Frame Context Selection

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Requirements for Temporal Scalability

- It should be possible to determine and control which previously coded frames are dependencies of the current frame
 - E.g., allow skipping every other frame

Requirements for Error Resilience

- It should be possible to determine if the decoder is missing a frame required for decoding
 - This allows retransmission or dropping of the frame
 - Allows a decoder that never shows a broken frame

VP9

- Reference frame dependencies
 - Implicitly or explicitly signaled with picture IDs in RTP mapping
 - Up to three allowed per frame (from pool of 8)
- Frame contexts (probabilities)
 - Stores probabilities that are backwards-adapted based on data from previous frames
 - Decoder maintains four independent sets
 - Each frame signals which one to use
 - Optionally writes back to the slot it read from
 - Choice uncorrelated with references or picture IDs

Problems with Frame Contexts

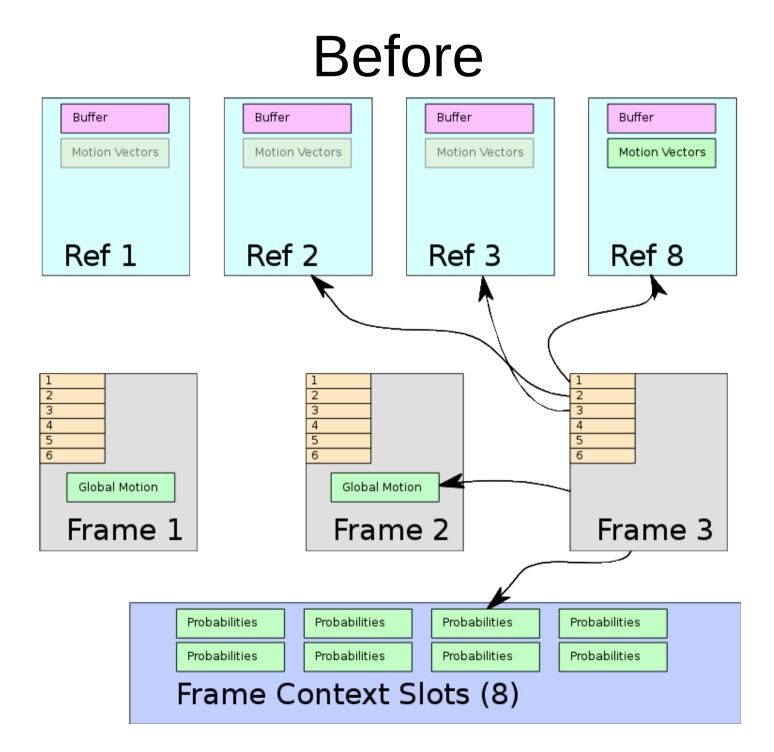
- If you lose a frame, you don't know which slot it updated
 - You no longer know if you can decode any frame
- The last frame to update the slot you're using might not be one of your reference frames
 - Frame contexts introduce potential hidden fourth frame dependency (this is surprising)
 - RTP mapping only signals three picture IDs (could fix)
- You can't fork probabilities and evolve them independently
 - Every layer pays cost of re-learning probabilities

AV1

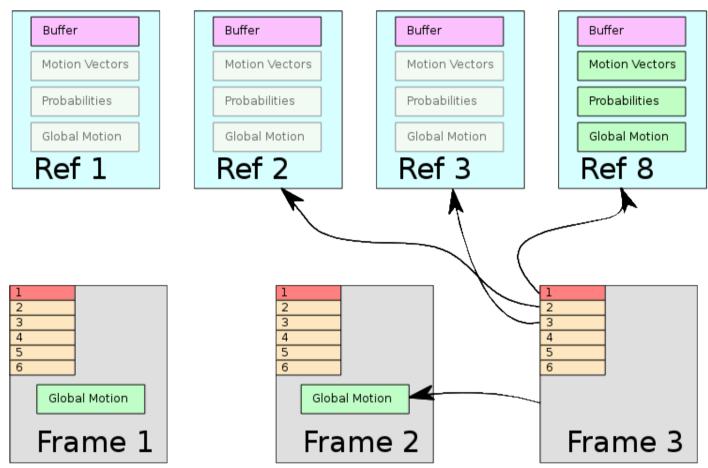
- Reference frame dependencies
 - Explicitly signaled and coded with frame IDs in codec payload
 - Up to six allowed per frame (from pool of 8)
- Probabilities
 - Currently same as VP9, but expanded to 8 slots
- Motion vectors for temporal MV prediction
 - Always from last coded frame
 - Fixed up by tempmv_signaling proposal
- Global motion data
 - Coded as deltas relative to last coded frame

