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Progress on Practical Shared Bottleneck Detection for Coupled Congestion Control

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R / T E

REDUCING INTERNET TRANSPORT LATENCY



Background

Problem

- ▶ Flows traversing different paths through a network may share a common congested link — a bottleneck
- ▶ Detecting which flows share a bottleneck and coupling their congestion control can provide performance advantages.

SBD design objectives

- ▶ Reliable
- ▶ Practical (not CPU nor network intensive)
- ▶ Small numbers of bottlenecks (< 10)
- ▶ Timely stable bottleneck detection (< 10 s)

Shared Bottleneck Detection

What does it rely on?

- ▶ flows that share a bottleneck are similar in a measurable way

Why is it hard?

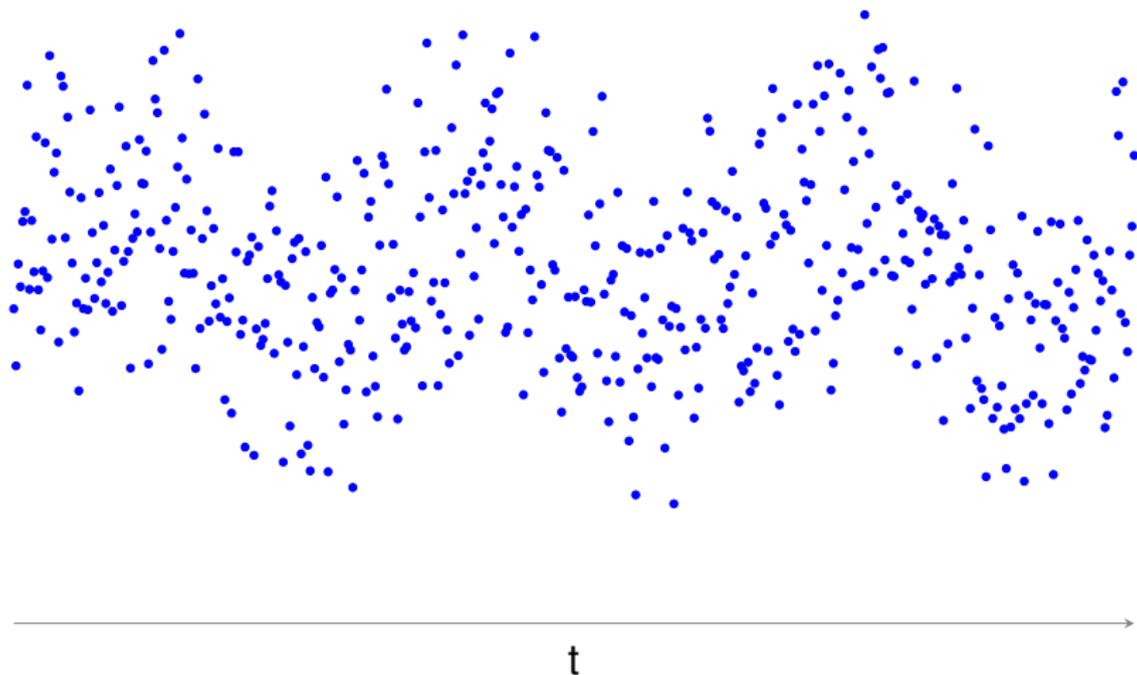
- ▶ delay and loss measurements include “noise” from rest of the path
- ▶ delay and loss at the bottleneck is noisy – each packet sees a different queueing delay
- ▶ different path delays cause time correlations to be lost or degraded at the measurement point

Classic cross correlation techniques

Pairwise flow cross correlation of delay samples

- ▶ delay signal is noisy
 - ▶ filter
- ▶ delay distribution is often skewed
 - ▶ sophisticated filter
- ▶ different path delays
 - ▶ incrementally shift and cross correlate to find lag of maximum correlation.

