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Shared Bottleneck Detection for Coupled Congestion Control for RTP Media

Update (draft-hayes-rmcat-sbd-02)

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R / T E

REDUCING INTERNET TRANSPORT LATENCY



Mechanism based on Summary Statistics

Why summary statistics?

- ▶ To limit feedback from receivers
- ▶ To deal with noise
- ▶ To deal with differing path lags

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Statistics Used

- ▶ a measure of delay variance (**var_est**)
- ▶ a measure of delay skewness (**skew_est**)
- ▶ a measure of delay oscillation (**freq_est**)
- ▶ a measure of packet loss (**pkt_loss**), a supplementary measure.
- ▶ *not a closed list*

Overview of work so far

The mechanism has been demonstrated using:

- ▶ Simulation experiments with multiple hops, changing bottlenecks, and realistic background traffic.
- ▶ Real network tests over the Internet and 3G mobile using NERNET(<https://www.nntb.no/>)

Publication

D. A. Hayes, S. Ferlin, and M. Welzl. [Practical passive shared bottleneck detection using shape summary statistics.](#)

In *Proc. of the IEEE Local Computer Networks (LCN)*, pages 150–158, Sept. 2014.

URL <http://dx.doi.org/10.1109/LCN.2014.6925767>

Key changes in -02

Some terminology improvements

Section on reducing noise in the statistical estimators

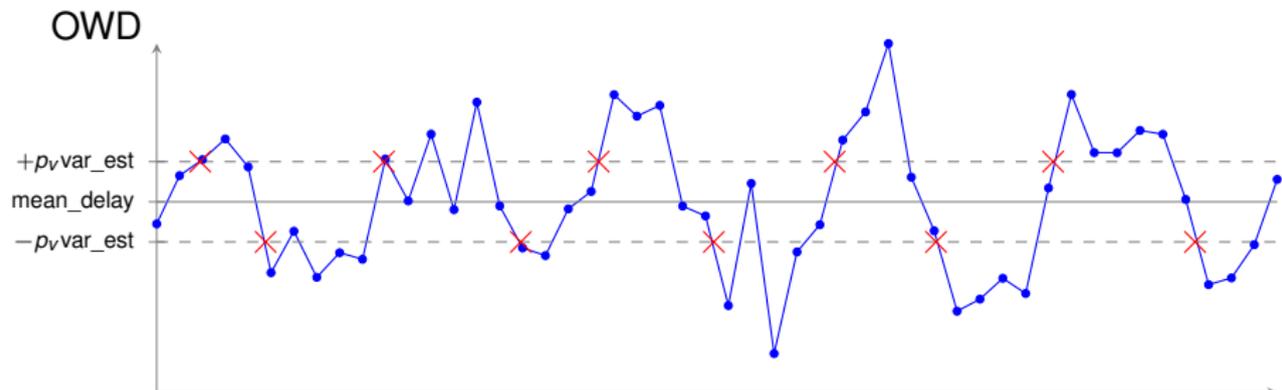
- ▶ removing noise from **freq_est** due to periods where there is no congestion
- ▶ removing bias in **skew_est**
- ▶ a simple adjustment for clock drift

Section on decreasing decision lag

- ▶ e.g. changes in networks and new signals

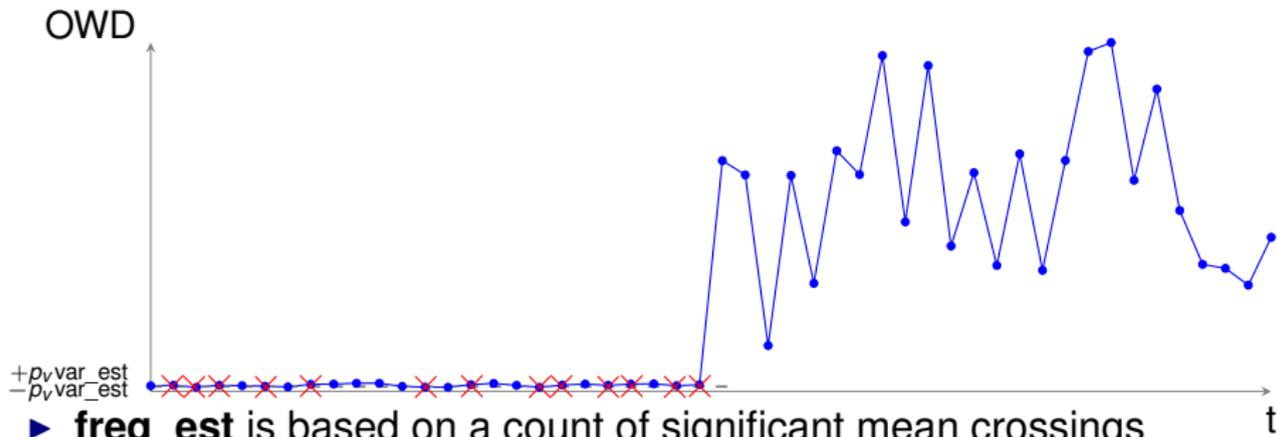
These are minor improvements that can improve the performance in certain circumstances.

