Starvation in End-to-End Congestion Control







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Loss-based CCAs don't bound delay

Delay bounding Congestion Control Algorithms (CCAs)





Delay-convergence (definition)



Starvation is caused by non-congestive delay

Total delay = Propagation delay + Congestive (bottleneck) delay + Non-congestive delay



Hard to distinguish between these

Sources of non-congestive delay

Wi-Fi sends TCP ACKs in bursts of tens of ms

Cellular base stations have a complex service process



End hosts send packets/acks in bursts



OS will only process packets when it gets the chance

One path can have multiple of these











How large is this delay (wired)?



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Non-congestive delays confuse congestion estimation



Every estimator we are aware of has failure modes:

Delay

Instantaneous, average, median, min, avg of max

Rate

Average, max of average

Can I just estimate congestive delay correctly then?



Starvation (definition):

- 1. The ratio of throughputs they get is arbitrarily large
- 2. It remains that way forever

Starvation in Vegas/FAST/Copa





Key Result: All delay-convergent CCAs starve



Theorem: We can always construct non-congestive delay smaller than D such that starvation occurs (for any $D > 2\delta$)



Proof: Constructing the non-congestive delay









Starvation in BBR

If the network has some jitter, BBR will maintain queuing delay equal to propagation delay

If propagation delay for two flows are different, the flow with the *smaller* propagation delay starves!



Starvation in Vegas/FAST/Copa





Could deliberately oscillating delay help?



Time

Why would deliberately oscillating delay help?



Link rate

What next?

- Deliberately oscillate the delay
- Design for a finite link range [see paper for how]
- Use ECN, fair queuing, ...