The delay signal



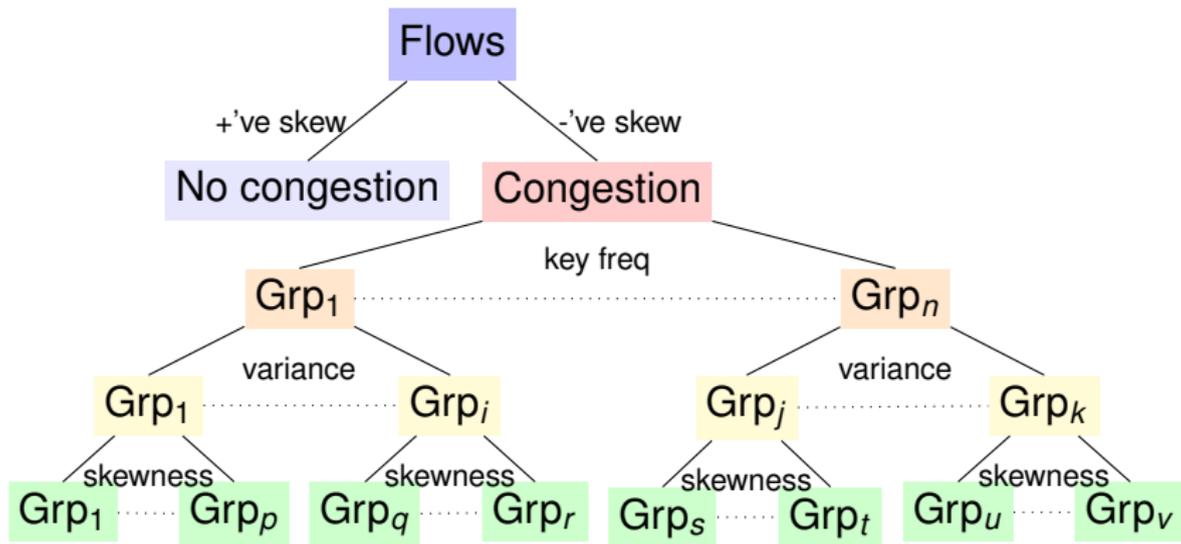
Dealing with the signal noise

- ▶ Remove half the noise from other links by using OWD instead of RTT
- ▶ Only using difference statistics
 - ▶ removes queueing delay estimate errors due to inaccurate estimate of OWD_{min}
- ▶ Mitigate lag and sample noise by:
 - ▶ relatively large statistic gathering periods
 - ▶ relax thresholds (no need to distinguish between 1000 bottlenecks)
 - ▶ use multiple measures

Summary statistics

- ▶ Skewness in OWD
 - ▶ an estimate using 2 counters
- ▶ Variance in OWD
 - ▶ estimated using PDV (RFC 5481)
- ▶ Key frequency of OWD at the bottleneck link
 - ▶ estimated based on significant mean crossings

Grouping overview



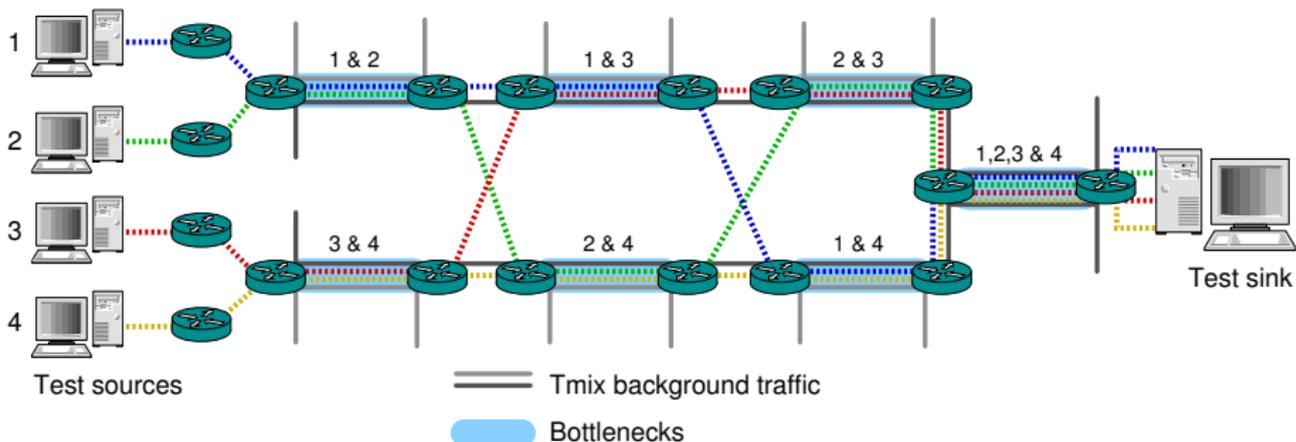
Simulation tests

Objectives

- ▶ Test with a known “ground truth”
- ▶ Simulations can allow us to look at worse than real scenarios.

