

Distributed Detection of SLA Violations

draft-irtf-nmrg-autonomic-sla-violation-detection-01

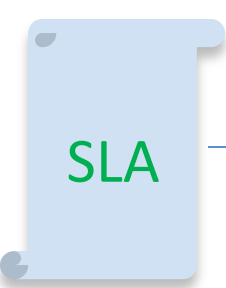
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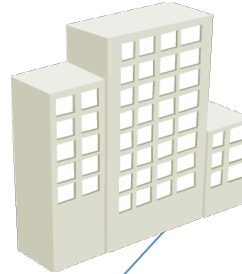
Alberto Gonzalez Prieto

Problem definition

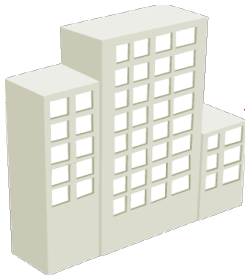


→ expected service level

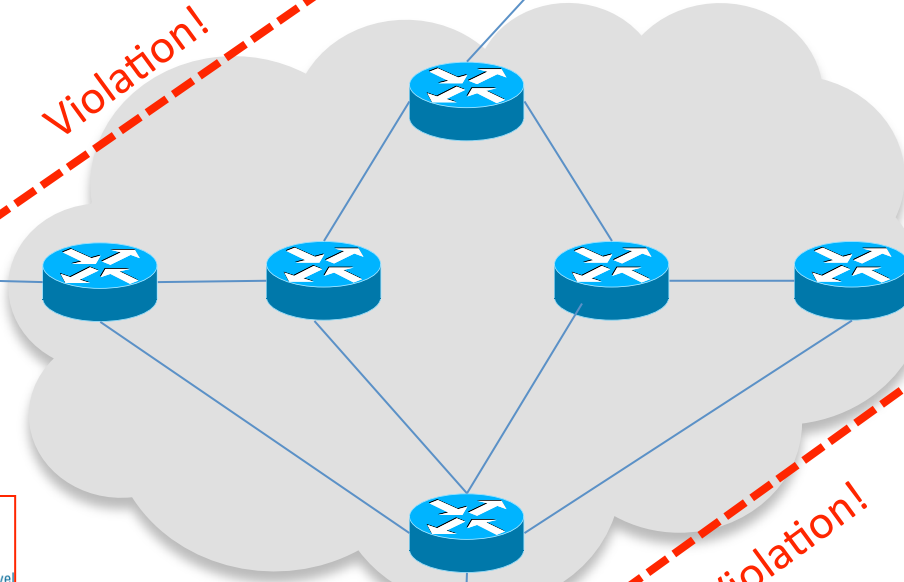
Site A



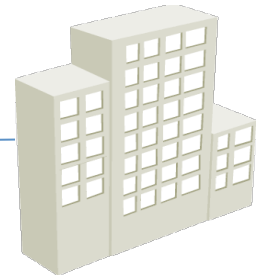
Site B



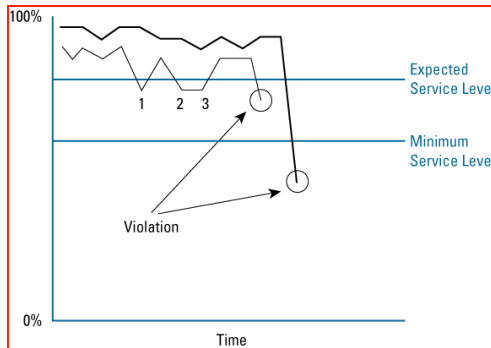
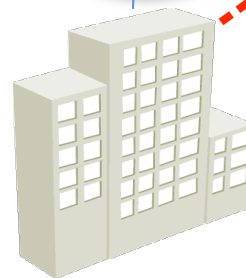
Violation!



Site C

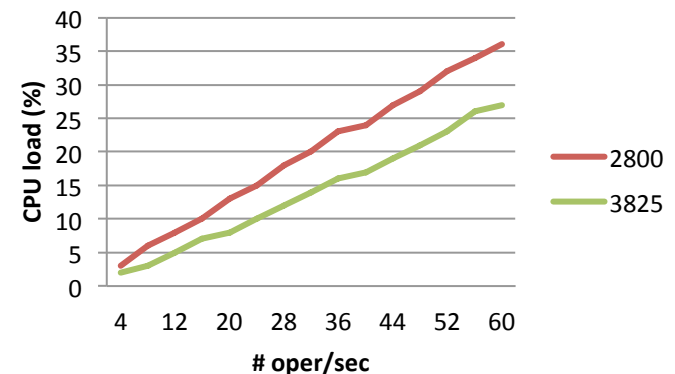
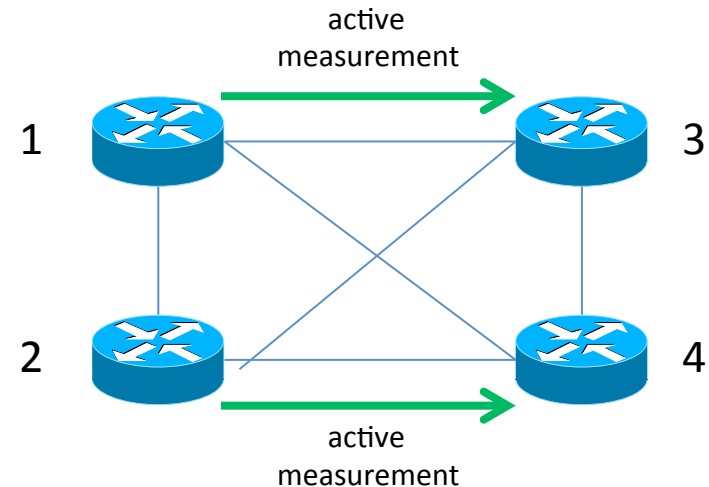


