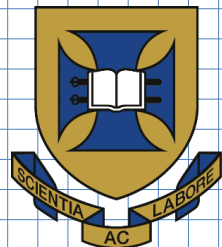


# **SCOR: Software-defined Constraint Optimal Routing platform for SDN**

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**April 2018**



**THE UNIVERSITY  
OF QUEENSLAND**  
A U S T R A L I A

# Outline

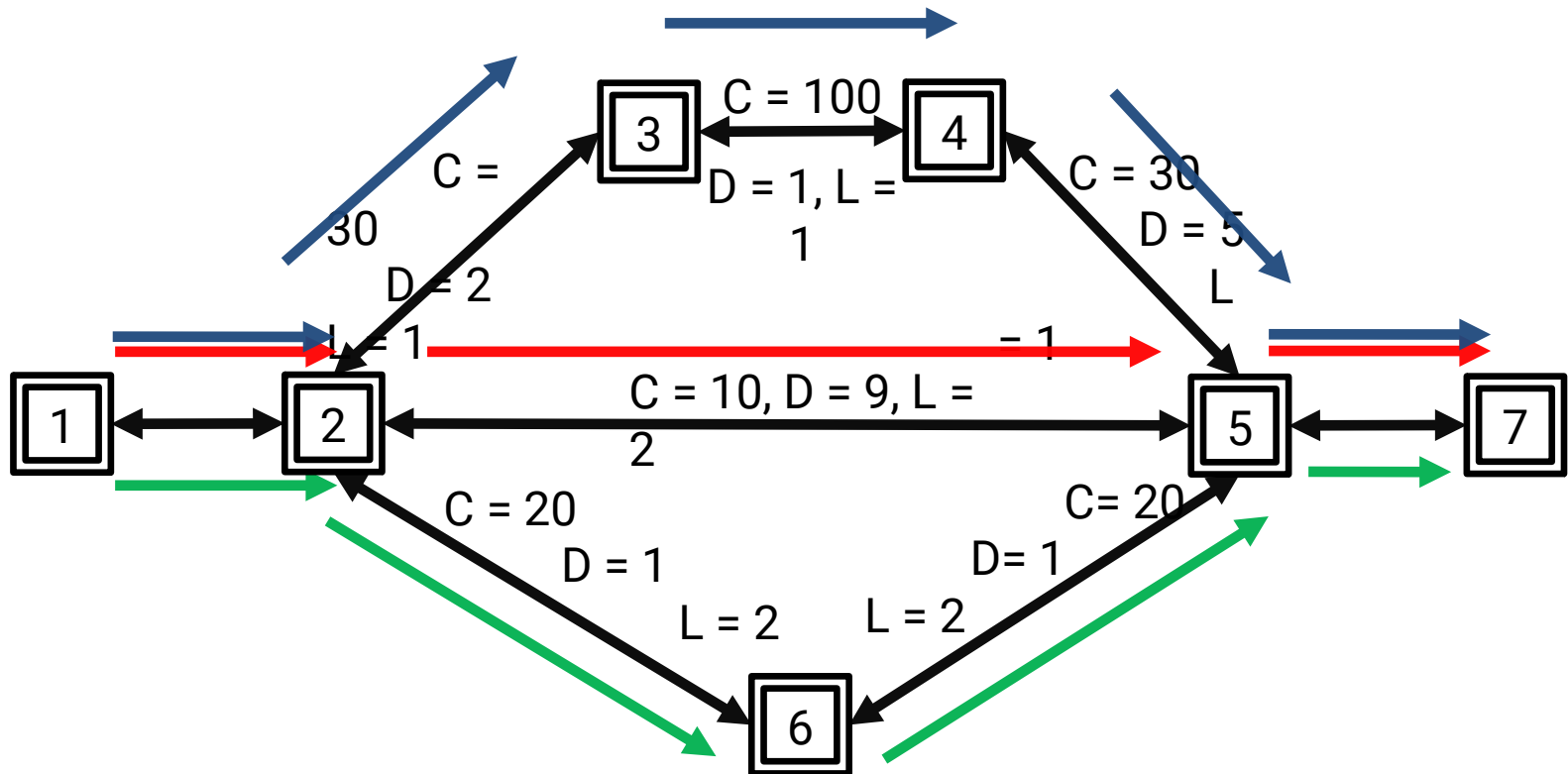
- **Background: QoS Routing**
- **SCOR's Structure**
- **SCOR Models for QoS Routing**
- **Use Cases: ONOS apps**

# QoS Routing

Shortest Path Routing

Widest Path Routing (Maximum Bandwidth Routing)

