Network work group Internet Draft Intended status: Informational Expires: April 2009

Call Parameter Negotiation with GMPLS Calls draft-xia-ccamp-gmpls-call-application-00.txt

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Abstract

This document defines the use of Generalized Multi-Protocol Label Switching (GMPLS) Calls for parameter negotiation in Automatically Switched Optical Networks (ASON) and Wavelength Switched Optical Networks (WSON). The intention of the document is to provide a reference for the authors of future documents to understand the application of GMPLS Calls. <Lastname>

Conventions used in this document

The key words "MUST", "MUST NOT", "REQUIRED", "SHALL", "SHALL NOT", "SHOULD", "SHOULD NOT", "RECOMMENDED", "MAY", and "OPTIONAL" in this document are to be interpreted as described in <u>RFC-2119</u> [<u>RFC2119</u>].

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1. Introduction

The concept of a Generalized Multi-Protocol Label Switching (GMPLS) Call is introduced in [RFC 4974]. A Call is an agreement between endpoints possibly in cooperation with the nodes that provide access to the network. It is used to facilitate and manage a set of Connections (that is, Label Switching Paths - LSPs) that provide endto-end data services. It may be established and maintained independently of the Connections that it supports. Call setup may include capability exchange, policy, authorization, and security. This document defines the use of Call for parameter negotiation with specific reference to its use in Automatically Switched Optical Networks (ASON) and Wavelength Switched Optical Networks (WSON). The intention of the document is to provide a reference for the authors of future documents to understand the application of GMPLS Calls.

<u>2</u>. Problem Statement

A Call is an agreement between endpoints possibly in cooperation with the nodes that provide access to the network. Call setup may include capability exchange, policy, authorization, and security. In this document, we will describe the use of GMPLS Call in parameter negotiation.

In some scenarios, service attributes have an effect on connection setup. Because equipment from different vendors may have different capabilities, a connection SHOULD only transit the nodes that all support the attributes required by a connection. IGP extension could solve this problem by advertising the attributes and capabilities of all network nodes, but this would increase the burden on the control plane. It is a good choice to introduce the function of parameter negotiation into GMPLS Calls to deal with this kind of problem. In the following subsection, two scenarios are presented.

2.1. Connection-Adaptation Negotiation for Ethernet Service

For Ethernet services over a transport network there is a key step to adapt Ethernet frames into transport channels. This must be done between the server edge nodes. The adaptation policy between ingress and egress edge nodes must be consistent. These adaptation policies include:

- Encapsulation protocol at the edge node. This is responsible for packet encapsulation, framing and rate adaptation. Examples include GFP (Generic Framing Procedure), LAPS (Link Access Procedure for SDH), HDLC (High Level Data Link Control protocol), etc.
- 2) Connection type and connection number used by the edge node. There are standard Contiguous Concatenation and Virtual Concatenation (VCAT) schemes in SDH networks. The maximum connection number of concatenation is different for different devices and different signals when VCAT is used. So it is necessary to negotiate the parameters of VCAT. This is described in [VCAT-LCAS].
- 3) Flow control. When traffic increases in a burst, flow control can be enabled. The ingress edge node can negotiate with the egress edge node whether to start flow control in this case, and how to apply the necessary control.

Parameter negotiation

All of these adaptation policies can be configured through the Management Plane. However, in the case of a large number of services, it is hard to perform fault localization when a configuration error has occurred. So it is more flexible to introduce dynamic parameter negotiation into this service. [RFC 4974] allows the Call and Connection to be isolated so that the Connection can be established with the correct connection-adaptation parameters according to the result of parameter negotiation on the Call.

For example, see the following figure, Figure 1. R1 and R2 are client nodes connected to the ASON via Ethernet interfaces. N1 and N6 are service access points. When R1 sends a Call request to N1 for Ethernet service, N1 includes the local capabilities for connectionadaptation to the Call as request parameters. For example, supporting GFP/LAPS, supporting VC-4-xc (x=1/4/16), supporting VCAT/LCAS, supporting VC-4-xv(x=1-7) and the relevant connecting address. When N6 receives the Call containing the connection-adaptation parameters, it checks local capabilities and applies local policies. In the Call response message, N6 will put the mapped capability as connectionadaptation parameters. If no mapped capability can be found, then N6 will reject the Call and return corresponding reason.