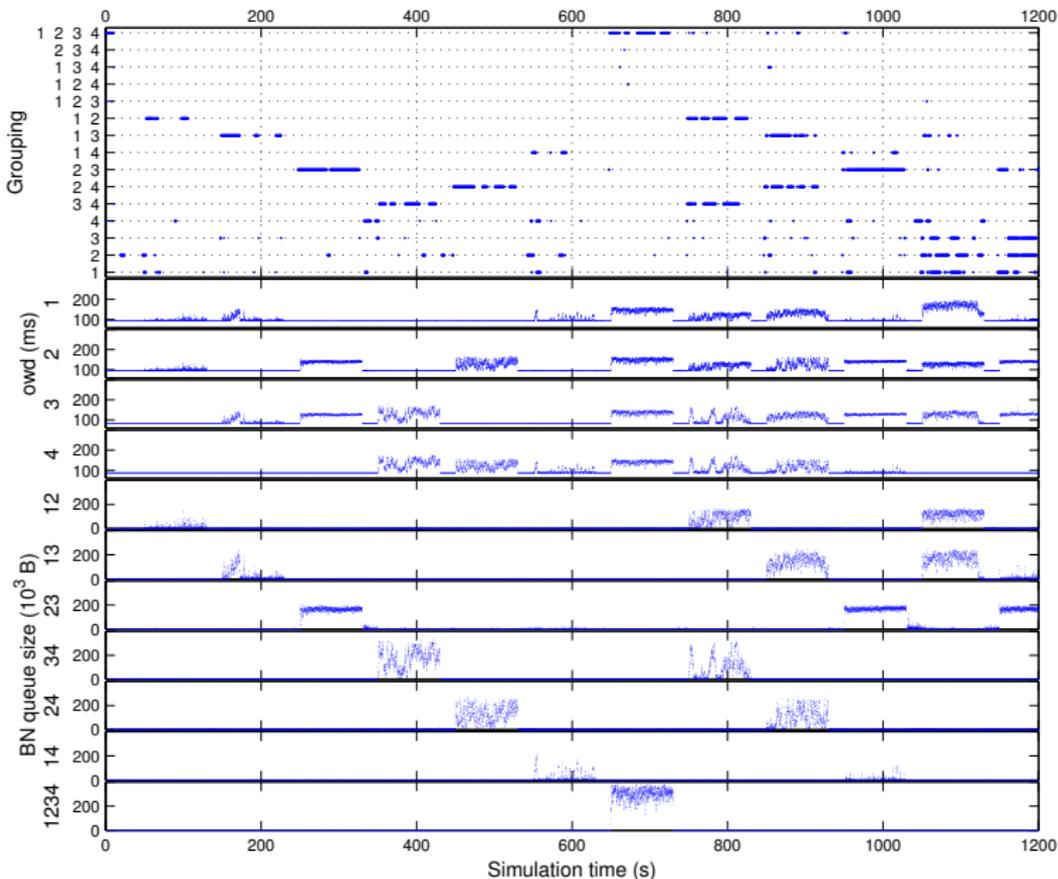
But, real network experiments are in progress will be discussed before the end.

Example NS2 Simulation



Notes on results

- ▶ Decisions made every 300 ms, but based on 6 – 15 s statistics.
- ▶ Decision “points” are large for legibility, but it can tend to magnify errors.
- ▶ Results illustrates what can and can't be done.



Simulation results

Different queue sizes, link owd std 2.5.

