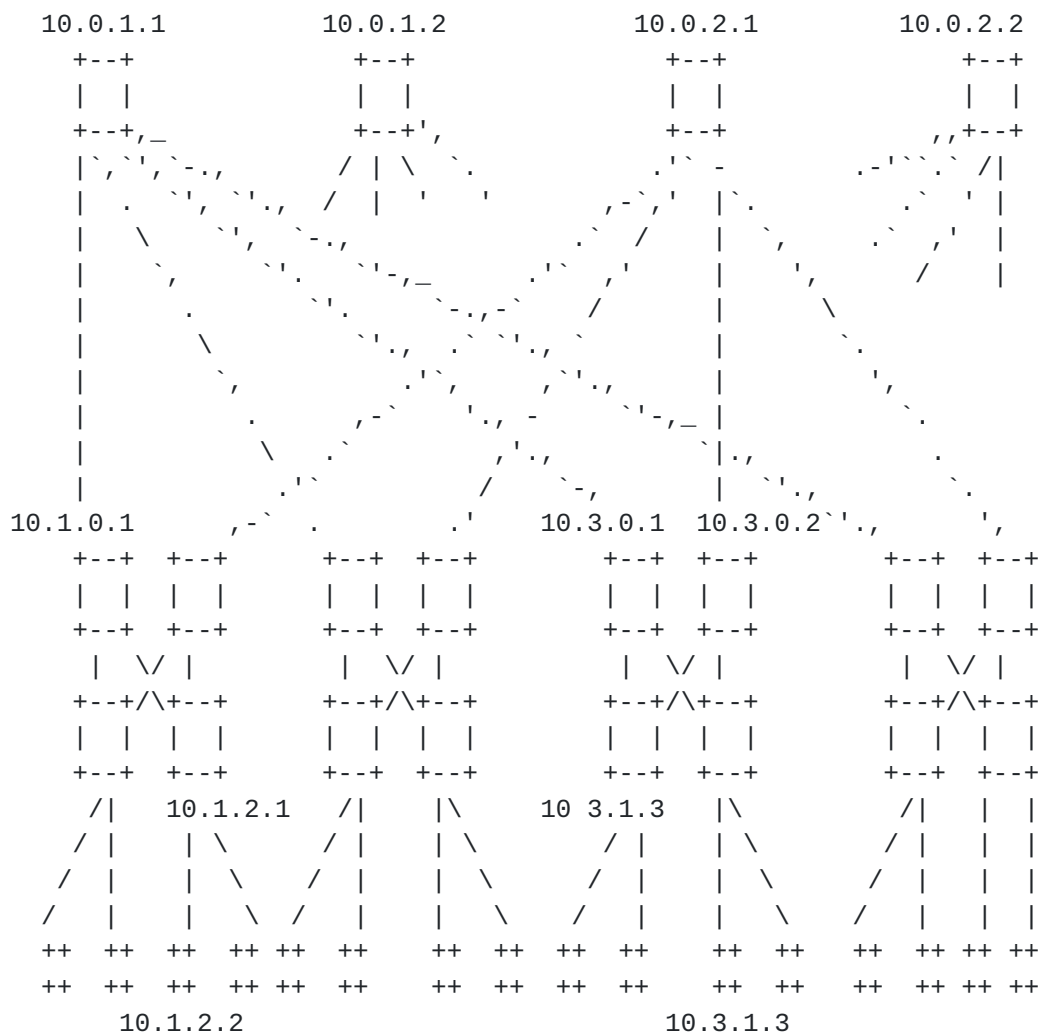


Figure 8: Fat-tree Network

Aggregation switches are given addresses of the form $10.\text{pod}.0.\text{switch}$, where pod denotes the pod number, and switch denotes the position of that switch in the upper pod (in $[1, k/2]$). Edge switches are given addresses of the form $10.\text{pod}.\text{switch}.1$, where pod denotes the pod number, and switch denotes the position of that switch in the lower pod (in $[1, k/2]$). The core switches are given addresses of the form $10.0.j.i$, where j and i denote that switch's coordinates in the

$(k/2)^2$ core switch grid (each in $[1, (k/2)]$, starting from top-left). The address of a host follows the pod switch to which it is connected to; hosts have addresses of the form: 10.pod.switch.ID, where ID is the host's position in that subnet (in $[2, k/2+1]$, starting from left to the right).

9.1. BRT Building Procedure

By leveraging the topology's regularity, every switch clearly knows how it forwards a packet. When a packet arrives at an edge switch, if the destination of the packet lies in the same subnet with the switch, then the switch directly forwards the packet to the destination server through layer-2 switching. Otherwise, the switch forwards the packet to any of aggregation switches in the same pod. When a packet arrives at an aggregation switch, if the destination of the packet lies in the same pod, the switch forwards the packet to the corresponding edge switch. Otherwise, the switch forwards the packet to any of core switches that it is connected to. If a core switch receives a packet, it forwards the packet to the corresponding aggregation switch that lies in the destination pod.