Figure 1: A Simple ASON Network

2.2. Service Parameter Negotiation in WSON

OTU is an important technology used to perform standard lambda conversion in WDM systems. It exists in OTM and REG.

Coded Modulation is a key technique in long distance and high speed Optical Transmission Systems. As different codes have distinct Parameter negotiation

capabilities against noise, dispersion and non-linear distortion, the maximum transmission distance will be extended without redundant devices if an appropriate code is selected. Currently, OOK (On-Off Keying Modulation), PSK (Phase Shift Keying Modulation) and PoISK (Polarization-shift keying Modulation) are the most common modulation techniques. In the establishment of a light path, it is necessary to ensure that the Coded Modulation is consistent at each OTU.

FEC is a technique to improve the system performance and reduce the cost of the system and extend the transmission distance by adding redundant error-correcting code to transmission code-sequence and thus reduce the SNR (Signal Noise Ratio) demand at receiver. In-band FEC and simple out-band FEC are used in general WDM systems. In ULH (Ultra-Long Haul) system, EFEC (Enhanced FEC) and SuperFEC are used to achieve higher coding-gain. OTU with different FECs can not understand each other. In-band FEC and simple out-band FEC have now been standardized. Vendors MAY have different code in EFEC and SuperFEC. Only the same code used in OTU can the service be established.

For the reasons stated above, it is necessary to verify and negotiate the attributes of Coded Modulation, FEC mode and code. Otherwise a connection can be established with enough resource, but be unable to bear service.

Some of these service attributes in OTU can be modified by configuration. For example, the port can be configured to disable FEC, or enable standard FEC, or EFEC. Generally, the light path is computed by the control plane in WSON, and it is not suitable to do the configuration manually. So it is necessary to add a key step during path establishment in WSON to negotiate and configure the service attributes.

<u>3</u>. Process of negotiation

The process for Call parameter negotiation SHOULD comply with the Call procedures which are described in [RFC4974]. The node that initiates the call puts the parameters that need to be negotiated in a CALL_Attributes object [MLN-EXT] in the Notify message that signals the Call request. It also lists all parameters and corresponding value that it supports.

Some parameters are negotiated between ingress and egress, while others should be negotiated among all domain border nodes in the path. Which kind of negotiation is selected is out of scope in the document. When a node receives a call request Notify message including a CALL_Attributes object with a parameter that needs to be negotiated, it checks whether any of the values listed are supported.

- o If none of the values is supported, then the receiver MUST reject the call and generate a Notify message in response.
- o If only parts of the values are not supported, then the receiver can accept the call and modify the parameter by deleting the values not supported. The remaining values are returned in the Notify message that accepts the call.
- o If all the values are supported, then the parameters are not modified and are returned in the Notify message that accepts the call.

When the call setup is complete, the ingress node will receive the parameters that are supported by all nodes that participate in call setup. It can select the preferred values with which to setup the LSP.

<u>4</u>. Example of required information for negotiation

This section describes the required information for parameter negotiation for the problem presented above.

4.1. CONNECTION_ADAPTER information

The CONNECTION_ADAPTER information, which is suggested to be a subobject of CALL_Attributes object, is introduced to support negotiation for Ethernet connection and adaptation during Call setup. It MAY be included in a Notify message used for Call setup. This optional information includes the link-local preference of connection and adaptation for Ethernet service. The Call-initiating node MAY add this information to a Notify message presenting the transport parameter. Receiving this message, the Call-terminating node checks the CONNECTION_ADAPTER information and match with local policy then return its choice also in the CONNECTION_ADAPTER information.

The contents of the CONNECTION_ADAPTER information is defined as a series of variable-length data items called sub-objects. The sub-object format is defined as follows:

4.1.1. FRAMING Sub-object

FRAMING Sub-object indicates the encapsulation protocol that the Call-initiating node (or Call-terminating node) preferred.

