



# IETF-96 (Berlin)

## ANIMA WG Meetings (Autonomic Networking Integrated Model and Approach)

Monday, 18:00-20:00, Afternoon Session III, Potsdam II  
Thursday, 16:20-18:20, Afternoon Session II, Potsdam III

Last update: July. 14<sup>th</sup>, 2016



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# Before begin the meeting

- Hope you noted the Note Well
- Blue sheets
- Need Jabber scribe(s)
- Need minutes takers
- Remote participation

<https://www.ietf.org/meeting/96/remote-participation.html>

- Slides

<https://datatracker.ietf.org/meeting/96/materials.html#anima>



# Before begin the meeting

- Mailing List:

[anima@irtf.org](mailto:anima@irtf.org)

<https://www.irtf.org/mailman/listinfo/aniam>

- WG co-chairs:

– Sheng Jiang

– Toerless Eckert

- WG web page:

<https://datatracker.ietf.org/wg/anima>



# Meeting Agenda

- Monday (July 18<sup>th</sup>, 2016) 2-hour session:  
18:00-20:00 Afternoon Session III, Potsdam II
1. WG Dash - 5 min  
18:00 - 18:05, by co-chairs
  2. ANIMA Generic Signaling (Design team) - 30 min  
18:05 - 18:35, by Brian Carpenter, [draft-ietf-anima-grasp](#)
  3. ANIMA Auto Bootstrapping (Design team) - 30 min  
18:35 - 19:05, by Max Pritikin, [draft-ietf-anima-bootstrapping-keyinfra](#)
  4. Autonomic Control Plane - 20 min  
19:05 - 19:25, by Michael Behringer, [draft-ietf-anima-autonomic-control-plane](#)
  5. AN Reference model - 35 min  
19:25 - 20:00, by Michael Behringer, [draft-ietf-anima-reference-model](#)

# Meeting Agenda (Cont.)

- Thursday (July 21st, 2016) 2-hour session:  
16:20-18:20 Afternoon Session II, Potsdam III
1. On-site progress update for WG documents - 10 min  
16:20 - 16:30
  2. \* Information Distribution over GRASP - 20 min  
16:30 - 16:50, by Bing Liu, [draft-liu-anima-grasp-distribution](#)
  3. \* Autonomic Functions Coordination By The Example - 20 min  
16:50 - 17:10, by Laurent Ciavaglia, [draft-ciavaglia-anima-coordination](#)
  4. \* Autonomic Functions Life-cycle and Management - 20 min  
17:10 - 17:30, by Pierre Peloso, [draft-peloso-anima-autonomic-function](#)
  5. \* ANIMA Intent Policy - 20 min  
17:30 - 17:50, by Jeferson C Nobre, [draft-du-anima-an-intent](#)
  6. \* GRASP API - 20 min  
17:50 - 18:10, by Bing Liu, [draft-liu-anima-grasp-api](#)
  7. Summary & ANIMA future activities - 5 min  
18:10 - 18:15, by co-chairs
- \* mean the non-chartered work items.

# WG Milestone Status

- WG Documents

- [draft-ietf-anima-gdn-protocol 06](#) (Adopted Aug 2015)  
Next Milestone: Apr 2016, Submit discovery and negotiation protocol(s) to IESG
- [draft-ietf-bootstrapping-keyinfrastructures 03](#) (Adopted Aug 2015)  
Next Milestone: Apr 2016, Submit bootstrap a trust infrastructure solution to IESG
- [draft-ietf-anima-autonomic-control-plane 03](#) (Adopted Aug 2015)  
Next Milestone: Sep 2016, Submit autonomic control plane solution to IESG



# WG Milestone Status (2)

- Documents adopted since last meeting
  - [draft-ietf-anima-stable-connectivity-01](#) (Adopted Dec 2015)  
Next milestone: Sep 2016, Submit the two validation drafts to IESG (Informational)
  - [draft-ietf-anima-prefix-management-01](#) (Adopted Dec 2015)  
Next milestone: Sep 2016, Submit the two validation drafts to IESG (Informational)
  - [draft-ietf-anima-reference-model-02](#) (Adopted Dec 2015)  
Next milestone: Dec 2016, Submit reference model to IESG (Informational)

# ANIMA WG Info

- More discussion will be taken into ANIMA mail list ([anima@ietf.org](mailto:anima@ietf.org))
- Chairs can be reached by [anima-chairs@tools.ietf.org](mailto:anima-chairs@tools.ietf.org)
- Next meeting
  - 97<sup>th</sup> IETF, November 13-18, 2016, in Seoul, South Korea
  - Interim meeting may be arranged
- Next Chartered Milestone:
  - Apr 2016 Submit discovery and negotiation protocol(s) to IESG (Standards Track)
  - Apr 2016 Submit bootstrap a trust infrastructure solution to IESG (Standards Track)
- Proposals without IPRs may be favored over proposals with IPRs by the WG

# Reading List

- Background
  - RFC7575, Autonomic Networking: Definitions and Design Goals
  - RFC7576, General Gap Analysis for Autonomic Networking
- WG Documents
  - [draft-ietf-anima-gdn-protocol](#)
  - [draft-ietf-bootstrapping-keyinfrastructures](#)
  - [draft-ietf-anima-autonomic-control-plane](#)
  - [draft-ietf-anima-stable-connectivity](#)
  - [draft-ietf-anima-prefix-management](#)
  - [draft-ietf-anima-reference-model](#)



# Reading List (2)

- Individual Documents

- [draft-ciavaglia-anima-coordination](#)
- [draft-ciavaglia-anima-knowledge](#)
- [draft-du-anima-an-intent](#)
- [draft-liu-anima-grasp-distribution](#)
- [draft-liu-anima-grasp-api](#)
- [draft-peloso-anima-autonomic-function](#)
- [draft-richardson-anima-state-for-joinrouter](#)
- [draft-strassner-anima-control-loops](#)

# Recharter

- In current charter, as milestone:
  - Dec 2016, recharter to refocus scope, or close
- We have been running second sessions as a forum for potential future work items
  - AN Intent, distribution, GRASP API, coordination, exchanging, ...
  - Autonomic Service Agents
- Calling for more potential work items

# Self-organizing in ETSI NGP

- ETSI NGP ISG
  - Next Generation Protocol Industry Specification Group
- Self-organizing Control & Management Planes (work item)
  - Calling individual contribution on autonomic
  - Introducing machine learning as mechanism for autonomic decision
  - [https://portal.etsi.org/tb.aspx?  
tbid=844&SubTB=844](https://portal.etsi.org/tb.aspx?tbid=844&SubTB=844)