

# 6TiSCH Minimal Scheduling Function (MSF)

draft-chang-6tisch-msf-00

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# Oops...

- We missed the deadline (timezone confusion...), thanks to Suresh for publishing the document at:
  - <https://tools.ietf.org/html/draft-chang-6tisch-msf-00>

# Abstract

This specification defines the 6TiSCH Minimal Scheduling Function (MSF). This Scheduling Function describes both the behavior of a node **when joining the network**, and **how the communication schedule is managed in a distributed fashion**. MSF builds upon the 6top Protocol (**6P**) and the **Minimal Security Framework** for 6TiSCH.

# In a nutshell

1. Start with a single cell
  - 6tisch-minimal
2. Perform secure join
  - 6tisch-minimal-security
3. Add/delete cells to parent
  - 6tisch-6top-protocol

☐ Completely defined behavior, fully standardized story <sup>^^</sup>

# Interaction with 6TiSCH-minimal

- Frames exchanged over the minimal cell:
  1. EBs
  2. DIOs
  3. Join request/response messages between pledge and JP
  4. the first 6P Transaction a node initiates
- Access rules to the minimal cell: cut bandwidth in portions:
  - $1/(3(N+1))$  for EBs (N= number of neighbors)
  - $1/(3(N+1))$  for DIOs
  - Rest for join and 6P (see above)
- Slotframe organization:
  - Slotframe 0 for minimal cell
  - Slotframe 1 for cells added by MSF

# Node Behavior at Boot (1/2)

- Start state
  - PSK
  - Any other configuration mentioned in minimal-security
- *[7-step join]*
- End state
  - node is **synchronized** to the network
  - node is using the **link-layer keying** material it learned through the secure joining process
  - node has identified its **preferred routing parent**
  - node has a **single dedicated cell** to its preferred routing parent
  - node is periodically sending **DIOs**, potentially serving as a router for other nodes' traffic
  - node is periodically sending **EBs**, potentially serving as a JP for new joining nodes

# Node Behavior at Boot (2/2)

- Step 1 - Choosing Frequency
  - Listen on random frequency
- Step 2 - Receiving Ebs
  - Listen for multiple neighbors, shoes one as JP
- Step 3 - Join Request/Response
  - First hop over minimal cells, rest over dedicated (same for response)
- Step 4 - Acquiring a RPL rank
  - Select preferred parent
- Step 5 - 6P ADD to Preferred Parent
  - Single TX|RX|SHARED cell to parent
- Step 6 - Send EBs and DIOs
  - Accept children
- Step 7 - Neighbor Polling
  - Keep-alive to each neighbor you have cells to every 10s; remove if dead.

did you spot the typo?

# Dynamic Scheduling (1/4)

- 3 reasons for adding/removing/relocating cells:
  - Adapting to Traffic
  - Switching Parent
  - Handling Schedule Collisions
- 6P carries out the work

# Dynamic Scheduling (2/4)

- Reason 1/3: Adapting to Traffic
  - A node always has at least one cell to preferred parent
  - Keep counters to preferred parent:
    - NumCellsPassed
    - NumCellsUsed
  - When NumCellsPassed reaches 16:
    - If NumCellsUsed > 12, add a cell
    - If NumCellsUsed > 4, remove a cell

# Dynamic Scheduling (3/4)

- Reason 2/3: Switching parents
  - Count number of cells to old parent
  - Schedule the same number to new parent
  - Remove cells from old parent

# Dynamic Scheduling (4/4)

- Reason 3/3: Handling schedule collisions
  - Counter for each cell to preferred parent:
    - NumTx
    - NumTxAck
  - When NumTx==256:
    - NumTx<<1
    - NumTxAck<<1
  - Periodically, compare numbers for all cells to parent
    - If no roll over yet, abort
    - If PDR of one cell <50% of cell with max PDR, relocate

# Other “details”

- 6P SIGNAL command
- Rules for CellList
- 6P Timeout Value
- Rule for Ordering Cells
- Meaning of the Metadata Field
- 6P Error Handling
- Schedule Inconsistency Handling

# 6TiSCH MSF challenge!

- Answer the following questions through implementation:
  - how long does it take a 100-node network to form? what topology?
  - what is the average latency of a packet in a typical 32-node indoor deployment?
  - how does the network handle bursty traffic? up to how much burstiness is acceptable (i.e. no packets lost)?
  - What is the code/memory footprint of an MSF implementation?
  - How resilient a network is to loss of nodes in the middle of its construction? While it's running?
  - What kind of network topology is difficult to handle to such scheduling function? (Linear, Tree, Random, ...).
  - What is the cost of adding a new node to the network once it's running? Does this cost increase with the size of the network?
  - what is the data rate that makes cell allocation too slow? considering the 2-way nature of 6p.
  - how often we get CLEARs due to inconsistency given certain network conditions (different levels of PDR)
  - what is the impact of cell-list size in the allocation probability (5 candidate cells are recommended, what about more or less?)
  - how do queues grow when a node is using its almost maximum capacity and starts requesting more cells.
  - what is the impact of message timeouts in the size of queues?
  - Etc. (ideas welcome!)
- 6TiSCH simulator and OpenWSN implementations ongoing!