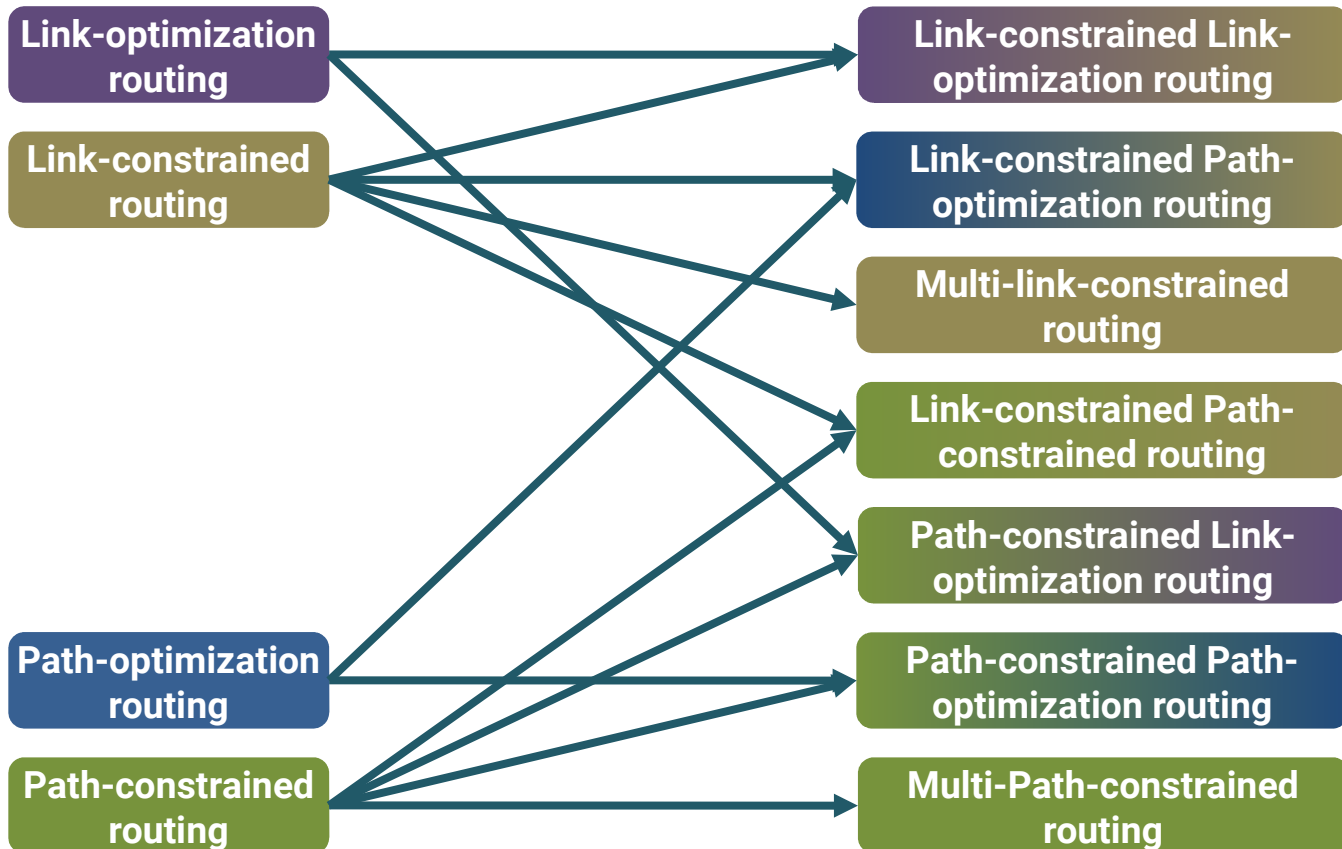
Minimum Delay Path Routing



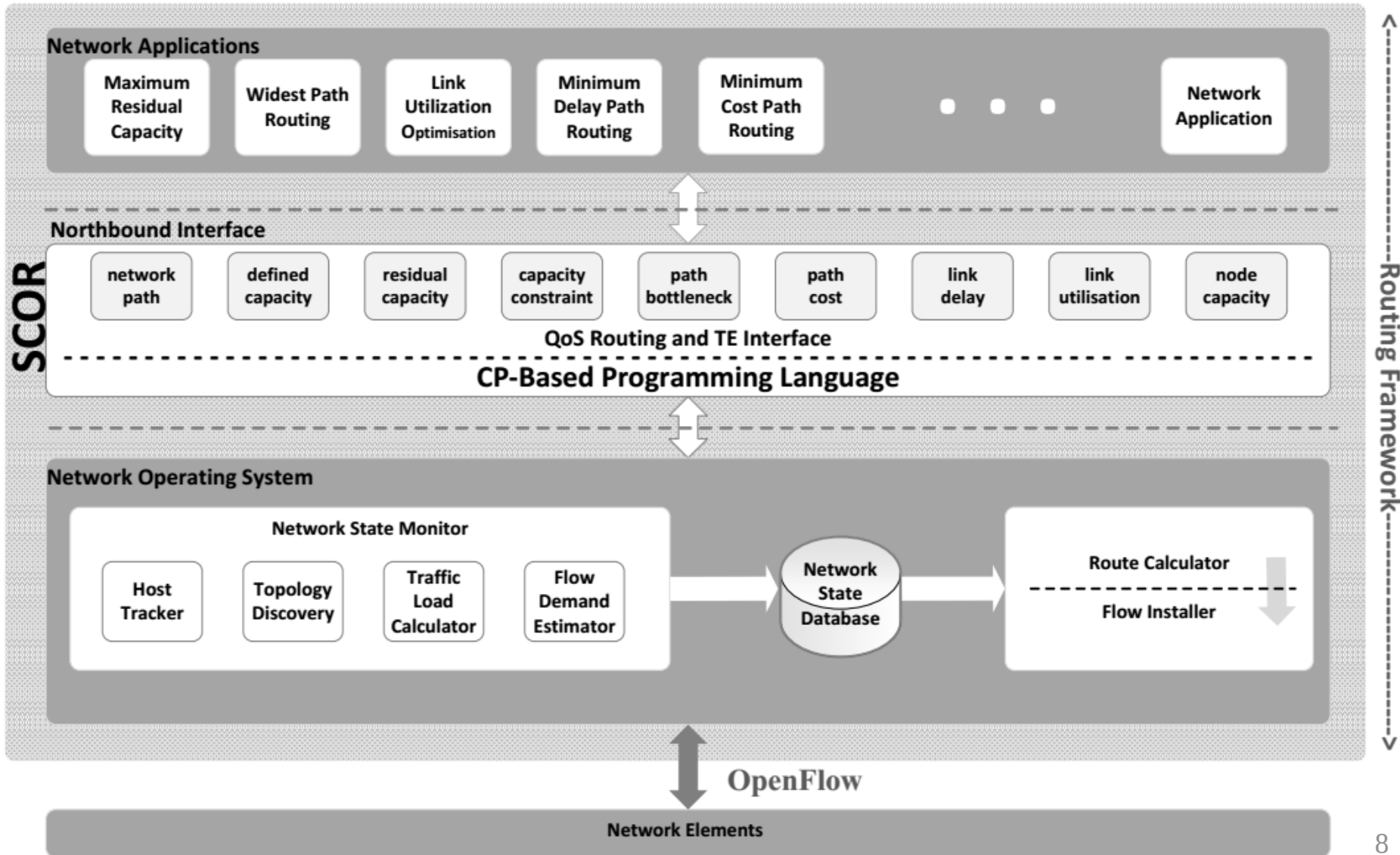
# Routing & QoS Routing

## Basic QoS Routing Algorithms

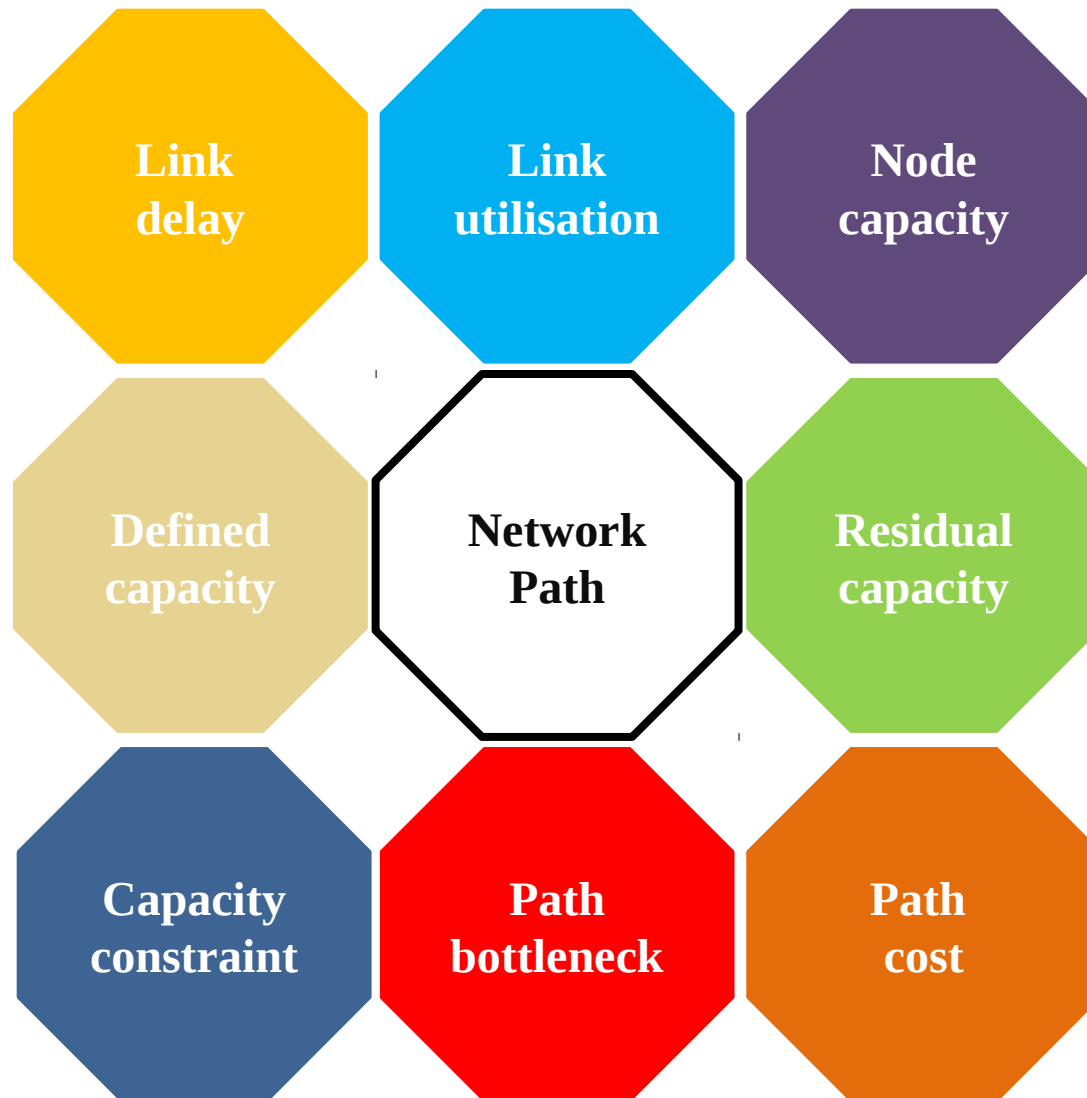
## Composite QoS Routing Algorithms



# SDN Routing Framework



# SCOR: a New Northbound Interface for Routing



# Introducing a New Northbound Interface for QoS Routing

Item	Predicate Name	Implemented Constraint/Defined Value
1	<i>network path</i>	$\sum_{\{v (u,v) \in \mathcal{L}\}} f(u,v) - \sum_{\{v (u,v) \in \mathcal{L}\}} f(v,u) = S_u \quad \forall u \in \mathcal{N}$
2	<i>defined capacity</i>	$c(u,v) \geq c_0 \quad \forall (u,v) \in P_f$
3	<i>residual capacity</i>	$r(u,v) = c(u,v) - f(u,v) \quad \forall (u,v) \in \mathcal{L}$
4	<i>capacity constraint</i>	$f(u,v) \leq c(u,v) \quad \forall (u,v) \in \mathcal{L}$
5	<i>path bottleneck</i>	$c_B[P_f] = \min_{(u,v) \in P_f} \{c(u,v)\}$
6	<i>path cost</i>	$a[P_f] = \sum_{(u,v) \in P_f} a(u,v) f(u,v)$
7	<i>link delay</i>	$D(u,v) = \frac{1}{c(u,v) - f(u,v)} \quad \forall (u,v) \in P_f$
8	<i>link utilisation</i>	$U(u,v) = \frac{f(u,v)}{c(u,v)} \quad \forall (u,v) \in P_f$
9	<i>node capacity</i>	$\sum_{\{v (u,v) \in \mathcal{L}\}} f(u,v) + \sum_{\{v (u,v) \in \mathcal{L}\}} f(v,u) \leq C_u \quad \forall u \in \mathcal{N}$

# Introducing a New Northbound Interface for QoS Routing

---

## **Predicate 1: Network Path**

---

```
1: forall(i in 1..N)(
2:     forall(j in 1..F)(
3:         flow_in_links[i] = sum(k in 1..L)(
4:             if Links[k,2]=i then LPM[k, j] else 0 endif
5:         )
6:         ^
7:         flow_out_links[i] = sum(k in 1..L)(
8:             if Links[k,1]=i then LPM[k, j] else 0 endif
9:         )
10:        flow_in_links[i] + (if i = s[j] then 1 else 0 endif) =
11:        flow_out_links[i] + (bif i = t[j] then 1 else 0 endif)
12:        ^
13:        flow_in_links[i] <= 1
14:    )
15:);
```

---

---

## **Predicate 3: residual Capacity**

---

```
1: forall(k in 1..L)(
2:     if sum(j in 1..F)(LPM[k,j])=0
3:     then Residuals[k] = Cmax
4:     else Residuals[k] = Links[k,4] - sum(j in 1..F)(Flows[j] × LPM[k,j])
5:     endif
6: );
```

---

---

## **Predicate 2: Defined Capacity**

---

```
1: forall(k in 1..L)(
2:     forall(j in 1..F)(
3:         if Links[k,4] < Limits[j] then LPM[k,j] = 0
4:         else true endif
5:     )
6: );
```

---

---

## **Predicate 4: Capacity Constraint**

---

```
1: include "Predicate_residual_capacity.mzn";
2: residual_capacity( LPM, Flows, Links, Residuals );
3: ^
4: forall(k in 1..L)(
5:     Residuals[k]>0
6: );
```

---



# Introducing a New Northbound Interface for QoS Routing

---

**Predicate 6: path bottleneck**

---

```