The forwarding policy discussed above is easily expressed through a BRT. The BRT of an edge switch, such as 10.1.1.1, is composed of the following entries:

Destination/Mask	Next hop
10.0.0.0/255.0.0.0	10.1.0.1
10.0.0.0/255.0.0.0	10.1.0.2

The BRT of an aggregation switch, such as 10.1.0.1, is composed of the following entries:

Destination/Mask	Next hop
10.1.1.0/255.255.0	10.1.1.1
10.1.2.0/255.255.255.0	10.1.2.1
10.0.0.0/255.0.0.0	10.0.1.1
10.0.0.0/255.0.0.0	10.0.1.2

The BRT of a core switch, such as 10.0.1.1, is composed of the following entries:

Destination/Mask	Next hop
10.1.0.0/255.255.0.0	10.1.0.1
10.2.0.0/255.255.0.0	10.2.0.1
10.3.0.0/255.255.0.0	10.3.0.1
10.4.0.0/255.255.0.0	10.4.0.1

9.2. NRT Building Procedure

The route entries in an NRT are related with link and node failures. We summarize all types of cases into three (3) catalogs.

9.2.1. Single Link Failure

In Fat-tree, Links can be classified as 3 types by their locations: 1) servers to edge switches; 2) edge to aggregation switches; 3) aggregation to core switches. Link failures between servers to edge switches only affect the communication of the corresponding servers and don't affect the routing tables of any switch, so we only discuss the second and third type of links failures.

Edge to Aggregation Switches

Suppose that the link between an edge switch, such as 10.1.2.1 (A), and an aggregation switch, such as 10.1.0.1(B), fails. This link failure may affect 3 types of communications.

- o Sources lie in the same subnet with A, and destinations do not. In this case, the link failure will only affect the routing tables of A. As this link is attached to A directly, A only needs to delete the route entries whose next hop is B in its BRT and add no entries to its NRT when A's M6 module detect the link failure.

- o Destinations lie in the same subnet with A, and sources lie in another subnet of the same pod. In this case, the link failure will affect the routing tables of all the edge switches in the same pod except for A. When an edge switch, such as 10.1.1.1, learns the link failure, it will add a route entry to its NRT:

Destination/Mask	Next hop
10.1.2.0/255.255.255.0	10.1.0.1

- o Destinations lie in the same subnet with A, sources lie in another pod. In this case, the link failure will affect the routing tables of all the edge switches in the other pods. When an edge switch in one other pod, such as 10.3.1.1, learns the link failure, because all the routings that pass through 10.3.0.1 to A will certainly pass

through the link between A and B, 10.3.1.1 need add a route entry to its NRT:

Destination/Mask	Next hop
10.1.2.0/255.255.255.0	10.3.0.1

Aggregation to Core Switches

Suppose that the link between an aggregation switch, such as 10.1.0.1 (A), and a core switch, such as 10.0.1.2(B), fails. This link failure may affect 2 types of communications.

- o Sources lie in the same pod (pod 1) with A, and destinations lie in the other pods. In this case, the link failure will only affect the routing tables of A. As this link is attached to A directly, A only need to delete the route entries whose next hop is B in its BRT and add no entries to its NRT when A's M6 module detect the link failure.

- o Destinations lie in the same pod (pod 1) with A, and sources lie in another pod. In this case, the link failure will affect the routing tables of all the aggregation switches in other pods except for pod 1. When an aggregation switch in one other pod, such as 10.3.0.1, learns the link failure, because all the routings that pass through 10.0.1.2 to the pod 1 where A lies will certainly pass through the link between A and B, 10.3.0.1 need add a route entry to its NRT:

Destination/Mask	Next hop
10.1.0.0/255.255.0.0	10.0.1.2

9.2.2. A Group of Link Failures

If all the uplinks of an aggregation switch fail, then this switch cannot forward packets, which will affect the routing of every edge switches. Suppose that all the uplinks of the node A (10.1.0.1) fail, it will affect two types of communications.

- o Sources lie in the same pod (pod 1) with A, and destinations lie in the other pods. In this case, the link failures will affect the routing of the edge switches in the Pod of A. To avoid the node A, each edge switch should remove the route entry "10.0.0.0/255.0.0.0 10.1.0.1" in which the next hop is the node A.

- o Destinations lie in the same pod (pod 1) with A, and sources lie in other pods. In this case, the link failures will affect the routing of edge switches in other pods. For example, if the edge switch 10.3.1.1 communicates with some node in the pod of A, it should avoid

the node 10.3.0.1, because any communication through 10.3.0.1 to the pod of A will pass through the node A. So a route entry should be added to 10.3.1.1:

Destination/Mask	Next hop
10.1.0.0/255.255.0.0	10.3.0.1

9.2.3. Node Failures

At last, we discuss the effect of node failures to a NRT. There are 3 types of node failures: the failure of edge, aggregation and core switches.

- o An edge switch fails. The failure doesn't affect the routing table of any switch.

- o A core switch fails. Only when all the core switches connected to the same aggregation switch fail, they will affect the routing of other switches. This case is equal to the case that all the uplinks of an aggregation switch fail, so the process of link failures can cover it.

