

# Piccolo - In-network compute for 5G services Use cases

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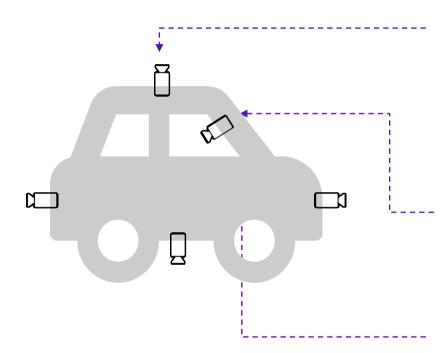
## Automotive real-time 'Risk Index'

#### What

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#### Why

- A real-time measure of the 'situational risk' of a vehicle
- Modification of vehicle occupant/ driver behaviours
- Decision support for remote fleet operations & control entities
- Ecosystem optimisation:
  - underwriting & insurance, policing
  - urban planning

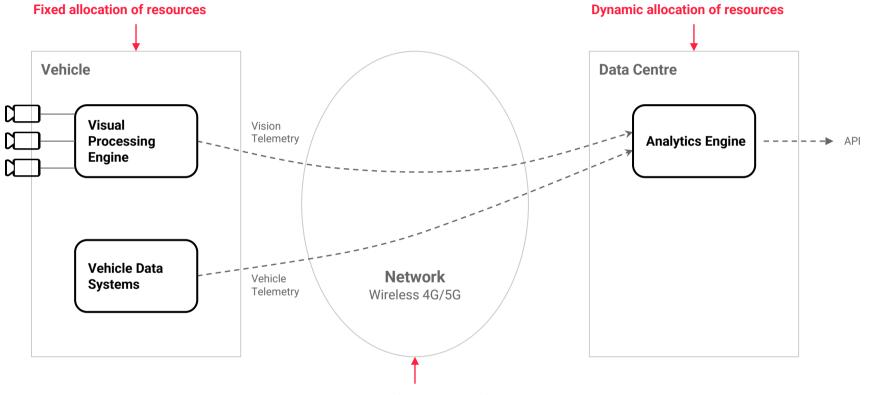


#### How

- Visual sensing of the situation and behaviours outside the vehicle
  - Environmental conditions
  - Humans and animals
  - Objects & hazards
- Visual sensing of the situation inside the vehicle
  - Human behaviour
- State of the vehicle and its subsystems
  - Vital signs
  - subsystem health etc.



#### Current architectural state of the art

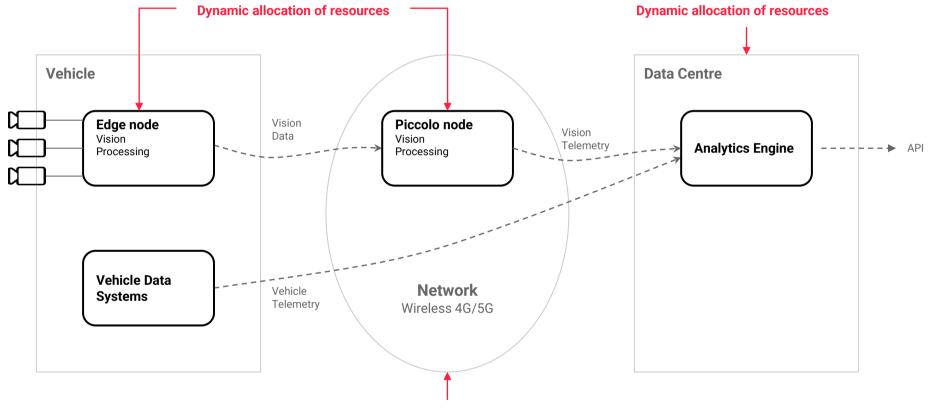


End to end view of network as a flow path



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### Piccolo architecture

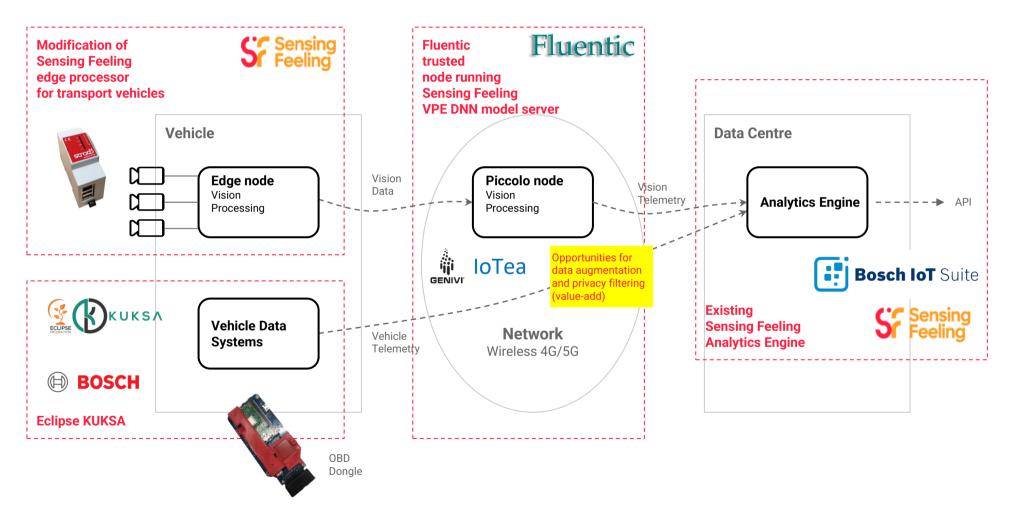


End to end view of network as a compute path

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## PoC design - Automotive real-time 'Risk Index'



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### **Topics under development & Research questions**

- Re-engineer the in-network logic to be able to handle multiple edge nodes
- Orchestration/control function eg to deliver algorithms to the network nodes
- Capabilities of in-network nodes: just ML/DNN inferencing or arbitrary logic?
- Flex resources up or down to handle concurrent demand
- Ensure the in-network execution is secure & private, as the vehicle moves



#### Piccolo – key facts

- Collaborative project under the Celtic framework
- Jointly funded by Partners and Innovate-UK (UK) & BMWi (Germany)
- 2 years from October 2020
- <u>https://www.piccolo-project.org/</u>
- Keen to collaborate through fora such as COINRG

Partner	Key people
Arm	Chris Adeniyi- Jones
Bosch	Dennis Grewe
BT (UK lead)	Philip Eardley
Uni Emden/Leer (German Lead)	Dirk Kutscher
Fluentic Networks	Yiannis Psaras
InnoRoute	Andreas Foglar
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