1: forall(j in 1..F)(  
2:   forall(k in 1..L)(  
3:     Width[k] = Links[k,4] × LPM[k,j]  
4:   )  
5:   ^  
6:   forall(k in 1..L, where Width[k] !=0)(  
7:     Bandwidth[k] = Width[k]  
8:   )  
9:   ^  
10:  Bottleneck[j] = min(Bandwidth)  
11: );
```

---

---

**Predicate 5: path cost**

---

```
1: forall(j in 1..F)(  
2:   Total_Cost[j] =  
3:     sum(k in 1..L)(  
4:       Links[k,3] × LPM[k,j] × Flows[j]  
5:     )  
6: );
```

---

---

**Predicate 7: link delay**

---

```
1: include "Predicate_capacity_constraint.mzn";  
2: capacity_constraint( LPM, Flows, Links, Residuals );  
3: ^  
4: forall(k in L)(  
5:   if sum(j in 1..F)(LPM[k,j])=0  
6:   then Delay[k] = 0  
7:   else Delay[k] = 1 / Residuals[k]  
8:   endif  
9: );
```

---

# Introducing a New Northbound Interface for QoS Routing

---

**Predicate 9: node capacity**

---

```
1: forall(i in 1..N)(
2:     node_flow_in[i] = sum(k in 1..L, j in 1..F)(
3:         if Links[k,2]=i then LPM[k, j] × Flows[j]
4:         else 0
5:         endif
6:     )
7:     ^
8:     node_flow_out[i] = sum(k in 1..L, j in 1..F)(
9:         if Links[k,1]=i then LPM[k, j] × Flows[j]
10:        else 0
11:        endif
12:    )
13:    ^
14:    node_flow_in[i] + node_flow_out[i] ≤ Node_Capacity
15: );
```

---

---

**Predicate 8: link utilisation**

---

```
1: forall(k in 1..L)(
2:     Link_Utilisation[k] = (
3:         sum(j in 1..F)(
4:             Flows[j] × LPM[k,j]
5:         ) / Link[k,4]
6:     ) × 100
7: );
```

---

# Modelling various QoS Routing Algorithms in SDN

Algorithm	Metrics	Type
Shortest Path	Hop Count	Basic
Widest Path	Bandwidth	Basic
Minimum-Delay Path	Transmission Delay	Basic
Minimum-Loss Path	Packet Loss	Basic
Constrained-Delay Path	Transmission Delay	Basic
Constrained-Bandwidth Path	Bandwidth	Basic
Constrained-Bandwidth -Minimum-Delay Path	Bandwidth, Transmission Delay	Multi- constraint
Maximum-Residual-Capacity Path	Bandwidth	Complex
Constrained-Residual-Capacity Path	Bandwidth	Complex
Minimum-Link-Utilisation Path	Bandwidth/total delay	Complex
Constrained-Link-Utilisation Path	Bandwidth/total delay	Complex
Minimum-Congestion Path	Bandwidth/total delay	Complex
Constrained-Congestion Path	Bandwidth/total delay	Complex

# Least Cost Path Routing

$$\text{minimise} \quad \sum_{(u,v) \in \mathcal{L}} a(u,v) f(u,v)$$

$$\sum_{\{v|(u,v) \in \mathcal{L}\}} f(u,v) - \sum_{\{v|(u,v) \in \mathcal{L}\}} f(v,u) = S_u, \quad \forall u \in \mathcal{N}$$

$$f(u,v) = f_1(u,v) = d_1 x_1(u,v)$$

$$\text{minimise} \quad \sum_{(u,v) \in \mathcal{L}} a(u,v) x_1(u,v)$$

$$\sum_{\{v|(u,v) \in \mathcal{L}\}} x_1(u,v) - \sum_{\{v|(u,v) \in \mathcal{L}\}} x_1(u,v) = S_u/d_1, \quad \forall u \in \mathcal{N}$$