- o An aggregation switch fails. This case is similar to the case that all the uplinks of an aggregation switch fail. It affects the routing of edge switches in other pods, but doesn't affect the routing of edge switches in pod of the failed switch. The process of this failure is same to the second case in [section 6.2.2](#).

9.3. Routing Procedure

FAR decides a routing by looking up its BRT and NRT. We illuminate the routing procedure by an example. In this example, we suppose that the link between 10.3.1.1 and 10.3.0.2 and the link between 10.1.2.1 and 10.1.0.2 have failed. Then we look into the routing procedure of a communication from 10.3.1.3 (source) to 10.1.2.2 (destination).

Step 1: The source 10.3.1.3 sends packets to its default router 10.3.1.1

Step 2: The routing of 10.3.1.1.

1) Calculate candidate hops

10.3.1.1 looks up its BRT and gets the following matched entries:

Destination/Mask	Next hop
10.0.0.0/255.0.0.0	10.3.0.1

So the candidate hops = {10.3.0.1}

2) Calculate avoiding hops

Its NRT is empty, so the set of avoiding hop is empty too.

3) Calculate applicable hops

The applicable hops are candidate hops minus avoiding hops, so:

The applicable hops = {10.3.0.1}

4) Forward packets to 10.3.0.1

Step 3: The routing of 10.3.0.1

1) Calculate candidate hops.

10.3. 0.1 looks up its BRT and gets the following matched entries:

Destination/Mask	Next hop
10.1.0.0/255.255.0.0	10.0.1.1
10.1.0.0/255.255.0.0	10.0.1.2

So the candidate hops = {10.0.1.1, 10.0.1.2}

2) Calculate avoiding hops

Destination/Mask	Next hop
10.1.0.0/255.255.0.0	10.0.1.2

So the avoiding hops = {10.0.1.2}

3) Calculate applicable hops

The applicable hops are candidate hops minus avoiding hops, so:

The applicable hops = {10.0.1.1}

4) Forward packets to 10.0.1.1

Step 4: 10.0.1.1 forwards packets to 10.1.0.1 by looking up its routing tables.

Step 5: 10.1.0.1 forwards packets to 10.1.2.1 by looking up its routing tables.

Step 6: 10.1.2.1 forwards packets to the destination 10.1.2.2 by layer-2 switching.

9.4. FAR's Performance in Large-scale Networks

FAR has good performance to support large-scale networks. In this section, we take a Fat-tree network composed of 2,880 48-port switches and 27,648 servers as an example to show FAR's performance.

9.4.1. The number of control messages required by FAR

FAR exchanges a few messages between routers and only consumes a little network bandwidth. Tab. 1 shows the required messages in the example Fat-tree network.

Table 1: Required messages in a Fat-tree network.

Message Type	Scope	size(bytes)	Rate	Bandwidth
Hello	adjacent switches	less than 48	10 messages/sec	less than 4 kbps
DLR	adjacent switches	less than 48	(1)	48bytes
DA	entire network	less than 48	(2)	1.106M
LFA	entire network	less than 48	(3)	48 bytes

(1) Produce one when a router starts

(2) The number of switches(2,880) in a period

(3) Produce one when a link fails or recovers

9.4.2. The Calculating Time of Routing Tables

A BRT is calculated according to the states of its neighbor routers and attached links. An NRT is calculated according to device and link failures in the entire network. So FAR does not calculate network topology and has no problem of network convergence, which greatly reduces the calculating time of routing tables. The detection and spread time of link failures is very short in FAR. Detection time is up to the interval of sending Hello message. In FAR, the interval is set to 100ms, and a link failure will be detected in 200ms. The spread time between any pair of routers is

less than 200ms. If a link fails in a data center network, FAR can detect it, spread it to all the routers, and calculate routing tables in no more than 500ms.

9.4.3. The Size of Routing Tables

For the test Fat-tree network, the sizes of BRTs and NRTs are shown in Tab. 2.

Table 2: The size of routing tables in FAR

Routing Table	Core Switch	Aggregation Switch	Edge Switch
BRT	48	48	24
NRT	0	14	333

The BRT's size at a switch is determined by the number of its neighbor switches. In the example network, a core switch has 48 neighbor switches (aggregation switch), so it has 48 entries in its BRT. Only aggregation and edge switches have NRTs. The NRT size at a switch is related to the number of link failures in the network. Suppose that there are 1000 link failures in the example network, the number of failed links is 1.2% of total links, which is a very high failure ratio. We suppose that link failures are uniformly distributed in the entire network. The NRT size at an edge switch is about 333 and the NRT size of an aggregation switch is about 14 in average.

10. Security Considerations

The security considerations will be discussed in a future version of this document.

11. Conclusions

This draft introduces FAR protocol, a generic routing method and protocol, for data centers that have a regular topology. It uses two routing tables, a BRT and an NRT, to store the normal routing paths and the forbidden (to-be-avoided) routing paths, respectively. This makes the FAR protocol very simple and efficient. The sizes of these two tables are very small. Usually, a BRT has only several tens of entries and an NRT has only several or about a dozen entries.

12. Acknowledgments

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