Note bottleneck queue sizes have been subsampled (1:350) and OWDs (1:20)

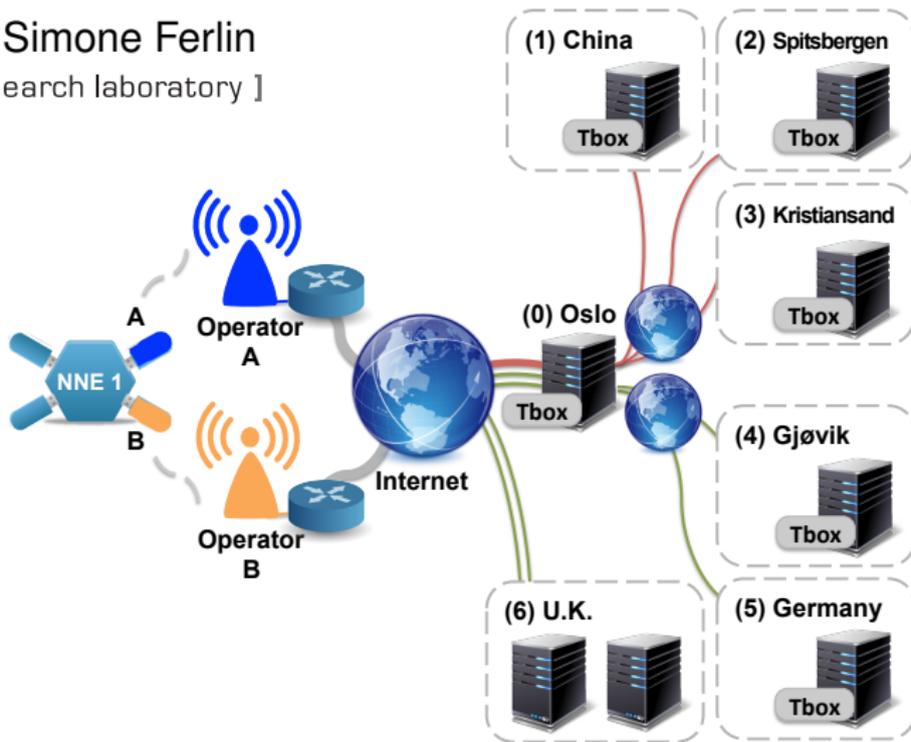
Real network experiments

- ▶ Bottleneck “ground truth” cannot be known with 100 % certainty.
 - ▶ Find thinnest link using STAB
 - ▶ Load thinnest link with distant internet sources to create known bottleneck
- ▶ What are we testing?
 - ▶ Robustness in unpredictable “real” environments

Real network experiments (in progress)

Work with Simone Ferlin

[[simula](#) , research laboratory]



Working with Coupled Congestion Control

- ▶ Summary statistics are gathered at the receivers
- ▶ Shared bottlenecks to a receiver
 - ▶ Receiver does grouping and sends information to senders
- ▶ Shared bottlenecks from a sender:
 - ▶ Receivers send summary statistics for grouping at sender.
- ▶ Can provide the necessary information for a future multi-sender multi-receiver coupled congestion control.

Conclusions and further work

Finalising this stage

- ▶ Finish real network experiments
- ▶ Paper submission soon (LCN)
- ▶ Draft (referring to paper)
- ▶ Quantitative results of % correct grouping
 - ▶ simulation based where “ground truth” is known
 - ▶ bottleneck definition based on queue empty rate or avg. queue size
 - ▶ extended version in journal

Next steps

- ▶ Protocol for sender/receiver information exchange
- ▶ Integration with coupled congestion control
 - ▶ time scales of detection
 - ▶ dealing with SBD errors
 - ▶ oscillating bottlenecks