# SCOR Model: Least Cost Path Routing

---

## Model 1: Least Cost Path Routing in SCOR

---

```
% Include item

1: include "Predicate_network_path.mzn";
2: include "Predicate_path_cost.mzn";

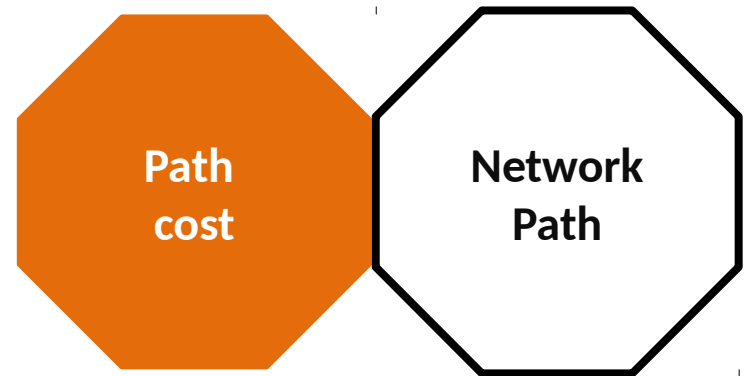
% Parameters
3: array[int,4] of int: Links;
4: int: L = max(index_set_1of2(Links));
5: array[int] of int: Nodes;
6: int: Flows;
7: int: s;
8: int: t;

% Decision Variables
9: var int: Cost;
10: array[1..L,1] of var 0..1: LPM;

% Constraints item
11: constraint network_path(LPM, Links, Nodes, s, t);
12: constraint path_cost(LPM, Links, Cost, Flows);

% Solve item
13: solve minimize Cost;
```

---



# Least Cost Path Constrained Capacity Routing

$$\text{minimise} \quad \sum_{(u,v) \in \mathcal{L}} a(u,v) f(u,v)$$

$$\sum_{\{v|(u,v) \in \mathcal{L}\}} f(u,v) - \sum_{\{v|(u,v) \in \mathcal{L}\}} f(v,u) = S_u, \quad \forall u \in \mathcal{N}$$

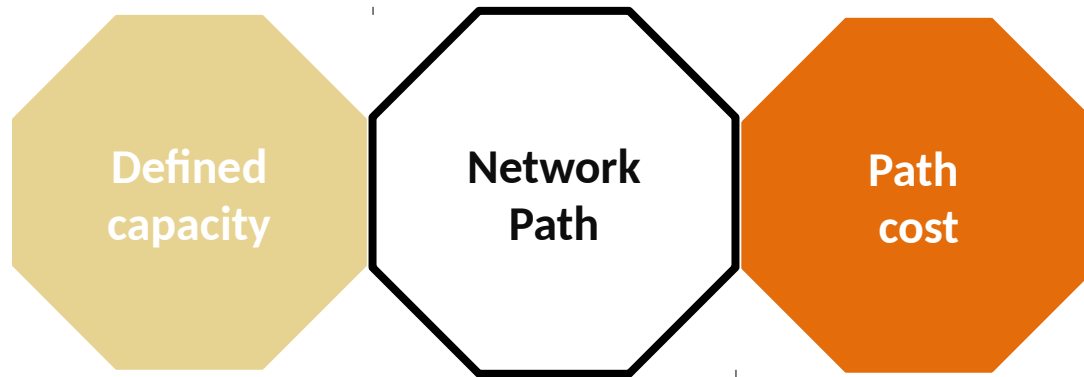
$$f(u,v) = f_1(u,v) = d_1 x_1(u,v)$$

$$\text{minimise} \quad \sum_{(u,v) \in \mathcal{L}} a(u,v) x_1(u,v)$$

$$\sum_{\{v|(u,v) \in \mathcal{L}\}} x_1(u,v) - \sum_{\{v|(u,v) \in \mathcal{L}\}} x_1(u,v) = S_u/d_1, \quad \forall u \in \mathcal{N}$$

$$x_1(u,v) \leq c(u,v)/d_1 \quad \forall (u,v) \in \mathcal{L}$$

# SCOR Model: Least Cost Path Constrained Capacity Routing



---

## Model 2: Least Cost Path with Defined Capacity Routing in SCOR

---

```
⋮
    % Include item
1 : include "Predicate defined_capacity.mzn";
⋮
    % Parameters
2 : int : Limit;
⋮
    % Constraints item
3 : constraint defined_capacity(LPM, Links, Flows, Limit);
⋮
```

---

# Maximum Residual Capacity Path Routing

$$\text{maximise}\{\mathcal{Z}\}$$

$$\mathcal{Z} \leq r(u, v) \quad \forall (u, v) \in \mathcal{L}$$

$$\sum_{\{v|(u,v) \in \mathcal{L}\}} x_j(u, v) - \sum_{\{v|(u,v) \in \mathcal{L}\}} x_j(v, u) = S_u^j/d_j \quad \forall u \in \mathcal{N}, j = 1..F$$

$$\sum_{j=1..F} d_j x_j(u, v) \leq c(u, v) \quad \forall (u, v) \in \mathcal{L}$$

$$r(u, v) = c(u, v) - f(u, v) \quad \forall (u, v) \in \mathcal{L}$$

$$f(u, v) = \sum_{j=1..F} f_j(u, v) = \sum_{j=1..F} d_j x_j(u, v) \quad \forall (u, v) \in \mathcal{L}$$

$$x_j(u, v) = \begin{cases} 0 & (u, v) \notin P_j \\ 1 & (u, v) \in P_j \end{cases}$$

$$S_u^j/d_j = \begin{cases} 1 & u = s_j, \\ -1 & u = t_j, \\ 0 & \text{otherwise} \end{cases} \quad u \in \mathcal{N}, j = 1..F$$



# SCOR Model: Maximum Residual Capacity Path Routing

---

## Model 3: Maximum Residual Capacity Routing in SCOR

---

```
% Include item
1: include "Predicate network path.mzn";
2: include "Predicate capacity constraint.mzn";

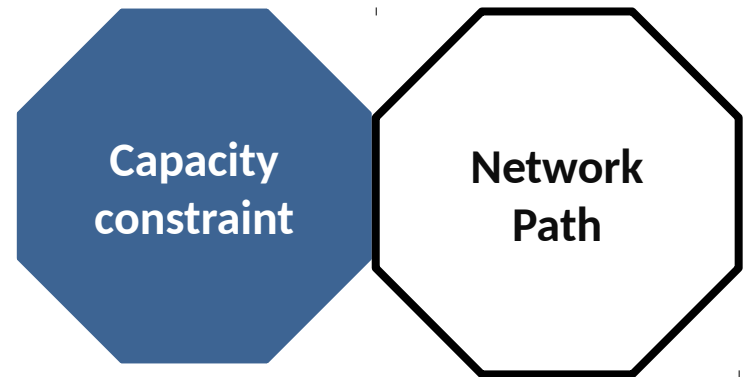
% Parameters
3: array[int,int] of int : Links;
4: int : L = max(index_set_1of2(Links));
5: array[int] of int : Nodes;
6: array[int] of int : Flows;
7: int : F = max(index_set(Flows));
8: array[1..F] of int : s;
9: array[1..F] of int : t;

% Decision Variables
10: array[1..L,1..F] of var 0..1 : LPM;
11: array[1..L] of var int : Residuals;

% Constraints item
12: constraint network_path(LPM, Links, Nodes, s, t);
13: constraint capacity_constraint(LPM, Links, Flows, Residuals);

% Solve item
14: solve maximize min(Residuals);
```

---



# MRCPR in Procedural Programming

```
str(len(G.node.keys()))+" "+str(len(edges))+" w/ error " + str(error)+ ": " +
str(shortestPathComputations)
    for node in G.node.iterkeys():
        print node, G.edge[node]
    return shortestPathComputations,count

def get_beta_hat(edges, commodities, error=GLOBAL_ERROR, karakosta=True):
    spc, beta_hat = maximum_concurrent_flow(edges, commodities, error=1., returnBeta=True,
    karakosta=karakosta,
                                     scale_beta=False)

    return beta_hat, spc

def two_approx(edges, commodities, error=GLOBAL_ERROR, karakosta=True):
    beta_hat, spc = get_beta_hat(edges, commodities, error=1., returnBeta=True, karakosta=karakosta)
    scale_demands(commodities, beta_hat / 2.)
    return maximum_concurrent_flow(edges, commodities, error=error, karakosta=karakosta,
    shortestPathComputations=spc)

def multi_route(edges, commodities, error=GLOBAL_ERROR, scale_beta=True, karakosta=False):
    beta_hat, spc = get_beta_hat(edges, commodities, error=1.)
    return maximum_concurrent_flow(edges, commodities, error=error, karakosta=karakosta,
    shortestPathComputations=spc,
                                     scale_beta=scale_beta, multi_route=True, beta_hat=beta_hat)

commodityTable[commodity] = 0
for head in G.edge.iterkeys():
    for tail, edge_dict in G.edge[head].iteritems():
        for commodity in commodities:
            if tail == commodity.sink:

commodityTable[commodity]+=edge_dict[FLOW_ATTRIBUTE]/commodity.demand
print "Lambda is " + str( min([x for x in commodityTable.itervalues()])))
print "OBJECTIVE: ", calculate_dual_objective(G)
print "SPC-"+str(karakosta)+"-"+str(twoApprox)+ " for G("
```

```
edge[FLOW_ATTRIBUTE] = edge.get(FLOW_ATTRIBUTE, 0) + added_flow
```

