# RSVP-TE extension for extension for signaling Objective Function and Metric Bound

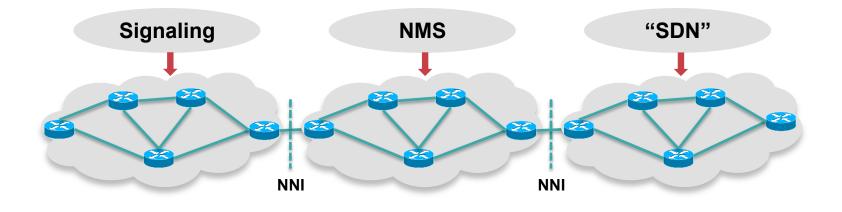
#### draft-ali-ccamp-rc-objective-function-metric-bound-04.txt

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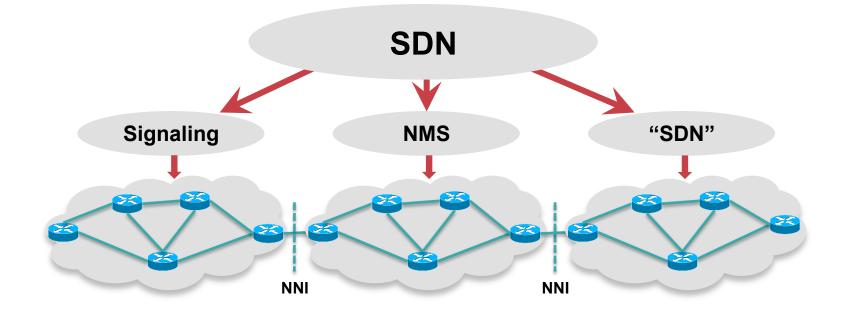
# Large SP Transport Layer Environment

- Mixed Vendor Environment; Possible Dual Cores
- Several Vendors in access
- No PCE is deployed
- SDN not yet deployed
- Multiple operations groups



# Large SP Transport Layer Environment

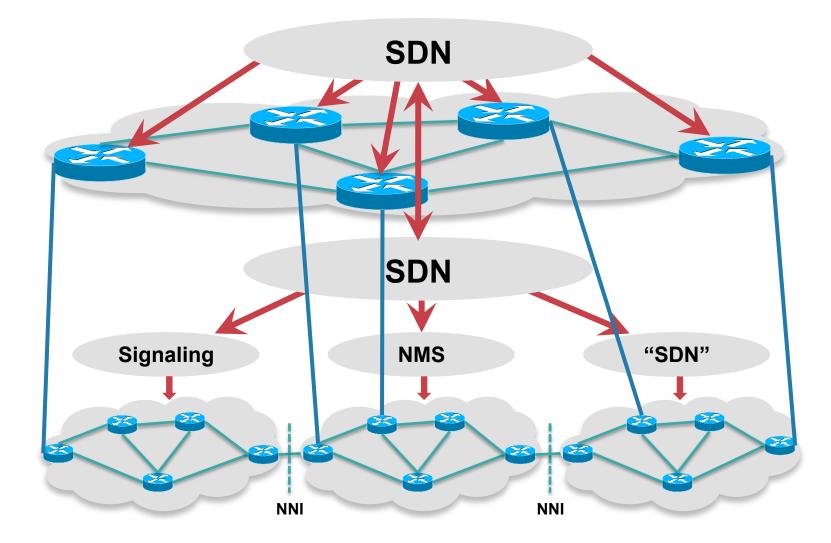
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# **Operational Culture**

- Good fences make good neighbors
  - ≻UNI exists to solve a political problem
  - ➢otherwise we'd just have GMPLS
- Fewer protocols is better (whether or not true, it is perceived)
  - Less training
  - Less configuration
  - Simpler debugging
  - ≻Above sums to less OpEx
- Resistant to allowing devices outside their control to participate in their protocols

# The full picture



#### **Recovery Requirements**

- Restoration needs to be performed in fully distributed fashion.
  - The entity that provisioned the path options may not be accessible/ active during a failure, e.g., SDN controller, planning tool, manual, etc.

>That entity may be overloaded during failure scenarios

>Involving that entity will slow down the restoration.

 A centralized entity may provide more relaxed constraints to be used in the event of a hard failure

➤(i.e. the primary constraints or ERO cannot be met)

 This approach offers the benefits of centralized planning, but gives network autonomy to find restoration paths

>Note that centralized planning could be an off-line exercise

# Motivation behind in/exclude route & OF

- RFC4208 restrictive in scope
- Idea is to open it up to information that parties are willing to agree to share
- Allow User to learn SRLGs and latency
- Allow User to specify requirements in more abstract, but highly relevant terms
  - ➢ Diverse from another path
  - ➢Follow another path
  - ➢ Meet a bound on latency
  - ➤Meet some other objective