Removing noise in freq_est



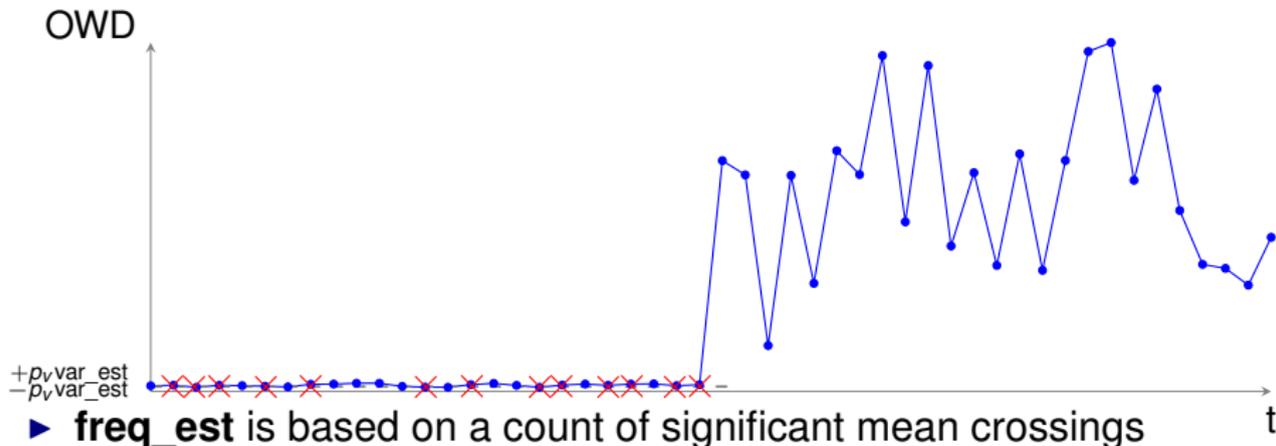
- **freq_est** is based on a count of significant mean crossings

Removing noise in freq_est



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- ▶ But when there is no congestion (ie no bottleneck), this is noise

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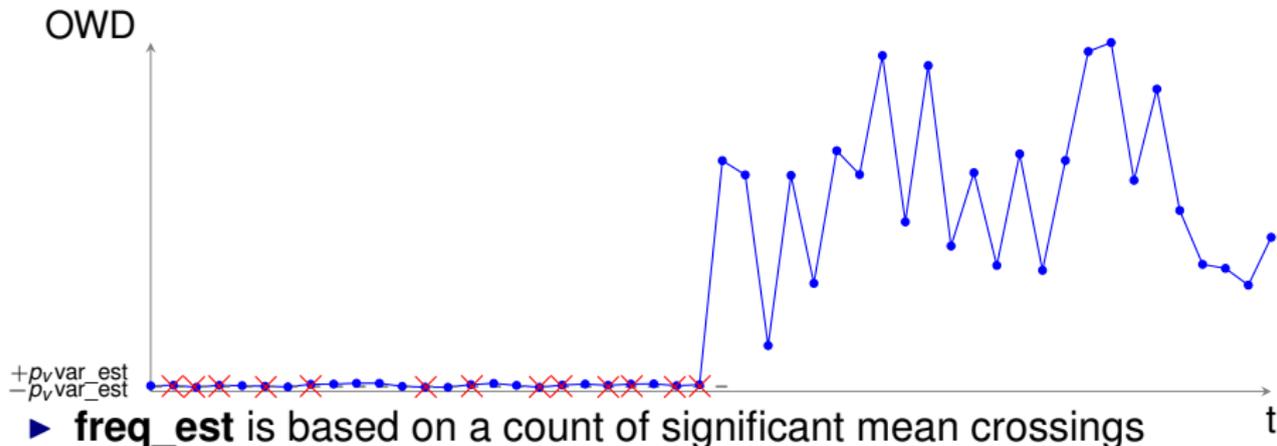


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Enhancement:

Only use PDV values obtained when path is congested (by **skew_est**)

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Enhancement:

Only use PDV values obtained when path is congested (by **skew_est**)

- ▶ PDV = NaN when no congestion
- ▶
$$\text{var_est} = \frac{\text{sum_M}(\text{PDV} \neq \text{NaN})}{\text{num_VM}(\text{PDV})}$$

Removing small sample bias in `skew_est`

Bias

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Avoiding bias

$$\text{skew_base_T} = \text{sum_T}(\text{OWD} < \text{mean_delay}) \\ - \text{sum_T}(\text{OWD} > \text{mean_delay})$$

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Possible approaches

- ▶ $M < N$ helps, but at the expense of poorer estimates.
- ▶ Linear correction based on a history of selected $\min(\text{OWD})$
 - ▶ Uses state not currently kept, but being investigated.
- ▶ Proposed approach is based on already stored $E_T(\text{OWD})$ values
 - ▶ modifies **mean_delay** calculation
 - ▶ may not track drift as well as using selected $\min(\text{OWD})$, but
 - ▶ helps congestion determination when OWDs slowly fall.