# Half-duplex Maximum Residual Capacity Path Routing

$$\text{maximise } \{Z\}$$

$$Z \leq r(u, v) \quad \forall (u, v) \in \mathcal{L}$$

$$\sum_{\{v|(u,v) \in \mathcal{L}\}} x_j(u, v) - \sum_{\{v|(u,v) \in \mathcal{L}\}} x_j(v, u) = S_u^j / d_j \quad \forall u \in \mathcal{N}, j = 1..F$$

$$\sum_{j=1..F} d_j x_j(u, v) \leq c(u, v) \quad \forall (u, v) \in \mathcal{L}$$

$$r(u, v) = c(u, v) - f(u, v) \quad \forall (u, v) \in \mathcal{L}$$

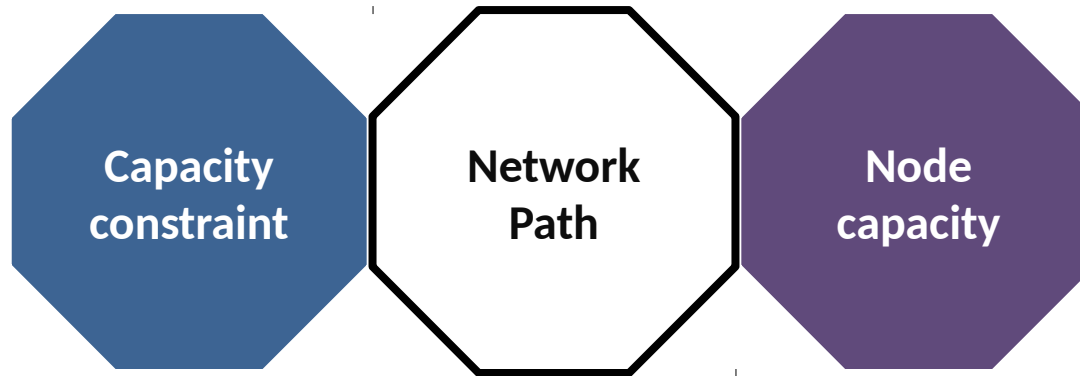
$$f(u, v) = \sum_{j=1..F} f_j(u, v) = \sum_{j=1..F} d_j x_j(u, v) \quad \forall (u, v) \in \mathcal{L}$$

$$x_j(u, v) = \begin{cases} 0 & (u, v) \notin P_j \\ 1 & (u, v) \in P_j \end{cases}$$

$$\sum_{\{v|(u,v) \in \mathcal{L}\}} f(u, v) + \sum_{\{v|(u,v) \in \mathcal{L}\}} f(v, u) \leq C_u \quad \forall u \in \mathcal{N}$$

$$S_u^j / d_j = \begin{cases} 1 & u = s_j, \\ -1 & u = t_j, \\ 0 & \text{otherwise} \end{cases} \quad u \in \mathcal{N}, j = 1..F$$

# SCOR Model: Half-duplex Maximum Residual Capacity Path Routing



---

**Model 4:** Half-duplex Maximum Residual Capacity Routing in SCOR

(Only lines not included in maximum residual capacity routing)

---

```
⋮
    % Include item
1 : include "Predicate node capacity.mzn";
⋮
    % Parameters
2 : array[int] of int : Nodes_Capacities;
⋮
    % Constraints item
3 : constraint node_capacity(LPM, Links, Flows, Nodes_Capacities);
⋮
```

---

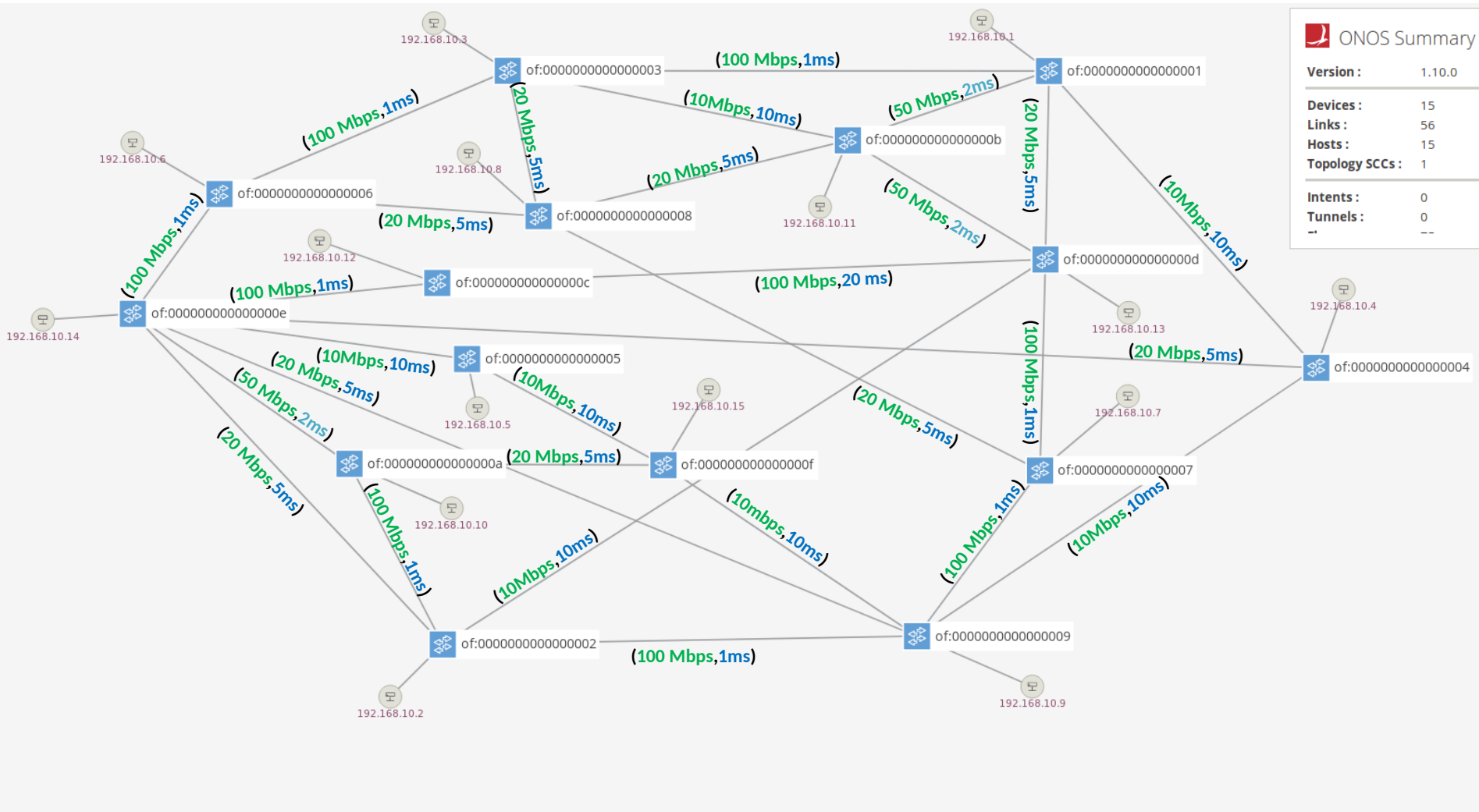
# Conciseness & Completeness

QoS Routing Problem	SCOR Predicates	#L
Shortest Path	path cost	3
Widest Path [11]	path bottleneck	3
Bandwidth-Guaranteed [13]	capacity constraint	3
Bandwidth-Constrained [11]	defined capacity	3
Minimum-Loss [14]	path cost	3
Minimum-Delay [14]	path cost	3
Minimum-Delay [64]	delay	3
Delay-Constrained [11]	path cost	3
Least-Cost [11]	path cost	3
Maximum Residual Capacity [12]	capacity constraint	3
Minimum Link Utilisation [16]	link utilisation	4
Delay-Constrained Least-Cost [11]	path cost $\times 2$	4
Delay-Delay Jitter-Constrained [11]	path cost $\times 2$	4
Bandwidth-Delay-Constrained [11]	defined capacity path cost	4
Bandwidth-Constrained Least-Delay [11]	defined capacity path cost	4
Minimum-Cost Bandwidth-Constrained [15]	capacity constraint path cost	4
Delay-Constrained Bandwidth-Optimised [11]	path cost path bottleneck	4
Widest Shortest Path [17]	path cost path bottleneck	6
Shortest Widest Path [17]	path cost path bottleneck	6