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This Sub-object has the following format:

Type = TBD, Length = 4

The following flags are currently defined. All other values are reserved.

G (GFP - 1bit): When this flag is set, it means that the node supports GFP encapsulation.

L (LAPS - 1bit): When this flag is set, it means that the node support LAPS encapsulation.

Other flags are reserved and MUST be set to zero.

4.1.2. VCAT Sub-object

The information related to VCAT is already defined in VCAT TLV object in [<u>VCAT-LCAS</u>] and the VCAT TLV object included in the CALL_Attributes object implies that the initiating node supports VCAT capability.

4.2. SERVICE_ATTRIBUTE information

The SERVICE_ATTRIBUTE information, which is suggested to be a subobject of CALL_Attributes object, is introduced to support negotiation for the service attributes of OTU during Call setup such attributes include service type, Coded Modulation, FEC mode and code. It MAY be included in a Notify message used for Call setup. This optional information includes the preference attribute of local OTU. Call-initiating node MAY add this information to a Notify message presenting the transport parameter of the OTU on OTM. Receiving this message, OTU on REG and OTM checks the SERVICE_ATTRIBUTE information and match with local policy then modify the information according to its choice. If the last OTU has matched service attribute, then returned Call message presents the negotiated parameter. If one of the OTU has some service attribute no matched, then return failed message. Parameter negotiation

The contents of the SERVICE_ATTRIBUTE information is defined as a series of variable-length data items called sub-objects. The sub-object format is defined as follows:

4.2.1. CODE Sub-object

This Sub-object has the following format:

Type = TBD, Length = 4

0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1 4 5 6 7 8 8 7 8 9 0 1 4 5 6 7 8 8 7 8 8 7 8 8 7 8 8 7 8 8 7 8 8 7 8 8 7 8 8 7 8 8

OOK mode (On-Off Keying): 8it. The following flags for OOK are currently defined. All other values are reserved.

N - NRZ, Non Return to Zero Modulation

R - RZ, Return to Zero Modulation

PSK mode (Phase Shift Keying): 8it. The following flags for PSK are currently defined. All other values are reserved.

E - 8-DPSK, Differential 8-level Phase Shift Keying Modulation

Q - DQPSK, Differential Quadrature Phase Shift Keying Modulation

D - DPSK, Differential Phase Shift Keying Modulation

PoISK mode (Polarization-shift keying Modulation): 8it. The following flag for PoISK is currently defined. All other values are reserved.

D - DpolSK, Duobinary Polarization-shift keying

The code Sub-object is the Coded Modulation method that supported by OTU. The head OTU node initiates a call and set all code it supported. The following OTU node along the path check the code, if some code can not be support, then the corresponding bit will be cleared in the Sub-object. If no one bit is set, it means the call failed.

4.2.2. FEC Sub-object

This Sub-object has the following format:

Type = TBD, Length = 8

0 3 1 2 0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1 Type | Length 1 Standard EFEC |I|0| |E| 1 SuperFEC Reserved |S|

Standard (16 bits): The following flags are currently defined. All other values are reserved.

I - In-band FEC supported

0 - Out-band FEC supported

EFEC (16 bits): The following flag is currently defined. All other values are reserved.

E - Extended FEC supported. Now there is one Extended FEC method.

SuperFEC (16 bits): The following flag is currently defined. All other values are reserved.

S - Super FEC supported. Now there is one Super FEC method.

This Sub-object is the FEC method that supported by OTU. The head OTU node initiates a call and set all FEC it supported and needed in the connection. The following OTU node along the path check the FEC, if some FEC can not be supported, then the corresponding bit will be cleared in the Sub-object. If no one bit is set, it means the call failed.

5. Security Considerations

This document describes some applications for GMPLS Calls whose mechanisms are described in [<u>RFC4974</u>]. It just introduces some new Sub-objects for CALL_Attributes object which is described in [<u>MLN-EXT</u>] and it does not introduce any new signaling messages. So this document does not introduce any additional security considerations.

<u>6</u>. Manageability Considerations

TBD.

7. IANA Considerations

TBD.

8. References

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Acknowledgment

Funding for the RFC Editor function is currently provided by the Internet Society.