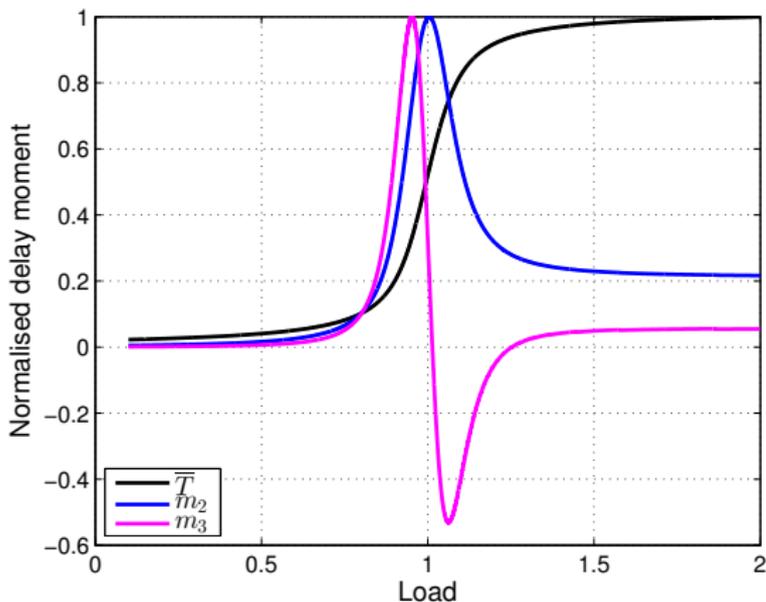


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Extra slides

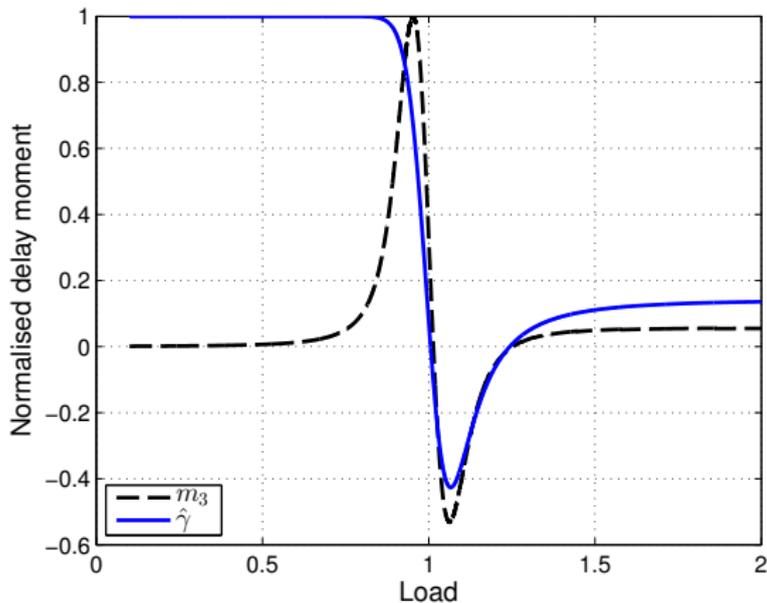


Time domain summary statistics

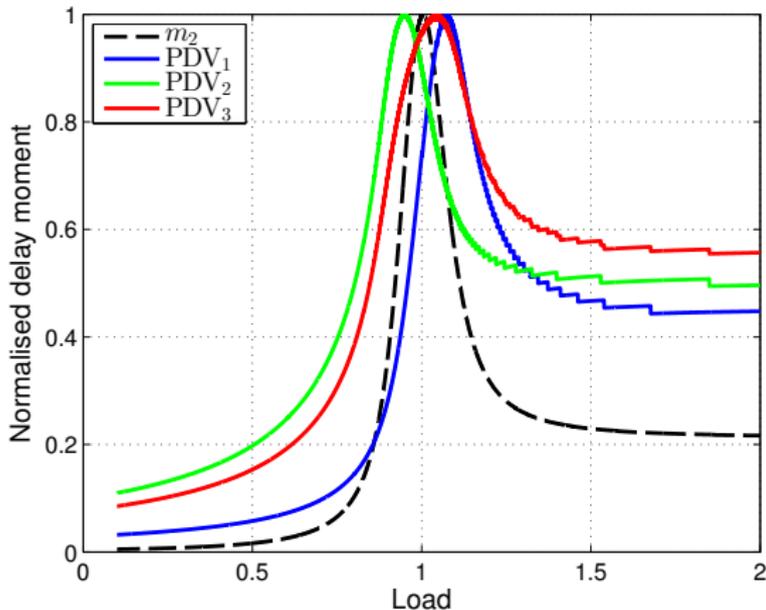


Mean, variance (m_2), skewness (m_3)

Practical estimation of skewness



Practical estimation of variance



Practical estimation of key frequency \hat{f}