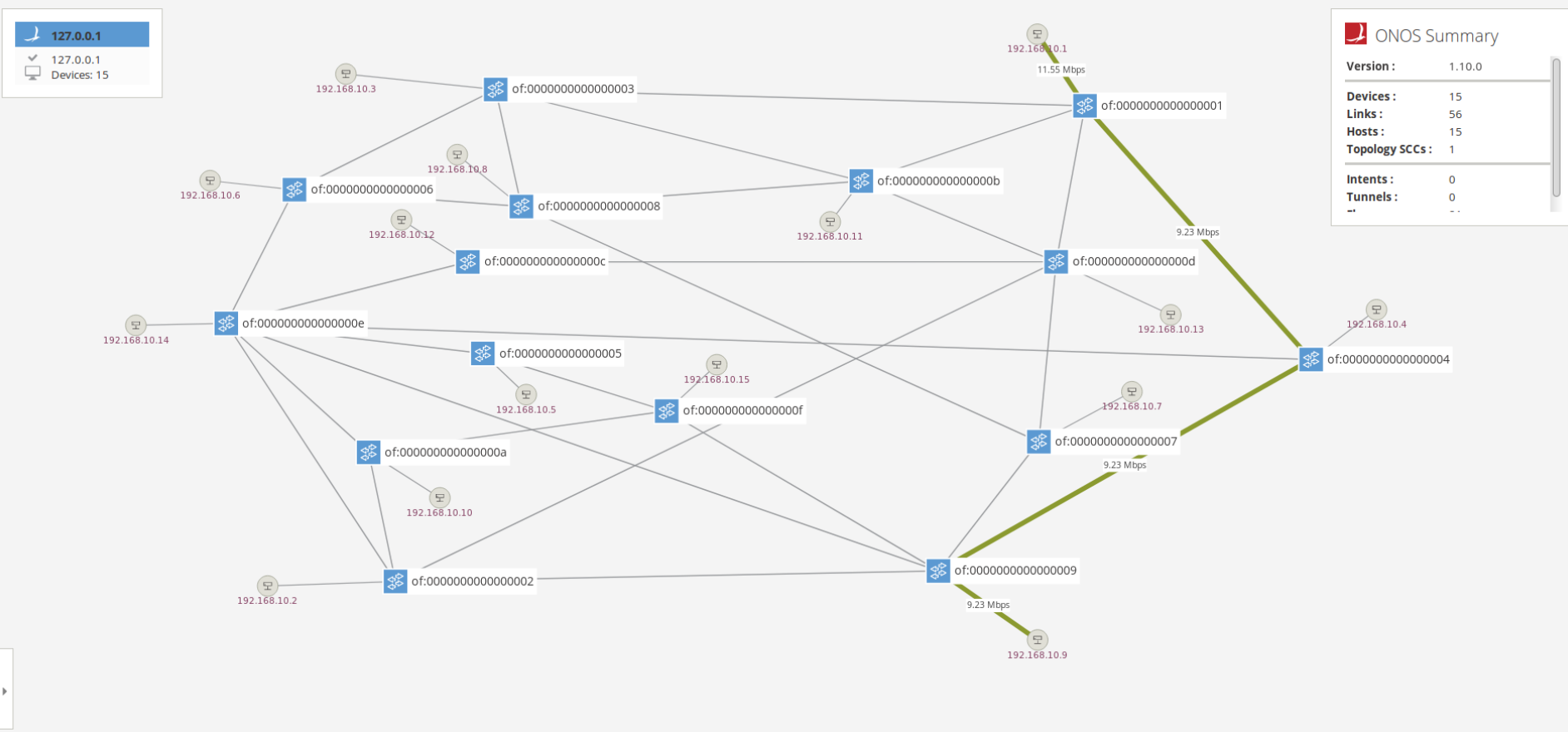
# Real-World Use Cases: ONOS Apps

- **Max-BW Routing**
- **Min-Delay Routing**
- **Max-BW Constrained Delay Routing**
- **Min-Delay BW Constrained Routing**
- **Minimizing Max Link Utilization**
- **Maximizing Min Residual Capacity**