Site D

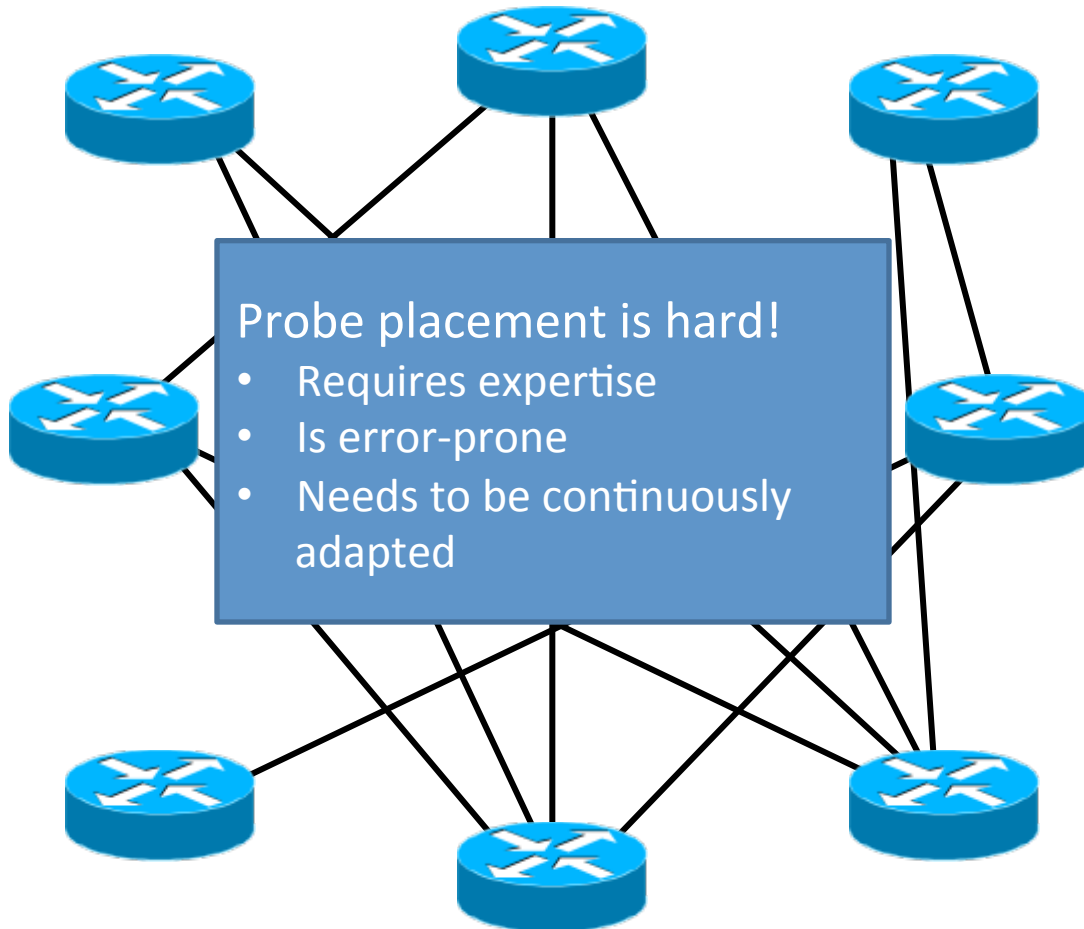


Basic Problem

- Maximize the number of detective violations
 - Active measurement is an effective way to detect SLA violations (RFC 6812, RFC 5357)
 - However, active measurement is expensive – CPU etc
 - Cannot measure everything → need to determine probes