Proposal

• Make all dependencies between frames track with reference frame structure



After



Details

- Remove frame context slots
- Remove all syntax elements for saving and restoring frame contexts
- Instead, always save frame context with reference buffers
 - When storing a reference frame, store updated probabilities, temporal MVs, etc., too
- No more syntax to reset frame contexts
 - Implicit on a keyframe

Complexities

- Interaction between reference number and function
 - In current encoder, first reference is always last frame from same layer
 - Need to re-order reference list to use probabilities from long-term reference (golden frame), alt-ref, etc.
- Using a previous frame context for intra-only frames
 Currently not supported (same as VP9)
- Using probabilities from a non-reference frame
 - No longer supported
 - With up to 6 of 8 references per frame, impact seems low

TODO

- Still some things to move to frame context
 - Global motion
 - Frame size prediction

Chroma from Luma

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New Update to CfL Proposal

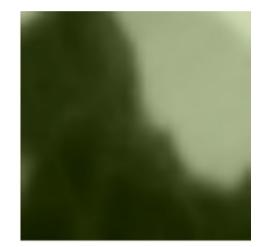
- Current evolution of draft-egge-netvc-cfl
 - A lot has changed
- **Complementary to** draft-midtskogennetvc-chromapred

What is Chroma from Luma?

• Exploits *local* correlation between color planes



Original



Reconstructed luma + chroma DC prediction (SSE: 315,364)



Reconstructed luma + CfL linear prediction $\alpha = <-0.25, -0.25>$ (SSE: 116,884)

Adapting CfL for AV1

- Daala CfL predicted coefficients directly
- Hard to do frequency-domain processing in AV1
 - Up to 16 different transform types
 - Luma transform type may not match chroma type
 - Luma transform *size* may not match chroma size
 - Could handle this for the DCT
 - Hard to do for all transform type combinations
- Lesson from Daala
 - Implicit model building is not very good
 - Okay when it works, can be very bad when it doesn't

Proposed vs. Prior CfLs

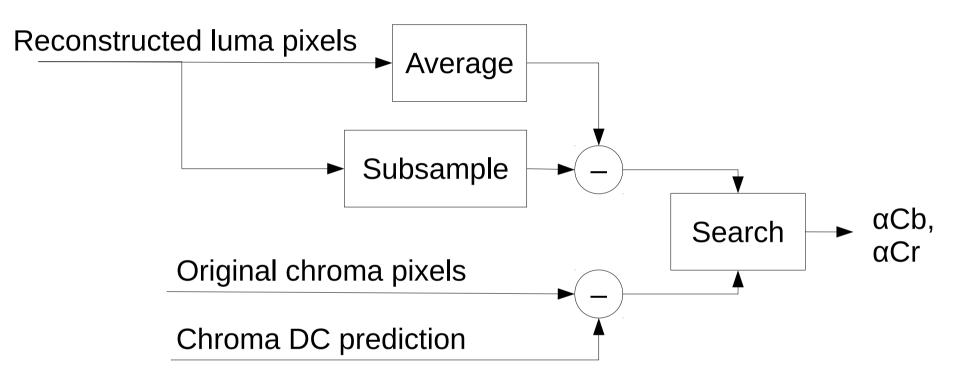
	LM Mode ¹	Thor CfL ²	Daala CfL ³	Proposed
Prediction Domain	Spatial	Spatial	Frequency	Spatial
Bitstream Signaling	No	No	Sign bit, PVQ gain	Polar index
Activation Mechanism	LM Mode (4×4 and 8×8)	Threshold	Signaled per band	CFL_PRED (UV-only mode)
Requires PVQ	No	No	Yes	No
Encoder Model Fitting	Yes	Yes	Via PVQ	Search
Decoder Model Fitting	Yes	Yes	No	No