# Real-World Use Cases: Scenario

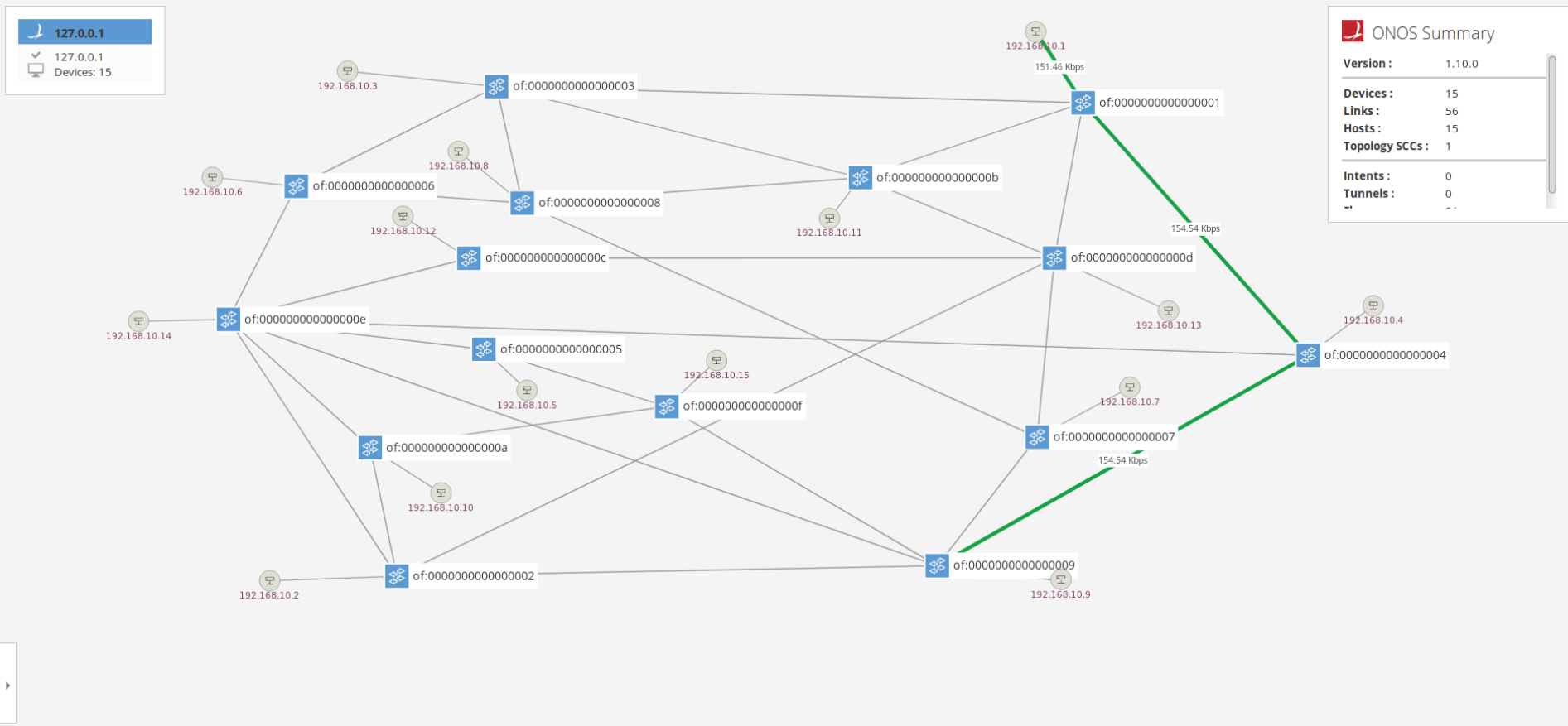


# Maximum-Bandwidth Routing

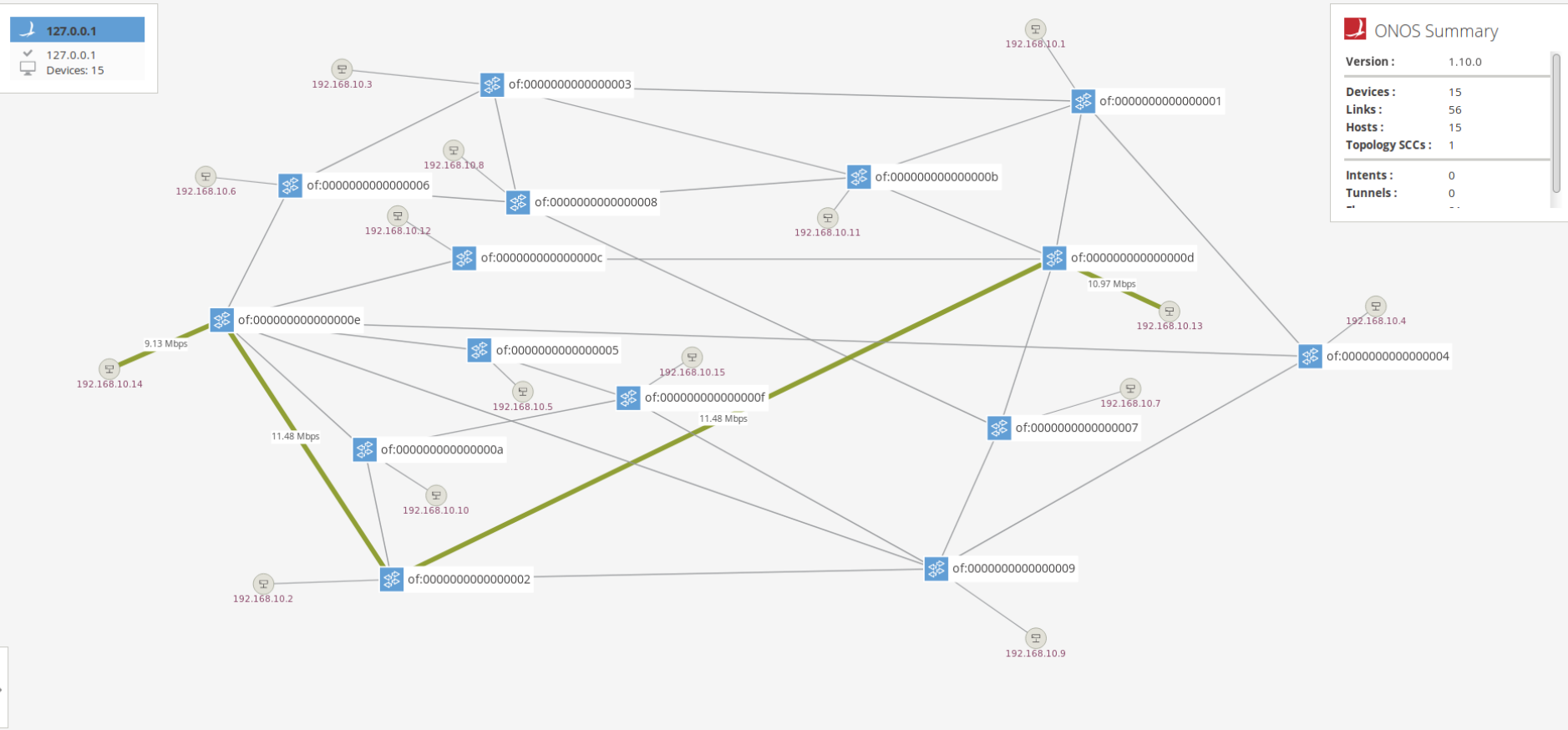




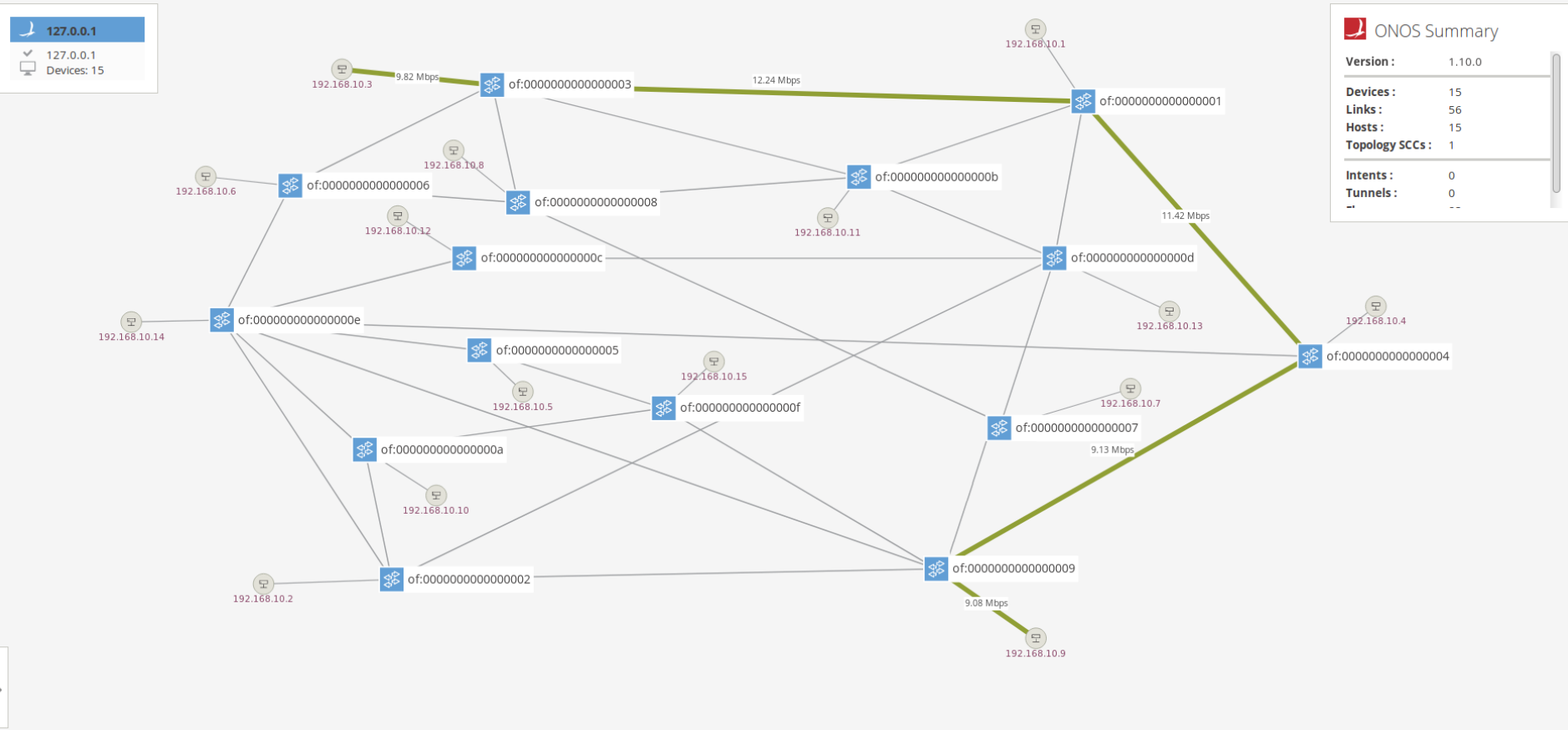
# Minimum-Delay Routing



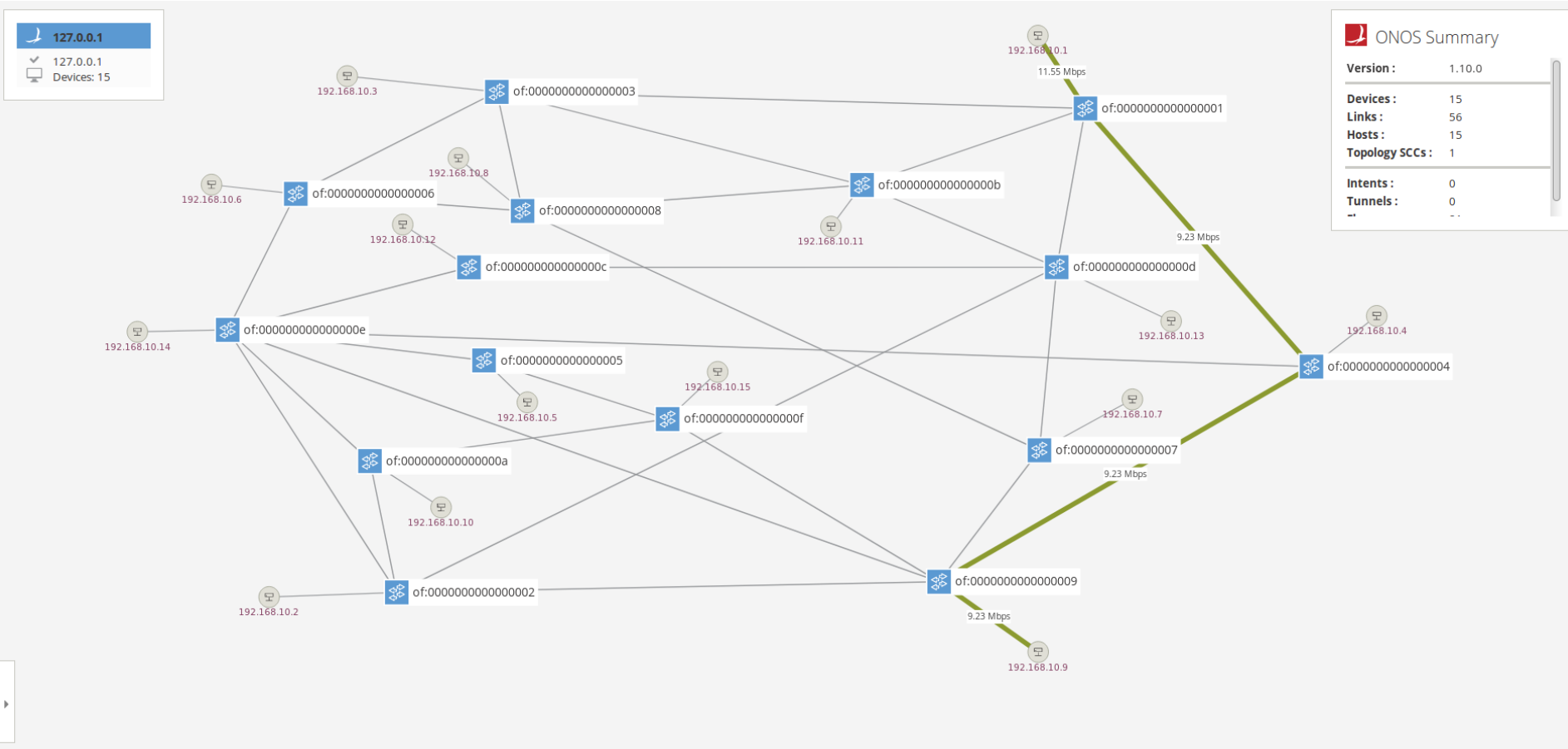