“Partial mesh” manual placement



- Determine a coverage objective, ie: 30%.
- Build a traffic matrix to identify the “hottest” points (hint: use NetFlow).
- Take the top 30% and evenly distribute operations

| A | B | C | D | E | F |
|---|---|---|----|----|----|
| B | | 5 | 6 | 7 | 5 |
| C | 1 | | 7 | 12 | 12 |
| D | 7 | 5 | | 5 | 11 |
| E | 4 | 4 | 12 | | 2 |
| F | 3 | 8 | 4 | 18 | |

Benefits of an Autonomic Solution

Enable a service-level aware, self-monitoring network

- Autonomic solution determines what / when / how to probe without human intervention such that violations are detected with high probability
- Better coverage, violation awareness with less resources
- No dependence on hard-to-obtain human expertise
- Adaptive to dynamic network conditions
- Easy to use

Autonomic Problem formulation

- Given a set of service level objectives (“intent”)
- In the context of a network, consisting of
 - n nodes
 - s connections
 - v connections with service level violations
- Maximize $v = \text{\#detected violations} / (\text{\#total violations} + 1)$
- Place a set p of probes such that v is covered
 - In the quickest possible time
 - With the least amount of resources
 - $\text{\#probes} \leq \alpha$ (upper bound on total probes in network)
 - $\text{\#probes}(i) \leq \beta(i)$ (upper bound on probes per node)
- Various extensions/variations:
 - Discover the “least good”
 - Tradeoff accuracy of probes – number of probes

Placement approaches

- Random
- Decision based on local information
- Decision based on local and remote information
- Coordinated decision

Decision based on local information

- Resource constraints analysis and path ranking are performed using local information
- Place probes in iterations
 - Identify set of candidate probes
 - Initial iteration: random placement or based on top destinations
 - Subsequent iterations: time since last observation, closeness to violation determine selection probability
 - Balance coverage over time (round robin) vs scrutiny for likely offenders
- Input:
 - SLO
 - Local observations (measurements, flow)

Algorithm 2 LocalInfoPlace($\alpha, \beta, staticweigh[], path[]$)

```
N ← GetNumberEdges(path[])
Rc ← min( $\beta, \alpha/N$ )
M ← min((Rc - GetNumberActiveProbes()), SizeOf(path[]))
for t = 1 → SizeOf(path[]) do
    path[t][Wu] ← GetUser(path[t])
    path[t][Wtl] ← GetTrafLocal(path[t])
    path[t][Wll] ← GetLabelLocal(path[t])
    t ← t + 1
end for
SortDesc(path[], key ← (staticweigh[Wu] * path[][Wu]/ $\Sigma path$ [][Wu] +
(staticweigh[Wtl] * path[][Wtl]/ $\Sigma path$ [][Wtl] + (staticweigh[Wll] *
path[][Wll]/ $\Sigma path$ [][Wll])/( $\Sigma staticweigh$ []))
for i = 1 → M do
    DeployProbe(path[i])
    i ← i + 1
end for
```

Extensions

- Decision based on local + remote information
 - Take into account results obtained from peers in previous cycle
 - Destinations for which violations are detected from one node may be scrutinized more closely by others
- Coordinate probing
 - Avoid duplicate routine probing of same destinations for greater coverage in same cycle
 - Nodes exchange what they measure (best effort, gossiping)
- Identify correlated peers for better coordination
 - Weigh information from nodes that are “similar” to you
 - In terms of observations – similar PIN and other characteristics
 - Assess, discover, validate if a peer is correlated
- Note: Inter-peer communication leverages Autonomic Control Plane

Comparison with current solutions

- No standardized solution for distributed autonomic detection of SLA violations
- Current solutions usually restricted to ad hoc scripts running on a per node fashion to automate some administrator's actions
- Some proposals for passive probe activation (e.g., DECON and CSAMP), but without the focus on autonomic features
- Barford et al. (INFOCOM 2009) → Detection and localization of links which cause anomalies along a network path
- Nobre et al. (CNSM 2012, ICC 2013, AINA 2014) → Utilization of P2P technology embedded in network devices to improve probe activation decisions using autonomic loops

Related IETF Work

- Large-Scale Measurement of Broadband Performance (LMAP) WG
 - AN solution relevant for LMAP → SLA violation screening
 - Solution to decrease the workload of human administrators in service providers → probably highly desirable

IP Flow Information Export (IPFIX) WG

- AN solution extension for passive measurement probes (i.e., metering exporters)
- Flow information used in the decision making of probe activation

Application Layer Traffic Optimization (ALTO) Working Group

- Definition of the topology regarding the network devices which exchange measurement data

Security Considerations

•Possible Approaches

- Bootstrapping of a new device → homenet approach [draft-behringer-homenet-trust-bootstrap]
- Measurement data exchange → signed and encrypted among devices
- Sensible information about network infrastructures

Possible Attacks

- Denial of service (DoS) attacks → activation of more local probe than the available resources allow
- Results could be forged by a device (attacker) in order to this device be considered peer of a specific device (target) → to gain information about a network infrastructure

Outlook

- Revision 02