1. JCTVC-E266 (Chen et al.)

2. draft-midtskogen-netvc-chromapred

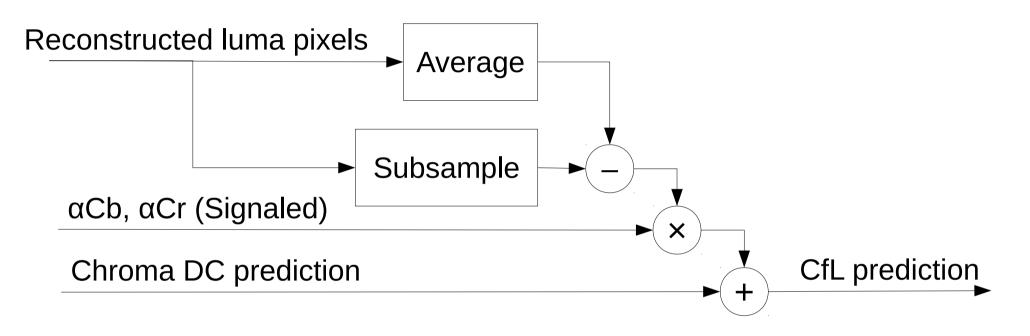
3. draft-egge-netvc-cfl

CfL: Encoder Side



- Luma average computed over transform block
 - Minimizes luma buffering in decoder
- Chroma DC computed over whole prediction block
 - Simplifies encoder search

CfL: Decoder Side



- Luma average computed over transform block
 - Minimizes luma buffering in decoder
- Chroma DC computed over whole prediction block
 - Simplifies encoder search

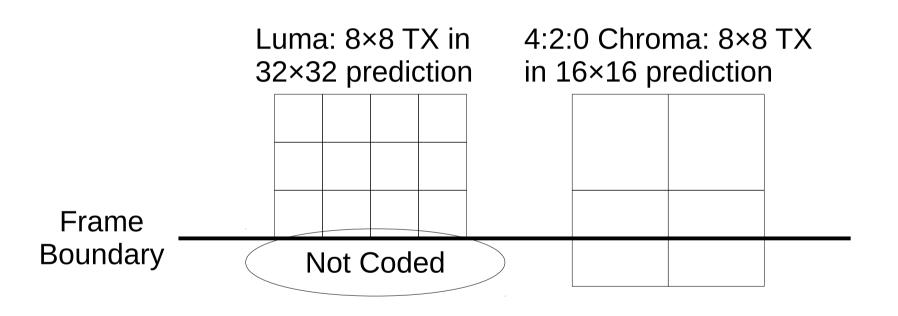
Complications (1)

- Sub-8×8 block sizes for 4:2:0 (and 4:2:2, 4:4:0)
 - Chroma uses one 4×4 transform with mode information from *bottom right*
 - Chroma is intra if bottom-right luma is intra
 - Must buffer luma from *inter* blocks above, left
- Chroma DC prediction for non-square blocks
 - Number of above + left pixels not a power of two
 - Average requires division (can implement with LUT)
 - AV1 adding rectangular transforms with rectangular intra prediction, so not a CfL-specific problem

Complications (2)

- Boundary handling
 - Frame size rounded up to nearest multiple of 8
 - Intra transform blocks completely outside this region are *not coded*
 - Chroma transform blocks may cover larger area than luma

Boundary Handling: Example



- Use simple extrapolation to recover missing luma pixels
- Also complicates DC prediction (not CfL-specific)

Outdated Example: AV1



205_-_Vallée_de_Colca_Panorama_-_Juin_2010_-_5_de_6.y4m (subset1) QP = 55, PSNR Cr = 37.26 dB Analyzer link: https://goo.gl/69N6LC

Outdated Example: AV1+CfL



205_-_Vallée_de_Colca_Panorama_-_Juin_2010_-_5_de_6.y4m (subset1) QP = 55, PSNR Cr = 38.58 dB Analyzer link: https://goo.gl/69N6LC

Latest Results

• AWCY BD-rate results on subset1 (still images)

PSNR	PSNR Cb	PSNR Cr	PSNR HVS	SSIM	MS SSIM	CIEDE 2000	
0.2948	-14.8567	-12.7782	0.5817	0.5682	0.5886	-5.0903	
reorder@2017-07-07T15:41:21.181Z →							
cfl-mode-uniform-alpha-it1-20@2017-07-13T13:13:50.456							

- Working on adjusting encoder's luma-chroma balance
 - Currently different parts of the encoder use different weights

Questions?