# Max-BW Constrained Delay Routing



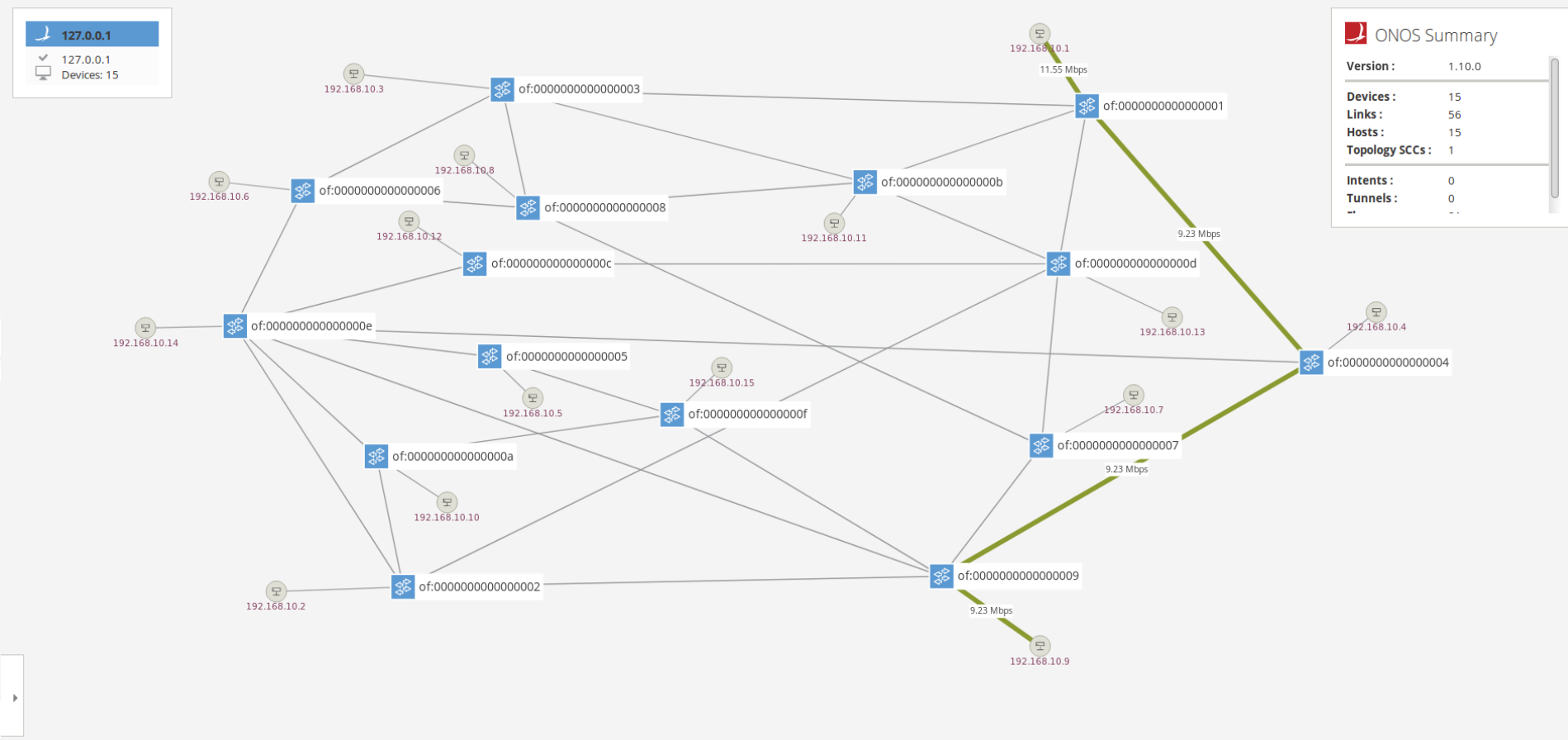
# Min-Delay Constrained BW Routing



# Minimizing Max Link Utilization



# Maximizing Min Residual Capacity



**Q & A**  
**Thank You**