Simple mean based adjustment for clock drift

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$$\text{CD_T} = \frac{(\text{Newer_mean} - \text{Older_mean})}{N/2}$$

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5. Adjusted mean:
$$\text{mean_delay} = E_M(E_T(\text{OWD})) + \text{CD_T} * M/2$$

► Used as the basis for **skew_est** and **freq_est**.

Decreasing decision lag

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- ▶ Exploit the fact that recent measurements are more important.

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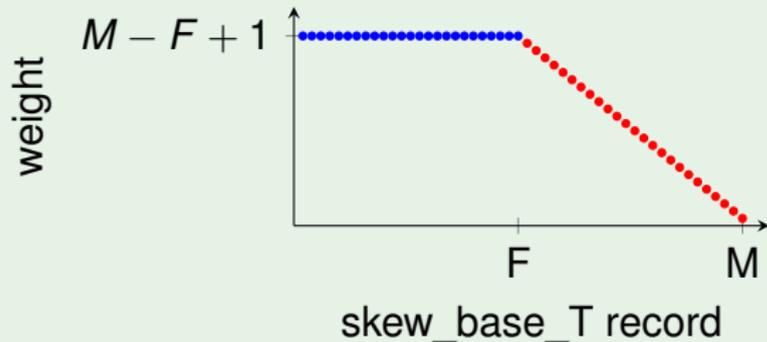
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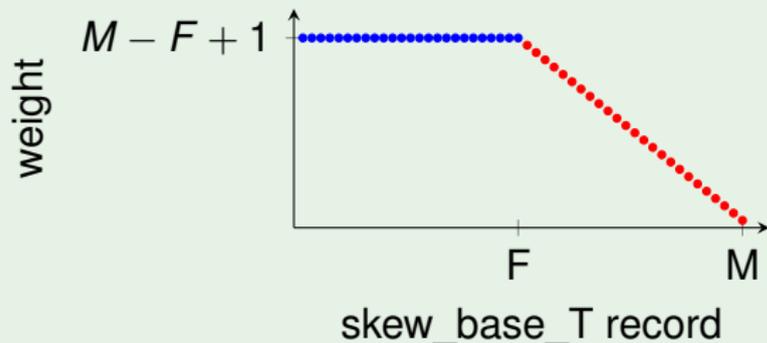
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Weighting

- ▶ Old measurements are still important for stability
- ▶ EMA: infinite tail, not enough weight for recent values
- ▶ Linear decreasing weights: not enough weight for recent values
- ▶ Propose a piecewise linear approach

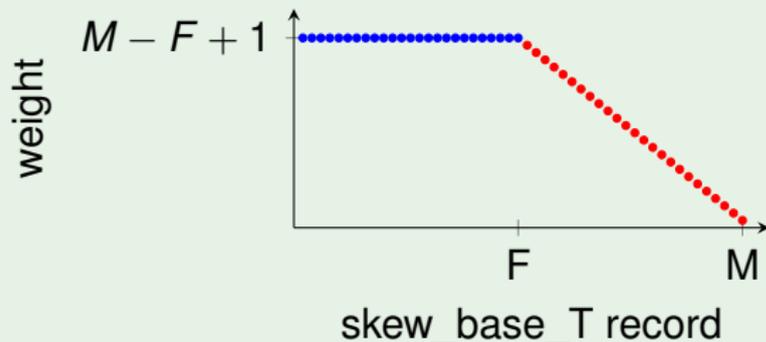
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$$\text{skew_est} = \frac{(M - F + 1) * \text{sum}(\text{skew_base_T}(1 : F)) + \text{sum}([(M - F) : 1]. * \text{skew_base_T}(F + 1 : M))}{(M - F + 1) * \text{sum}(\text{numsampT}(1 : F)) + \text{sum}([(M - F) : 1]. * \text{numsampT}(F + 1 : M))}$$

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- ▶ Similarly for **var_est**

Conclusions and plans

- ▶ Outline the effect each threshold has on performance
- ▶ Define sender receiver interaction
- ▶ Evaluate the effect of time resolution
- ▶ Extend tests to wifi scenarios
- ▶ Journal
 - ▶ algorithm refinements
 - ▶ quantitative tests

Acknowledgements

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Extra slides

