

draft-nexagon LISP-H3 based Mobility Network IETF 104 Sharon Barkai

http://34.219.56.157/mot.html#nexagons&hexagons=10100&location=tlv&date=2019-03-19

Mobility Networks

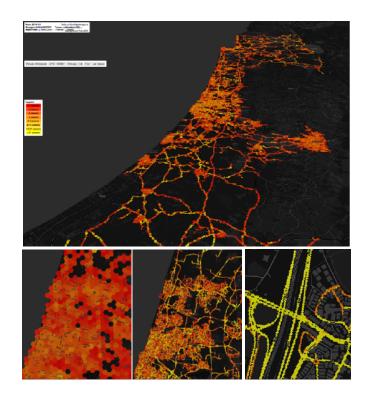
- Vehicle to Vehicle / Vehicle to Infrastructure
- Goal: share information while on shared road
- Facilitate safety and efficiency use-cases
- Very slow progress over the passed decade
- Layer2 battles between Wifi and Cellular
- Logical interoperability-privacy challenges



Sharing jittery GPS vectors not very valuable - Sharing deeper annotations interoperability nightmare

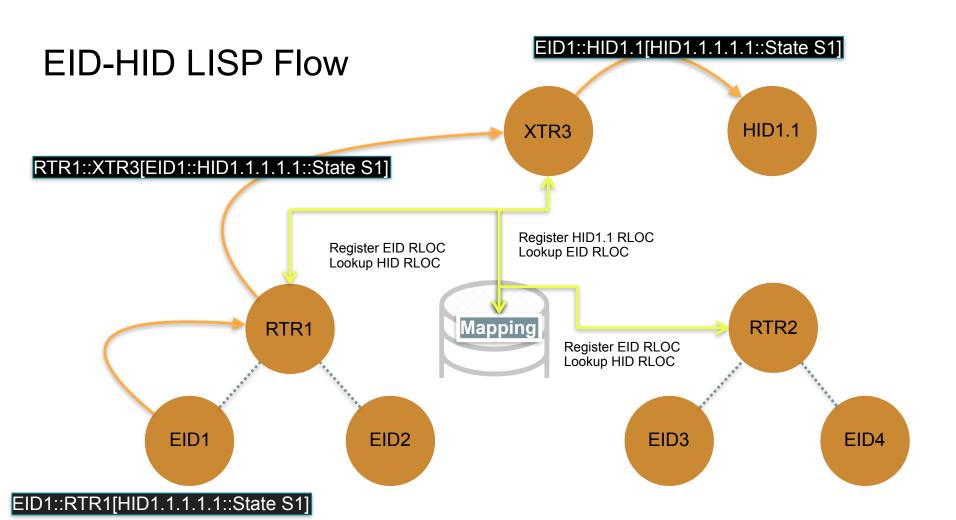
LISP-H3 Approach

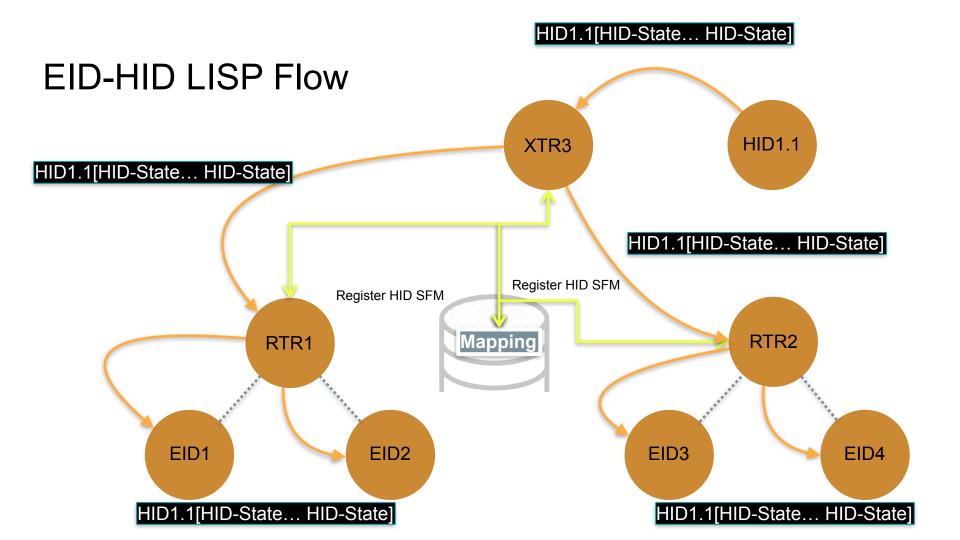
- Not share sensor (visual-lidar) data peer-to-peer
- Instead communicate through in-network state
- State of road (not cars) represented by H3 tiles
- EIDs (cars) communicate with HIDs (tiles)
- pXTRs use mapping to route between them
- EIDs publish-subscribe to HID ucast-mcast



LISP-Based Mobility-Network Indirection: Cars Ucast Tiles, Tiles Mcast Cars & Infrastructure







Example

- EID1 sees the problem
 Car pulling out parking
- EID1 Ucasts HID2
- HID2 Mcasts EID3
- Shared Neural Vision
 By simple indirection
 Standard ID-CODEC
 No peer-to-peer com







Use Cases

- Sharing in-town annotations through tiles beyond line-of site
- Garbage trucks, unloading, double-park, jaywalkers
- Signage, markings, potholes, traffic-lights ...
- Sharing out-of-town annotations through tiles beyond bends
- Slow-downs, stopped-vehicles, responders, heavy-incoming
- Signage, markings, potholes, traffic-lights ...

